GOVERNMENT COLLEGE OF ENGINEERING

(An Autonomous Institution Affiliated to Anna University) $BARGUR - 635 \ 104$

Curriculum for

MECHANICAL ENGINEERING

(Full Time)

I TO VIII SEMESTERS

2018

Regulations

For the students admitted during

AY 2018-2019

Revised on 06/03/2020

OFFICE OF CONTROLLER OF EXAMINATIONS
GOVERNMENT COLLEGE OF ENGINEERING
BARGUR - 635 104

Website: www.gcebargur.ac.in

	PROGRAM SPECIFIC OUTCOMES (PSOs):
1	Acquire basic knowledge and expertise necessary for professional practice in Mechanical Engineering for higher studies and research.
2	Attain and practice technical skills to identify, analyze, innovate and interact with industry
_	to solve complex problems related to Mechanical Engineering.
3	Possess a professional attitude as an individual or a team member with consideration for
	society, professional ethics, environmental factors and motivation for lifelong learning.
	PROGRAM OUTCOMES (POs)
1	Engineering Knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
2	Problem Analysis: Identify, formulate, research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
3	Design/development of Solutions: Design solutions for complex engineering problems and
	design system components or processes that meet the specified needs with appropriate
	consideration for the public health and safety, and the cultural, societal, and environmental
4	considerations. Conduct Investigations of Complex Problems: Use research-based knowledge and
4	research methods including design of experiments, analysis and interpretation of data, and
	synthesis of the information to provide valid conclusions.
5	Modern Tool usage: Create, select, and apply appropriate techniques, resources, and
	modern engineering and IT tools including prediction and modelling to complex
	engineering activities with an understanding of the limitations.
6	The Engineer and Society: Apply reasoning informed by the contextual knowledge to
	assess societal, health, safety, legal and cultural issues and the consequent responsibilities
	relevant to the professional engineering practice.
7	Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
8	Environment and Sustainability: Understand the impact of the professional engineering
	solutions in societal and environmental contexts, and demonstrate the knowledge of, and
	need for sustainable development.
9	Individual and Team Work: Function effectively as an individual, and as a member or
10	leader in diverse teams, and in multidisciplinary settings.
10	Communication: Communicate effectively on complex engineering activities with the
	engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and
	receive clear instructions.
11	Project Management and Finance: Demonstrate knowledge and understanding of the
	engineering and management principles and apply these to one's own work, as a member
	and leader in a team, to manage projects and in multidisciplinary environments.
12	Life-long Learning: Recognize the need for, and have the preparation and ability to engage
	in independent and life-long learning in the broadest context of technological change

MECHANICAL ENGINEERING (UG) CURRICULUM DESIGN CREDIT SUMMARY

Name of the UG Programme: **B.E - MECHANICAL ENGINEERING**

S. No	Sub. Area			Credits per Semester				Credits Total	% of Total Credits	Total no. of Cour ses	Suggested Breakup of Credits (Total 160)*		
		I	II	III	IV	IV V		VII	VIII				
1	HSMC		3		3		1.5			7.5	5	3	12
2	BSC	9.5	9.5	4						23	14	7	25
3	ESC	8	8	7						23	14	8	24
4	PCC			13.5	17	17.5	14	8		70	41	25	48
5	PEC					3	3	6	6	18	11	6	18
6	OEC						3	3	3	09	7.5	3	18
7	PROJ					1.5		3	6	10.5	7.5	4	14.5
8	MC	0	0		0	0				0.0	0	4	
	Total	17.5	20.5	24.5	20	22	21.5	20	15	161	100	60	160*

STUDENTS ARE ENCOURAGED TO SELECT ELECTIVES FROM SWAYAM / NPTEL / MOOC

GOVERNMENT COLLEGE OF ENGINEERING, BARGUR(An Autonomous Institution Affiliated to Anna University)

B.E MECHANICAL ENGINEERING 2018 REGULATIONS

Induction Program

Induction program(mandatory)	3 Weeks Duration
Induction program for students to be	Physical activity
Offered right at the start of the first	Creative Arts
year.	Universal Human Values
	Literary
	Proficiency Modules
	Lectures by Eminent People
	Visits to local Areas
	• Familiarization to Dept./Branch & Innovations

FIRST SEMESTER

S. No	Subject Code	Course Title	CAT	CONTACT PERIODS	L	Т	P	C
THEOR	RY							
1	18EMS101	Engineering Physics	BSC	4	3	1	0	4
2	18ZBS102	Engineering Mathematics I	BSC	4	3	1	0	4
3	18ZES103	Basic Electrical Engineering	ESC	3	2	1	0	3
4	18ZES104	Engineering Graphics and Design	ESC	5	1	0	4	3
5	18ZMC105	Induction Program	MC	-	-	-	-	0
		PRACTICAL						
6	18EMS106	Physics Laboratory	BSC	3	0	0	3	1.5
7	18ZES107	Basic Electrical Engineering Laboratory	ESC	4	0	0	4	2
		TOTAL		23	9	3	11	17.5

SECOND SEMESTER

Sl.No	Subject Code	Course Title	CAT	CONTACT PERIODS	L	Т	P	C
THEO	RY							
1	18MBS201	Applied Chemistry	BSC	4	3	1	0	4
2	18ZBS202	Engineering Mathematics II	BSC	4	3	1	0	4
3	18MES203	Programming in Python	ESC	3	3	0	0	3
4	18ZHS204	Technical English	HSMC	2	2	0	0	2
5	18ZMC205	Constitution of India	MC	1	1	0	0	0
PRAC'	TICAL							
6	18EMS206	Chemistry Laboratory	BSC	3	0	0	3	1.5
7	18MES207	Programming in Python Laboratory	ESC	4	0	0	4	2
8	18ZES208	Workshop Practice	ESC	5	1	0	4	3
9	18ZHS209	Communication English Laboratory	HSMC	2	0	0	2	1
		TOTAL		28	13	2	13	20.5

THIRD SEMESTER

SL. NO	COURSE CODE	COURSE TITLE	CAT	CONTACT PERIODS	L	Т	P	С		
THEO	THEORY									
1	18 MBS 301	Transforms and Partial Differential Equations	BSC	4	3	1	0	4		
2	18 MES 302	Engineering Mechanics	ESC	4	3	1	0	4		
3	18MPC303	Manufacturing Technology I	PCC	3	3	0	0	3		
4	18MPC304	Engineering Thermodynamics	PCC	4	3	1	0	4		
5	18MPC305	Fluid Mechanics and Fluid Machinery	PCC	3	3	0	0	3		
6	18MES306	Basic Electronics Engineering	ESC	3	3	0	0	3		
PRAC	CTICAL									
7	18MPC307	Fluid Mechanics and Fluid Machinery Laboratory	PCC	3	0	0	3	1.5		
8	18MPC308	Machine Drawing	PCC	4	0	0	4	2.0		
		TOTAL		28	18	3	7	24.5		

FOURTH SEMESTER

SL. NO.	COURSE CODE	COURSE TITLE	CAT	CONTACT PERIODS	L	Т	P	С			
THEC	THEORY										
1	18MPC401	Thermal Engineering	PCC	3	3	0	0	3			
2	18MHS402	Human Values and Professional Ethics	HSMC	3	3	0	0	3			
3	18MPC403	Strength of Materials	PCC	4	3	1	0	4			
4	18MPC404	Engineering Materials and Metallurgy	PCC	3	3	0	0	3			
5	18MPC405	Kinematics of Machines	PCC	4	3	1	0	4			
6	18ZMC406	Environmental Science and Engineering	MC	1	1	0	0	0			
PRAC	CTICAL										
7	18MPC407	Strength of Materials Laboratory	PCC	3	0	0	3	1.5			
8	18MPC408	Thermal Engineering Laboratory	PCC	3	0	0	3	1.5			
		TOTAL		24	16	2	6	20.0			

FIFTH SEMESTER

Sl. No	COURSE CODE	COURSE TITLE	САТ	CONTACT PERIODS	L	Т	P	C
THEC	ORY							
1	18MPC501	Design of Machine Elements	PCC	4	3	1	0	4
2	18MPC502	Heat and Mass Transfer	PCC	4	3	1	0	4
3	18MPC503	Manufacturing Technology II	PCC	3	3	0	0	3
4	18MPC504	Metrology and Measurements	PCC	3	3	0	0	3
5		Professional Elective I	PEC	3	3	0	0	3
PRAC	CTICAL		1				I	
6	18MPC506	Manufacturing Processes and Metrology Laboratory	PCC	4	0	0	4	2
7	18MPC507	Heat and Mass Transfer Laboratory	PCC	3	0	0	3	1.5
8	18MPR508	•	PROJ	3	0	0	3	1.5
		TOTAL		26	15	2	9	22

SIXTH SEMESTER

Sl. No	COURSE CODE	COURSE TITLE	CAT	CONTACT PERIODS	L	Т	P	C		
THEORY										
1	18MPC601	Dynamics of Machinery	PCC	4	3	1	0	4		
2	18MPC602	Finite Element Analysis	PCC	4	3	1	0	4		
3	18MPC603	Additive Manufacturing	PEC	3	3	0	0	3		
4		Professional Elective II	PEC	3	3	0	0	3		
5		Open Elective I	OEC	3	3	0	0	3		
PRAC	CTICAL									
6	18MPC606	Simulation Laboratory	PCC	3	0	0	3	1.5		
7	18MPC607	Dynamics of Machinery Laboratory	PCC	3	0	0	3	1.5		
8	18HSC608	Soft skills and Personality Development Laboratory	HSC	3	0	0	3	1.5		
		TOTAL		26	15	2	9	21.5		

SEVENTH SEMESTER

Sl. No	COURSE CODE	COURSE TITLE	CAT	CONTACT PERIODS	L	Т	P	C
THEORY								
1	18MPC701	Automation in Manufacturing	PCC	3	3	0	0	3
2	18MPC702	Design of Transmission systems	PCC	3	3	0	0	3
3	-	Professional Elective III	PEC	3	3	0	0	3
4	-	Professional Elective IV	PEC	3	3	0	0	3
5	-	Open Elective II	OEC	3	3	0	0	3
PRAC	CTICAL							
6	18MPC706	CAD/CAM and Mechatronics Laboratory	PCC	4	0	0	4	2
7	18MPR707	Project II	PROJ	6	0	0	6	3
		TOTAL		24	15	0	9	20

EIGHTH SEMESTER

Sl. No	Course Code	COURSE TITLE	CAT	CONTACT PERIODS	L	Т	P	C
THEORY								
1	-	Professional Elective V	PEC	3	3	0	0	3
2	-	Professional Elective VI	PEC	3	3	0	0	3
3	-	Open Elective III	OEC	3	3	0	0	3
PRAC	CTICAL							
5	18MPR804	Project III	PROJ	12	0	0	12	6
		TOTAL		21	9		12	15

TOTAL NO. OF CREDITS: 161

Value Added Courses

The students can undergo **Internship** in Government / Government Recognized industries / Organizations, for the period of 4 to 6 weeks.

This will be indicated in the **Grade Sheet** under the head, "Value Added Courses".

OPEN ELECTIVES (ONLY OFFERED TO THE OTHER DEPARTMENT STUDENTS

Sl.No	Subject Code	Course Title	CAT	L	Т	P	С
1	18MOE001	Engineering Economics	OEC	3	0	0	3
2	18MOE002	Industrial Engineering	OEC	3	0	0	3
3	18MOE003	Entrepreneurship Development	OEC	3	0	0	3
4	18MOE004	Elements of Project Management	OEC	3	0	0	3
5	18MOE005	Non Destructive Testing	OEC	3	0	0	3
6	18MOE006	Introduction to Automobile Engineering	OEC	3	0	0	3
7	18MOE007	Industrial Automation	OEC	3	0	0	3
8	18MOE008	Introduction to Composite Materials.	OEC	3	0	0	3
9	18MOE009	Industrial Refrigeration and Air-Conditioning	OEC	3	0	0	3

OPEN ELECTIVES (OFFERED BY ECE)

Sl.No	Subject Code	Course Title	CAT	L	Т	P	С
1	18LOE001	Real Time Systems	OEC	3	0	0	3
2	18LOE002	Wireless sensor Networks	OEC	3	0	0	3
3	18LOE003	Industrial automation and Robotics	OEC	3	0	0	3
4	18LOE004	Principles of VLSI design	OEC	3	0	0	3
5	18LOE005	Applied Electronics	OEC	3	0	0	3
6	18LOE006	Wireless networking	OEC	3	0	0	3
7	18LOE007	Internet of Things	OEC	3	0	0	3
8	18LOE008	Soft Computing	OEC	3	0	0	3

OPEN ELECTIVES (OFFERED BY EEE)

Sl.No	Subject Code	Course Title	CAT	L	T	P	С
1	18EOE001	Matlab Programing	OEC	3	0	0	3
2	18EOE002	Renewable Energy Sources OEC			0	0	3
3	18EOE003	Energy Management and Auditing	OEC	3	0	0	3
4	18EOE004	Reliability Engineering	OEC	3	0	0	3
5	18EOE005	Disaster Management and Mitigation	ent and Mitigation OEC		0	0	3
6	18EOE006	Power Electronics and Drives	OEC	3	0	0	3

OPEN ELECTIVES (OFFERED BY CSE)

Sl.No	Subject Code	Course Title	CAT	L	Т	P	С
1	18SOE001	Programing in C++	OEC	3	0	0	3
2	18SOE002	Java Programing OEC 3		0	0	3	
3	18SOE003	Data base Concepts OEC 3		0	0	3	
4	18SOE004	Web Designing	OEC 3		0	0	3
5	18SOE005	Android Application Development	roid Application Development OEC 3		0	0	3
6	18SOE006	Computer Architecture	OEC	3	0	0	3
7	18SOE007	Fundamentals of Computer Network	OEC	3	0	0	3
8	18SOE008	Linux and RTOS	OEC		0	0	3
9	18SOE009	Introduction to Python	OEC 3		0	0	3
10	18SOE010	Introduction to Data Analytics	OEC	3	0	0	3

Also,

STUDENTS ARE ENCOURAGED TO SELECT ELECTIVES FROM SWAYAM / NPTEL / MOOC

PROFESSIONAL ELECTIVES

S.No	Subject Code	Course Title	CAT	L	T	P	C
1	18MPE001	Internal Combustion Engines	PEC	3	0	0	3
2	18MPE002	Mechatronic Systems	PEC	3	0	0	3
3	18MPE003	Microprocessors in Automation	PEC	3	0	0	3
4	18MPE004	Processing of Composite Materials	PEC	3	0	0	3
5	18MPE005	Computer Aided Design	PEC	3	0	0	3
6	18MPE006	Operations Research	PEC	3	0	0	3
7	18MPE007	Theory of Metal cutting	PEC	3	0	0	3
8	18MPE008	Welding Technology	PEC	3	0	0	3
9	18MPE009	Refrigeration and Air Conditioning	PEC	3	0	0	3
10	18MPE010	Power Plant Engineering	PEC 3		0	0	3
11	18MPE011	Gas Dynamics and Jet Propulsion	PEC 3		0	0	3
12	18MPE012	Process Planning and Cost Estimation	PEC 3		0	0	3
13	18MPE013	Lean Manufacturing	PEC	3	0	0	3
14	18MPE014	Design of Jigs, Fixtures and Press Tools	PEC	3	0	0	3
15	18MPE015	Mechanical Vibrations	PEC	3	0	0	3
16	18MPE016	Principles of Management	PEC	3	0	0	3
17	18MPE017	Automobile Engineering	PEC	3	0	0	3
18	18MPE018	Energy Conservation and Management	PEC	3	0	0	3
19	18MPE019	Industrial Robotics	PEC	3	0	0	3
20	18MPE020	Computational Fluid Dynamics	PEC	3	0	0	3
21	18MPE021	Design for Manufacture, Assembly and Environments	PEC 3		0	0	3
22	18MPE022	Nano Technology	PEC	3	0	0	3
23	18MPE023	Total Quality Management	PEC	3	0	0	3
24	18MPE025	Optimization Techniques	PEC	3	0	0	3

LIST OF MANDATORY COURSES

S. No	Subject	Course Title	CAT	L	T	P	C
1	18ZMC105	Induction Program	MC	-	Ī	-	0
2	18ZMC205	Constitution of India	MC	1	0	0	0
3	18ZMC406	Environmental Science and Engineering	MC	1	0	0	0

LIST OF ES

S.No	Subject	Course Title	CAT	L	T	P	C
1	18ZES103	Basic Electrical Engineering	ESC 2		1	0	3
2	18ZES104	Engineering Graphics and Design	ESC 1 0		0	4	3
3	18ZES107	Basic Electrical Engineering Laboratory	ESC 0		0	4	2
4	18MES203	Programming in Python	ESC	3	0	0	3
5	18MES207	Programming in Python Laboratory	ESC	0	0	4	2
6	18ZES208	Workshop Practice	ESC	1	0	4	3
7	18MES302	Engineering Mechanics	ESC	3	1	0	4
8	18MES306	Basic Electronics Engineering	ESC	3	0	0	3

LIST OF HSMC

S.No	Subject	Course Title	CAT	L	T	P	C
1	18ZHS204	Technical English	HSMC 2		0	0	2
2	18ZHS209	Communication English Laboratory	HSMC 0 0		0	2	1
3	18HSC608	Soft skills and Personality Development Laboratory	HSMC	0	0	3	1.5
4	18MHS402	Human Values and Professional Ethics	HSMC	3	0	0	3

LIST OF BS

S.No	Subject	Course Title	CAT	L	T	P	С
1	18EMS101	Engineering Physics	BSC	3	1	0	4
2	18ZBS102	Engineering Mathematics I	BSC	3	1	0	4
3	18EMS106	Physics Laboratory	BSC	0	0	3	1.5
4	18MBS201	Applied Chemistry	BSC	3	1	0	4
5	18ZBS202	Engineering Mathematics II	BSC	3	1	0	4
6	18EMS206	Chemistry Laboratory	BSC	0	0	3	1.5
7	18MBS301	Transforms and Partial Differential Equations	BSC	3	1	0	4

LIST OF PC

S. No	Subject	Course Title	CAT	L	Т	P	C
1	18MPC303	Manufacturing Technology I	PCC	3	0	0	3
2	18MPC304	Engineering Thermodynamics	PCC	3	1	0	4
3	18MPC305	Fluid Mechanics and Fluid Machinery	PCC	3	0	0	3
4	18MPC307	Fluid Mechanics and Fluid Machinery Laboratory	ics and		3	1.5	
5	18MPC308	Machine Drawing	PCC	0	0	4	2
6	18MPC401	Thermal Engineering	PCC	3	0	0	3
7	18MPC403	Strength of Materials	PCC	3	1	0	4
8	18MPC404	Engineering Materials and Metallurgy	gineering Materials PCC 3 0		0	3	
9	18MPC405	Kinematics of Machines	PCC	3	1	0	4
10	18MPC407	Strength of Materials Laboratory	oratory PCC 0		0	3	1.5
11	18MPC408	Thermal Engineering Laboratory	PCC	0	0	3	1.5
12	18MPC501	Design of Machine Elements	PCC 3 1		0	4	
13	18MPC502	Heat and Mass Transfer	PCC	3	1	0	4
14	18MPC503	Manufacturing Technology II	PCC	3	0	0	3
15	18MPC504	Metrology and Measurements	PCC	3	0	0	3
16	18MPC506	Manufacturing Processes and Metrology Laboratory	PCC	0	0	3	1.5
17	18MPC507	Heat and Mass Transfer Laboratory	PCC	0	0	3	1.5
18	18MPC601	Dynamics of Machinery	PCC	3	1	0	4
19	18MPC602	Finite Element Analysis	PCC	3	1	0	4
20	18MPC603	Additive Manufacturing	PCC	3	0	0	3
21	18MPC606	Simulation Laboratory	PCC	0	0	3	1.5
22	18MPC607	Dynamics of Machinery Laboratory	PCC	0	0	3	1.5
23	18MPC701	Automation in Manufacturing	PCC	3	0	0	3
24	18MPC702	Design of Transmission systems	PCC 3 0		0	3	
25	18MPC706	CAD/CAM and Mechatronics Laboratory	PCC	0	0	4	2

EVALUATION SCHEME :: 2018 REGULATIONS

Each course shall be evaluated for a maximum of **100 marks** as shown below:

Sl. No	Category of course	Continuous Assessment	End-Semester Examinations
1.	Theory Courses	50 Marks	50 Marks
2.	Laboratory Courses	50 Marks	50 Marks
3.	Project Work	50 Marks	50 Marks
4.	All other EEC Courses (non theory)	100 Marks	-
5.	Mandatory Courses		100 Marks (Internal Evaluation)

Continuous Assessment Mark the following guidelines are to be followed.

Sl. No.	Category Details	CA Marks	Weightage
1.	Test (3 Nos.) {each test is to be conducted for 50 Marks}	30 Marks	60%
2.	Assignment (3 Nos.)	20 Marks	40%
	TOTAL	50 Marks	100%

Marks for **Mini Project & Project Work and the Viva-Voce Examination** will be distributed as indicated below:

Contin	Continuous Assessment: 50 Marks			End Semester Examination: 50 Marks			
Review (25 Mar)		Review II (25 Marks)		Report Evaluation (20 Marks)	Viva-Voce (30 Marks)		
Review Committee (Excluding Guide)	Guide	Review Committee (Excluding Guide)	Guide	External Examiner	External Examiner	Internal Examiner **	
15	10	15	10	20	15	15	

^{**}Guide will be the internal

ATTENDANCE

A student has to **secure minimum of 75% attendance** for appearing end semester examination. If a student secures <u>65% to 75% attendance</u> in the Current Semester due to medical reasons (hospitalization / accident / specific illness) or due to participation in the College / University / State / National / International Level Sports events with prior permission from the Head of the Department concerned, the student shall apply for **condonation**. Condonation can be allowed only two semesters during the entire course of study (i.e Only two condonations during the entire course of study).

Students who secure <u>less than 65% attendance</u> will <u>not be permitted</u> to write the **End-Semester Examination.**

<u>SPECIAL NOTE</u>: All the students should **undergo Internship** (4 to 6 weeks duration) as a value added course. This will be indicated in the Grade Sheet under the head, "**Value Added Courses**".

18EMS1	101		ENGINEERING PHYSICS	L	T	P	C
		(Common to MECH, EEE, ECE & CSE	3	1	0	4
OBJECTI	CTIVES:						
•	To develop knowledge on properties of solids						
•	To understand the properties of conducting and semiconducting materials						
•	To be	come j	proficient in magnetic and dielectric materials				
•	To apply principles of quantum physics in the engineering field						
To know about the fundamentals of LASER and fibre optics and its applicant.					icati	ons	

UNIT I PROPERTIES OF MATTER

9+3

Elasticity – Hooke's law – Stress – Types of Stresses – Strain- Types of Strain - Young's Modulus – Rigidity Modulus – Bulk Modulus –Poisson's ratio – Relationship between three elastic constants and Poisson's ratio – Torsional Pendulum – Factors affecting elasticity of materials - Bending moment of a Beam – Depression of cantilever (Theory and Experiment) – Determination of Young's modulus – Uniform and non-uniform bending (Theory and Experiment).

UNIT II CONDUCTING AND SEMICONDUCTING MATERIALS

9+3

Conductors – Ohm's Law – Electrical conductivity – Relation between current density, drift velocity and mobility – Classical free electron theory of metals – Expression for electrical conductivity of a metal –Expression for thermal conductivity of a metal – Wiedemann – Franz law – Fermi distribution function – Effect of temperature on Fermi Function – Density of energy states.

Intrinsic semiconductor – Energy band diagram – Direct and indirect semiconductors – Carrier concentration in an intrinsic semiconductor (derivation) – Extrinsic semiconductors – n-type & p-type semiconductors (Qualitative) – Determination of Bandgap of semiconductors (Experiment)

UNIT III MAGNETIC AND DIELECTRIC MATERIALS

Magnetism in materials – magnetic field and induction – magnetization – magnetic permeability and susceptibility – types of magnetic materials –microscopic classification of magnetic materials –Domain theory of ferromagnetism.

Dielectric materials: Polarization processes – dielectric loss – internal field – Clausius-Mosotti relation – dielectric breakdown – high-k dielectrics.

UNIT IV OUANTUM PHYSICS

9+3

9+3

Blackbody radiation – Wien's displacement law – Rayleigh-Jean's law - Planck's theory (derivation) – Deduction of Wien's displacement law and Rayleigh-Jean's law – Matter waves – De-Broglie's Hypothesis – Properties of matter waves - Wave-particle duality – Wave function and its physical Significance – Schrodinger wave equation – Time-dependent and time-independent – Application of Schrodinger wave equation: Particle in a 1 D box.

UNIT V LASER PHOTONICS AND FIBRE OPTICS

9+3

LASER – Interaction of light radiation with materials – Einstein"s A and B coefficient derivation – Concept of LASER – Population inversion – Pumping action – Methods for pumping action – Characteristics of LASER – Principle, construction and working of Nd-YAG – Industrial and

medical applications of lasers.

Structure of Optical Fibre – Guiding mechanism – Total internal reflection – Critical Angle – Conditions for total internal reflection – Principle and Propagation of light in Optical Fibres – Numerical aperture and acceptance angle – Types of optical fibres (Material, refractive index and mode) – their characteristics and applications.

TOTAL: 60 PERIODS	TOTAL:	60 PERIOD	S
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	TOTAL: 00 I EXIODS					
OUTCOMI	ES:					
1.	To learn about three types of elastic moduli and able to calculate them for different materials					
2.	To learn about conducting and semiconducting materials and able to derive different parameters relevant to them					
3.	To learn about types of magnetic materials and their types and functional knowledge of dielectric materials					
To understand the quantum nature of materials and apply fundamental principles of quantum physics to the engineering field						
5.	To understand the working principles of lasers and their types and also to know about fibre optics and mechanism of propagation of light through them.					
TEXTBOO	KS:					
1.	P. Mani, "Engineering physics", Dhanam Publications, 2017.					
2.	G. Senthil Kumar, "Engineering physics", VRB Publishers					
3.	A. Marikani, "Engineering Physics", PHI Learning Pvt., India 2009					
4.	Wahen M. A. "Solid state physics: Structure and properties of materials" Narosa publishing house, 2009					
REFEREN(CES:					
1.	R. K. Gaur and S.C. Gupta, "Engineering physics", Dhanpat Rai publications, New Delhi 2003.					
2.	M. N. Avadhanulu and P. G. Kshirsagar, "A textbook of engineering physics", S. Chand and Company Ltd, New Delhi, 2005.					
3.	K. Rajagopal, "Engineering Physics", PHI, New Delhi, 2011.					
4.	P. K. Palanisamy, "Engineering Physics", SCITECH Publication, 2011					
5.	M. Arumugam, "Engineering physics", Anuradha publishers					

						P	POs						PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	1		1				1	2	1	2	3	2	
CO2	3	2	1		1				1	2	1	2	3	2	
CO3	3	2	1		1				1	2	1	2	3	2	
CO4	3	2	1		1				1	2	1	2	3	2	
CO5	3	2	1		1				1	2	1	2	3	2	
Average	3	2	1		1				1	2	1	2	3	2	
Round off	3	2	1		1				1	2	1	2	3	2	

18 Z B	S102	ENGINEERING MATHEMATICS- I	L	T	P	C
			3	1	0	4
OBJE						
•		x algebra and techniques and using them in engineering applic				
•	infinite	ncept of infinite series and their convergence so that they will be familiar v series approximations for solutions arising in mathematical modelling.				using
•		ential and integral calculus and their applications in various er ations.	nginee	ering		
UNIT I		IATRICES				9+3
eigenval Diagona	ues and lization	Eigenvectors of a real matrix — Characteristic equation eigenvectors — Statement and applications of Cayley-Happing for matrices — Reduction of a quadratic form to canonical forms.	milto	n Tl	neore	em -
UNIT	II S	EQUENCES AND SERIES				9+3
Tests of	converge Leibnitz,	ition and examples – Series: Types and Convergence – Series ence: Comparison test, Integral test and D,,Alembert,,s ratio tests test – Series of positive and negative terms – Absolute and c	st - A	ltern	ating	
UNIT	III A	PPLICATIONS OF DIFFERENTIAL CALCULUS				9+3
		tesian co-ordinates – Centre and radius of curvature – Circopes - Evolute as envelope of normals.	ele of	curv	ature	2 –
UNIT	[V F	UNCTIONS OF SEVERAL VARIABLES				9+3
function	s – Jacob	tinuity — Partial derivatives — Total derivative — Differentian and properties — Taylors series for functions of two variations of two variables — Lagranges method of undetermined mul	ıbles -	- Ma		
UNIT	V M	IULTIPLE INTEGRALS				9+3
enclosed	by plane	tegrals in cartesian and polar coordinates – Change of order of curves – Change of variables in double integrals – Area of a Volume of Solids. LECTURE: 45 TUTORIAL: 15 TOTAL	curve	d sur	face	-
OUTC	OMES					
1.	solve pro	blems on matrices and to apply concepts of matrix theory who ld of engineering.	enevei	app	licat	ole
2.	solve pro	blems using convergence tests on sequences and series and to ing field appropriately.	apply	the	n in	
3.	solve pro	oblems on differential and integral calculus and will be exposed ons in engineering	d to th	neir		
TEXT	воок	S:				
		and Manish Goyal, "A Text book of Engineering Mathematically blications Pvt Ltd., 2011.	es", E	ighth	Edi	tion,
2.		B.S, "Higher Engineering Mathematics", 41st Edition, Kh	ianna	Pub	licat	ions,
REFE	RENCE	SS:				
	Dass, H.					

2.	Glyn James, "Advanced Modern Engineering Mathematics", 3rd Edition, Pearson Education, 2012.
3.	Peter V.O Neil, "Advanced Engineering Mathematics", 7th Edition, Cengage learning, 2012.
4.	Ramana B.V, "Higher Engineering Mathematics", Tata McGraw Hill Publishing Company, New Delhi, 2008.
5.	Sivarama Krishna Das P. and Rukmangadachari E., "Engineering Mathematics", Volume I, Second Edition, PEARSON Publishing, 2011.

_	POs									PSOs					
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	1		1			1	1	2		2	3	2	
CO2	3	2	1		1			1	1	2		2	3	2	
CO3	3	2	1		1			1	1	2		2	3	2	
Average	3	2	1		1			1	1	2		2	3	2	
Round off	3	2	1		1			1	1	2		2	3	2	

18ZES	103	В	SIC ELECTRICAL ENGINE	ERING	L	T	P	C
		(Co	nmon to Mech & CSE)		2	1	0	3
OBJEC	CTIVE	ES:			•		•	•
•	To in	itroduce	electric circuits and theorems.					
•	To ur	nderstar	the basics of AC circuits					
•	To st	udy the	Basics of Transformer					
•	To ur	nderstai	the concept of electrical machines					
•	To st	udy abo	t the electrical installations					
UNIT I		DC C	RCUITS					9
Superposition circuits.	on, The	evenin a	simple circuits with DC excit d Norton Theorems. Time-domain					nd Ro
UNIT II		AC C	RCUITS					9
reactive pov consisting o	wer, apport	parent C, RL,	I waveforms, peak and RMS values, ower, power factor. Time domain A C, RLC combinations (series and pard current relations in star and delta co	analysis of sinallel), resonar	ngle-p	hase	ac c	ircuit
reactive pove consisting of balanced cire. UNIT III	wer, appof R, L, creuits, v	parent C, RL, oltage a	ower, power factor. Time domain A C, RLC combinations (series and pard current relations in star and delta constructions)	analysis of sinallel), resonar onnections.	ngle-p nce. T	hase hree-	ac c	ircuit e 9
reactive pove consisting of balanced cire. UNIT III Magnetic m	of R, L, orcuits, v	parent C, RL, coltage a TRAN	ower, power factor. Time domain A C, RLC combinations (series and pard current relations in star and delta co	analysis of sinallel), resonar onnections.	ngle-pace. T	hase hree- ircuit	ac cophaso	e es in
reactive pove consisting of balanced cire. UNIT III Magnetic metransformers	wer, appof R, L, reuits, v	parent C, RL, coltage a TRAN , BH ch ation ar	ower, power factor. Time domain A C, RLC combinations (series and pard current relations in star and delta constructions) SFORMERS racteristics, ideal and practical transfer	analysis of sinallel), resonar onnections.	ngle-pace. T	hase hree- ircuit	ac cophaso	e es in
reactive pove consisting of balanced cire. UNIT III Magnetic metransformers UNIT IV Generation Significance control of characteristics	of rotate of to inductic and s	parent C, RL, coltage a TRAN , BH chation ar ELEC ing magrique-slip on moto peed column to the colu	ower, power factor. Time domain A C, RLC combinations (series and part d current relations in star and delta components and practical transfer efficiency. Auto-transformer and the components and the characteristic. Loss components and an end of the components and the components and the components and the components are components and components and components are components and components and components are components and components are components. Components are components and components are components and components are components and components are components.	ormer, equivalee-phase trans	lent ci	ircuit er co	, loss	es in tions. 9 motor speed
reactive pove consisting of balanced cire. UNIT III Magnetic metransformers. UNIT IV Generation Significance control of	of rotate of to induction and specific and s	rque-slippeed cotary An	ower, power factor. Time domain A C, RLC combinations (series and part d current relations in star and delta components and practical transfer efficiency. Auto-transformer and the components and the characteristic. Loss components and an end of the components and the components and the components and the components are components and components and components are components and components and components are components and components are components. Components are components and components are components and components are components and components are components.	ormer, equivalee-phase transformers of a three-phase transformer, working of synconstruction, working of synconstruction, working of synconstruction.	lent ci	ircuit er co	, loss	es in tions. 9 motor speed
reactive pove consisting of balanced circular transformers. UNIT III Magnetic metransformers. UNIT IV Generation Significance control of characteristing generators [I] UNIT V DC-DC buckinverters; si ELCB, MCG for Batteries.	of rotate of to induction	parent C, RL, coltage a TRAN , BH chation ar ELEC ing magrique-slip on motopeed coltary An POW INST. Coost collaboration and modupes of the collaboration in	ower, power factor. Time domain A C, RLC combinations (series and pard current relations in star and delta constructions, ideal and practical transformer and three transformers. Auto-transformer and three transformers. CRICAL MACHINES detic fields, Construction and working characteristic. Loss components a characteristic. Loss components a single-phase induction motor. Construction and working of the construction and working characteristic. Construction and working characteristics. Construction and working characteristics.	ormer, equivalee-phase transformstruction, working of syncorrer Switch Fus Batteries, Imp	hase in the chrone chro	inducting ag, to bus	, loss nnect and orque tage ;	es in tions. 9 motor speed-speed 9 sourc MCB cristic
reactive pove consisting of balanced cire. UNIT III Magnetic metransformers. UNIT IV Generation Significance control of characteristing generators [I] UNIT V DC-DC buckinverters; si ELCB, MC of batteries.	of rotate of to induction	parent C, RL, coltage a TRAN , BH chation ar ELEC ing magrique-slip on motopeed coltary An POW INST. Coost collaboration and modupes of the collaboration in	wer, power factor. Time domain A C, RLC combinations (series and pard current relations in star and delta constructions in star and delta constructions, ideal and practical transfer efficiency. Auto-transformer and the TRICAL MACHINES TRICAL M	ormer, equivalee-phase transformstruction, working of syncorrer Switch Fus Batteries, Imp	hase in hase i	ircuit er con inducting ig, to ous	, loss nnect and orque tage :	es in ions. 9 motor speed-speed Source MCE cristic
reactive pove consisting of balanced circular transformers. UNIT III Magnetic metransformers. UNIT IV Generation Significance control of characteristing generators [IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	of rotate of to induction	parent C, RL, coltage a TRAN , BH chation ar ELEC ing magrique-slip on motopeed coltary An POWI INSTA poost colal modupes of Ventary collaboration are collaborative control of Ventary Collaborative	wer, power factor. Time domain A C, RLC combinations (series and pard current relations in star and delta constructions in star and delta constructions, ideal and practical transfer efficiency. Auto-transformer and the TRICAL MACHINES TRICAL M	ormer, equivalee-phase transformer of a three-phase transformer, working of syncorking	hase in hase i	ircuit er con inducting ig, to ous	, loss nnect and orque tage :	es in ions. 9 motor speed-speed Source MCE cristic
reactive pove consisting of balanced circular transformers. UNIT III Magnetic metransformers. UNIT IV Generation Significance control of characteristing generators [IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	of rotate of to induction	parent C, RL, coltage a TRAN , BH chation ar ELEC ing magrique-slip on motopeed coltary An POW INST. Coost colla modupes of the entary of An	ower, power factor. Time domain A C, RLC combinations (series and pard current relations in star and delta constructions in star and delta constructions. Auto-transformer and three transformer and working characteristic. Loss components a characteristic. Loss components a single-phase induction motor. Construction and working of the transformer and three transformer and working characteristic. Loss components a characteristic characteristic characteristic. Loss components a characteristic characterist	ormer, equivalee-phase transformstruction, working of syncorrer Switch Fus Batteries, Impower factor in TOTA	hase in hase i	ircuit er con inducting ig, to ous	, loss nnect and orque tage :	es in ions. 9 motor speed-speed Source MCE cristic
reactive por consisting of balanced circumstring of balanced circumstransformers. UNIT III Magnetic metransformers. UNIT IV Generation Significance control of characteristing generators [II] UNIT V DC-DC buckinverters; si ELCB, MC for Batteries battery Back OUTCON 1. U	of rotate of to induction	parent C, RL, coltage a TRAN , BH chation ar ELEC ing magrique-slip on motopeed coltary An POW INST. Coost colla modupes of the entary of the	ower, power factor. Time domain A C, RLC combinations (series and pard current relations in star and delta constructions in star and delta constructions, ideal and practical transfer efficiency. Auto-transformer and the TRICAL MACHINES TRICAL	ormer, equivalee-phase transformstruction, working of syncorrer Switch Fus Batteries, Impower factor in TOTA	hase in hase i	ircuit er con inducting ig, to ous	, loss nnect and orque tage :	es in ions. 9 motor speed-speed MCB cristic

TEXT	TEXT BOOKS:							
1.	D. P. Kothari and I. J. Nagrath, "Basic Electrical Engineering", Tata McGraw Hill, 2010.							
2.	D. C. Kulshreshtha, "Basic Electrical Engineering", McGraw Hill, 2009.							
3.	L. S. Bobrow, "Fundamentals of Electrical Engineering", Oxford University Press, 2011							
REFE	RENCES:							
1.	E. Hughes, "Electrical and Electronics Technology", Pearson, 2010.							
2.	V. D. Toro, "Electrical Engineering Fundamentals", Prentice Hall India, 1989.							

MAPPING	OF C	COs,	POs .	AND	PSC	s:									
						P	Os							PSOs	3
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2		3					3			3	2	1
CO2	3	2	2		3					3			3	2	1
CO3	3	2	2		3					3			3	2	1
Average	3	2	2		3					3			3	2	1
Round off	3	2	2		3					3			3	2	1
3- Strong Cor	relatio	on; 2	- Med	ium (Correl	ation	; 1 – l	Low (Correl	ation					

18ZES10	ENGINEERING GRAPHICS AND DESIGN	L	T	P	C		
	1	0	4	3			
COURSE	OBJECTIVES:						
•	This course aims to introduce the concept of graphic communication, develop the drawin skills for communicating concepts, ideas and designs of engineering products and to expot them to existing national standards related to technical drawings						
•	To draw the projection of simple solids like prisms, pyramids, cylinder etc.						
_	To draw the development of surfaces to estimate the sheet metal requirement and t prepare sectional views of solids.						
•	To develop skills in three-dimensional visualization of engineering draw isometric views of simple solids.	con	npon	ents a	and to		

CONCEPTS AND CONVENTIONS (Not for Examination)

Importance of graphics in engineering applications – use of drafting instruments – BIS / ISO conventions and specifications – size, layout and folding of drawing sheets – lettering and dimensioning.

UNIT I PLANE CURVES AND FREE-HAND SKETCHING

6+9

Basic geometrical constructions, curves used in engineering. Conics – construction of ellipse, parabola and hyperbola by eccentricity method – drawing of tangents and normal to the above curves. Visualization concepts and free hand sketching: visualization principles –representation of three dimensional objects – layout of views- freehand sketching of multiple views from pictorial views of objects.

UNIT II PROJECTION OF POINTS, LINES AND PLANE SURFACES 6+9

Orthographic projection – Principles-principal planes - First angle projection - Projection of points - Projection of straight lines inclined to both the principal planes - determination of true lengths and true inclinations by rotating line method - traces. Projection of planes (polygonal and circular surfaces) inclined to both the principal planes by rotating object method.

UNIT III PROJECTION OF SOLIDS

6+9

Projection of simple solids like prisms, pyramids, cylinder, cone and truncated solids, when the axis is inclined to both the principal planes by rotating object method.

UNIT IV PROJECTION OF SECTIONED SOLIDS AND DEVELOPMENT 6+9 OF SURFACES

Sectioning of prisms, pyramids, cylinders and cones in simple vertical position when the cutting plane is inclined to the one of the principal planes and perpendicular to the other – obtaining true shape of section. Development of lateral surfaces of simple and sectioned solids – prisms, pyramids cylinders and cones.

UNIT V ISOMETRIC PROJECTION AND OVERVIEW OF COMPUTER GRAPHICS 6+9

Principles of isometric projection – isometric scale –isometric projections of simple solids and truncated solids - prisms, pyramids, cylinders, cones- combination of two solid objects in simple vertical positions – Introduction to CAD - The Menu System, Toolbars (Standard, Object Properties, Draw, Modify and Dimension), Drawing Area (Background, Crosshairs, Coordinate System), Dialog boxes and windows, Shortcut menus (Button Bars), The Command Line (where applicable), The Status Bar, Different methods of zoom as used in CAD- (CAD – evaluation during CA only)

Lectui	re: 15 Periods Tutorial: 0 Periods Practical: 60 Periods Total: 75 Periods
OUTCO	MES: On completion of this course, students will be able to
1	Familiarize with the fundamentals, standards of Engineering graphics and Perform freehand sketching of multiple views of basic geometrical constructions.
2	Draw orthographic projections of points, lines and plane surfaces.
3	Draw projections of solids, sectioned solids and development of surfaces.
4	Visualize and draw isometric views of simple solids.
5	Appreciate the use of computers in drawing and modelling of simple objects.
TEXT B	OOKS:
1.	Natrajan K. V., "A text book of Engineering Graphics", Dhanalakshmi Publishers, Chennai, 2016.
2.	Venugopal K. and Prabhu Raja V., " Engineering Graphics ", New Age International (P) Limited, 2016.
3.	Shah, M. B. and Rana B. C. "Engineering Drawing and Computer Graphics", Pearson Education, 2010
REFERI	ENCES:
1.	N S Parthasarathy and Vela Murali, "Engineering Graphics", Oxford University, Press, New Delhi, 2015.
2.	Gopalakrishna K.R., "Engineering Drawing" (Vol. I&II combined), Subhas publications, Bangalore, 2014.
3.	Basant Agarwal and Agarwal C.M., "Engineering Drawing", Tata McGraw Hill Publishing Company Limited, New Delhi, 2013.
4.	Luzzader, Warren J. and Duff John M., "Fundamentals of Engineering Drawing with an introduction to Interactive Computer Graphics for Design and Production", Eastern Economy Edition, Prentice Hall of India Pvt. Ltd, New Delhi, 2005
5.	Bhatt N. D. and Panchal V. M., "Engineering Drawing", Charotar Publishing House, 53 rd Edition, 2014.

						P	Os							PSOs	;
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2		3		3			3			3	2	2
CO2	3	2	2		3		3			3			3	2	2
CO3	3	2	2		3		3			3			3	2	2
CO4	3	2	2		3		3			3			3	2	2
CO5	3	2	2		3		3			3			3	2	2
Average	3	2	2		3		3			3			3	2	2
Round off	3	2	2		3		3			3			3	2	2

18EMS10	6	PHYSICS LABORATORY	L	T	P	C
		(Common to MECH, EEE, ECE & CSE)	0	0	3	1.5
OBJECT	IVE	S				
_		troduce different experiments to test basic understanding of ed in optics, thermal physics, properties of matter and liquid		sics	conce	epts
LIST OF EXPERIM		PERIMENTS : PHYSICS LABORATORY (AN	Y 5			
1.	Det	ermination of rigidity modulus : Torsion Pendulum				
2.	Det	ermination of Young"s modulus by non-uniform bending m	etho	d		
3.		Determination of wave length and particle size using LASE Determination of acceptance angle in an optical fibre	R			
4.	Det	ermination of thermal conductivity of a bad conductor - Le	e"s D)isc	meth	od
5.		ermination of velocity of sound and compressibility of fluid	l — U.	ltras	onic	
6.	Det	ermination of wavelength of mercury spectrum – Spectrome	eter g	grati	ng	
7.	Det	ermination of band gap of a semiconductor				
			To	tal	: 45	Period
OUTCON	MES	On completion of this course, students will be able to				
		e course, the student will be able to apply principles of elast properties for engineering applications.	icity,	opt	ical a	nd

Mapping of	COs	s, POs	and	PSOs	:										
						P	Os							PSO	S
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	1		1			1	1	2		2	3	2	
Average	3	2	1		1			1	1	2		2	3	2	
Round off	3	2	1		1			1	1	2		2	3	2	
3- Strong C	orrel	lation	; 2 - N	Aediu	m Co	rrelat	ion; 1	-Lo	w Co	rrelati	on		•	•	•

18ZES	ZES107 BASIC ELECTRICAL ENGINEERING LABORATORY L T P C (Common to MECH & CSE) 0 0 4 2																				
		((Cor	nmoı	ı to l	ME	СН	I &	z C	CSI	E)						0	0		4	2
OBJEC	CTIVE	S:																	•		•
•	To intr	oduc	ice ba	asic el	ectri	cal n	neas	suri	ing	g In	nstr	ume	ents.								
•	To obta	ain t	trans	ient a	nd ste	eady	sta	ate c	cha	arac	acte	ristic	cs o	f ele	ectric	al ci	rcuit	S.			
•	To obta	ain d	diffe	rent e	lectri	cal r	macl	chine	nes :	an	nd t	rans	forn	ner	basic	cha	racte	ristics	١.		
•	To intr	oduc	ice ba	asic p	ower	con	vert	ters.	5.												
LIST (F EXI	PER	RIM	ENT	ΓS :				-												
1.	(a) Stu (b) M	•											resis	stive	load	ls.					
2.	(a) Mo (b) Ide						-	-					_			Cap	acito	s valı	ıes	S.	
3.	a) Stea a Step b) Sir and vo c) Oba d) Res	o inp nusoi erific	put vo pidal ication vation	oltage steady on. of pl	usin y stat	g a s e res diffe	stora spon	rage nse (e os	scil f R-	illos L,	and	e. R-C	C cii	rcuits	s — i1	nped				ion
4.	(a) Ob (b) Lo												n Tra	ansf	forme	er or	an o	scillo	SC	ope.	
5.	Measi	urem	nent	of thr	ee ph	iase	pow	ver i	in	ıat	bala	ance	d th	ree	phas	e ciı	cuits				
6.	Demo (a) DO arrang cage r (c) sys (d) Sir	C magemerotor	nachin nent) r) ronoi	ne (co (b)Inc	mmu luction	taton on m	r-bro achi	rush nine wing	h e (so ngin	squi	iirre	el	ring	arra	ngen	nent)				
7.	Torqu	ie Sp	peed	Chara	acteri	istics	s of	DC	$\mathbb{C}[S]$	Shu	unt	mote	or.								
8.	(a)Syn (b)Din (c) Ton (d) Ge	rection rque	ion re e-Slip	eversa Cha	al by racte	chan ristic	nge of	of p	pha n in	ase ndu	e-se ucti	que on r	nce note	of c or.	onne	ectio	ns.		us	spee	ed.

9.	(b) dc-ac (c) the use	ration of converters converters – PWM waveform e of dc-ac converter for speed control of an induction motor onents of LT switchgear.								
		TOTAL PERIODS	45							
OUTC	OMES:	After the course, the student will be able to								
	1.	Identify common electrical components and their ratings								
	2.	Make electrical connections by wires of appropriate ratings	S.							
	3.	Understand the usage of common electrical measuring inst	ruments.							
	4. Understand the basic characteristics of transformers and electrical machines.									
	5. Understand the working of power electronic converters.									

		POs												PSOs	;
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2		3					3			3	2	1
CO2	3	2	2		3					3			3	2	1
CO3	3	2	2		3					3			3	2	1
CO4	3	2	2		3					3			3	2	1
CO5	3	2	2		3					3			3	2	1
Average	3	2	2		3					3			3	2	1
Round off	3	2	2		3					3			3	2	1

18MBS201	APPLIED CHEMISTRY	L	T	P	C
		3	0	0	3
OBJECTIVES:			<u>l</u>	I	—
• To mak	e students conversant with water parameters, boilers, need for w	ater	trea	tmer	nt
and acq	uire basic knowledge in spectroscopy and its applications.				
	s ought to be aware of fundamental principles behind different e	lecti	roch	emic	al
	is, corrosion of materials, methods to prevent corrosion and indu				
	nce of alloys.				
-	n the chemistry behind polymers, synthesis, merits, demerits and	its	appl	icati	ons
	us field.				
To acqu	ire basic knowledge in non-conventional energy resources and t	he c	hem	nical	
-	is involved in cell, batteries and function of lubricants.				
To learn	n the chemistry behind fuels and combustion.				
UNIT I	WATER TECHNOLOGY AND ANALYTICAL TECHNIC	QUI	ES	9	
	: Characteristics – alkalinity and its significance – hardness (pro	oble	ms)	- ty	pes
	EDTA method – potable water treatment – boiler feed water -			-	_
disadvantages of u	sing hard water in boilers (Scales & Sludge, Boiler corrosi	ion,	Pri	ming	. &
	embrittlement) – water treatment – Internal treatment – exter				
Demineralization pr	ocess – desalination – reverse osmosis.				
Analytical Techni	ques: Electromagnetic spectrum – Beer-Lambert's law - F	und	ame	ntals	of
spectroscopy – (Ins	rumentation) of UV-Visible, AAS, Flame photometry.				
UNIT II F	CLECTROCHEMISTRY, CORROSION AND ALLOYS			9	
Electrochemistry:	Electrochemical cells – reversible and irreversible cells – EMF	- n	neas	urem	ent
of EMF – single ele	ectrode potential – Nernst equation (Problems) – reference elect	trod	e – s	stand	ard
hydrogen electrode	and calomel electrode – electrochemical series and its application	ons.			
Corrosion: Corrosi	on - Pilling Bedworth rule - dry corrosion - electrochemical co	orro	sion	– ty	pes
(galvanic, pitting, d	ifferential aeration) – factors influencing corrosion – corrosion	cont	rol 1	meth	ods
- sacrificial anode	method - impressed current cathodic method - protective coa	ting	$s-\frac{1}{2}$	paint	is –
constituents - func	tions - metallic coatings - electroplating (Cu) and electro le	ss p	olatii	ng (I	Ni).
Alloys – importanc	e of alloys - heat treatment of alloys - Ferrous alloys (nichror	ne a	nd s	stain	less
steel) – non-ferrous	alloys (Brass and bronze).				
UNIT III	POLYMERS AND COMPOSITES			9	
Polymers: Definition	on – classification – functionality – polymerization – degree of p	olyı	neri	zatic	n –
types (addition, c	ondensation, copolymerization) - mechanism (free radical) –	pla	astics	, –
thermoplastics and	thermosetting plastics - preparation, properties and uses of indi-	vidu	ıal p	olyn	iers
(PVC, TEFLON, N	Nylon-6,6, Nylon-6, PET, epoxy resin) – rubber - vulcanizati	ion	of r	ubbe	r –
applications - Ac	vanced polymeric materials and electronic devices - c	cond	ucti	ng	and
semiconducting pol	ymers - liquid crystal properties - definition: dendrimers and	thei	r di	ffere	nce
from polymers.					
-	ition - types polymer matrix composites - Fibre Reinforc		-		s –
	nced composite materials – physical and chemical properties – a			ons.	
UNIT IV	NON-CONVENTIONAL ENERGY SOURCES AND STORAGE DEVICES - LUBR	ICA	NTS	9	
	renewable energy resources and their importance - Nuclear energy				
_	rater nuclear reactor for power generation – breeder reactor				
	cells – wind energy – batteries: alkaline batteries – lead–acid a				
disadvantages	eries – fuel cells – H_2 - O_2 fuel cell - principles and applications –	auv	anta	iges	and

disadvantages.

Lubricants: Lubricants - mechanism of lubrication, classification and properties of lubricants (viscosity index, flash and fire points, cloud and pour points, oilyness), Additives for lubricants, synthetic lubricants, Greases – Preparation & properties (consistency, drop point) and uses.

UNIT V FUELS AND COMBUSTION

COURSE OUTCOMES

New Delhi, 2008.

2

9

Classification - Calorific value - coal - analysis of coal (Proximate and Ultimate) - metallurgical coke - manufacture by Otto-Hoffmann method - petroleum - manufacture of synthetic petrol (Bergius method) - Knocking -octane number - diesel oil - cetane number - natural gas - compressed natural gas (CNG) - Liquefied petroleum gas (LPG) - Producer gas - water gas. Power alcohol - biodiesel and its synthesis (transesterification) - chromatographic analysis of biodiesel.

Combustion of fuels: theoretical calculation of calorific value – calculation of stoichiometry of fuel and air ratio – ignition temperature – explosive range – flue gas analysis (ORSAT apparatus)

TOTAL PERIODS 45

On completion of the course the student will be able to, apply the knowledge of basic science in identifying, to formulate and to solve the engineering problems. analyze water borne problems faced in boilers, water treatment methods and analytical techniques and its applications. understand polymerization reactions and electrochemical reactions and its applications. Obtain knowledge in various renewable energy resources, Batteries, fuel cells, lubricants and its applications. acquire in-depth knowledge in fuels and combustion. TEXT BOOKS: Vairam S, Kalyani P and SubaRamesh., "Engineering Chemistry"., Wiley India PvtLtd., New Delhi., 2011

	2010
REFERI	ENCES:
1.	Pahari A and Chauhan B., "Engineering Chemistry"., Firewall Media., New Delhi.,
	2010.
2.	Jain and jain , 16 th editin, "Engineering Chemistry" Dhanpat Rqai Publishing Co.
3.	Foster R., Ghassemi M., Cota A., "Solar Energy", CRC Press, 2010.
4.	Physical Chemistry, P.W. Atkin (ELBS, Oxford Press).
5.	Sivasankar B, "Engineering Chemistry", Tata Mc Graw-Hill Publishing Company Ltd,

Dara S.S, UmareS.S. "Engineering Chemistry", S. Chand & Company Ltd., New Delhi,

Mapping of	COs, PO)s and	l PSO	s:											
						PO	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2		2		1			1			1	1			
CO2	2	1	3		1			1	1		2	1			
CO3	2		1		1			1	1		2	1	2		1
CO4	2		3		2			1	1		2	1	1		1

CO3	2		1	1		1	1	2	1	2	1
CO4	2		3	2		1	1	2	1	1	1
CO5	2		1	2		1	1	2	1	1	1
Average	2	1	2	1.4		1	0.8	1.8	1	0.8	0.6
Round off	2	1	2	1		1	1	2	1	0.8	1

3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation

18 Z B	BS202											
		(Common to MECH, EEE, ECE & CSE)	3	1	0	4						
OBJE	CTIVI	ES										
•	Vec	or calculus and their uses in various field theoretic subjects										
•	_	ner order and special type of linear differential equations and tions.	l method	s to fi	ind							
•		ace transforms and properties and their applications in engi-										
•		struction of analytic functions and concepts of concepts of c plex integration and series solutions.	onforma	l map	ping	,						
UNIT	I	VECTOR CALCULUS			9	9+3						
Vector is	ntegrati	gence and curl – Directional derivative – Irrotational and solon – Green,,s theorem in a plane, Gauss divergence theorem (fs) – Simple applications involving cubes and rectangular p	and Sto	kes,, t	heor							
UNIT :	II	ORDINARY DIFFERENTIAL EQUATIONS				9+3						
paramete	ers – Ca	ear differential equations with constant coefficients – Methouchy,,s and Legendre,,s linear equations – Simultaneous fir				tion						
with con	nstant co	pefficients.			1	itiOii						
UNIT : Laplace Basic pr	transfo	LAPLACE TRANSFORMS rm – Sufficient condition for existence – Transform of s – Transforms of derivatives and integrals of functions - D	elementa Perivativa	ary fu	nctio	9+3 ons -						
Laplace Basic pr of transf function theorem	transforoperties forms - as. Inverties - Solu	LAPLACE TRANSFORMS rm – Sufficient condition for existence – Transform of	elementa erivative Transfo	ary fu es and orm o	nction interest in all	9+3 ons - egral riodic						
Laplace Basic pr of transf function theorem	transforoperties forms - as. Inverties - Solumation t	LAPLACE TRANSFORMS rm – Sufficient condition for existence – Transform of s – Transforms of derivatives and integrals of functions - D. Transforms of unit step function and impulse functions – see Laplace transform -Statement of Convolution theorem ation of linear ODE of second order with constant coefficients.	elementa erivative Transfo	ary fu es and orm o	nctice	9+3 ons - egral riodic						
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Laplace Basic pr of transf function theorem transform UNIT Function equation analytic mapping UNIT Complex integral Cauchy,	transforoperties forms - as. Inverties - Solumation to IV IN IN IN IN IN IN IN IN IN	Transforms of derivatives and integrals of functions - Days and Transforms of derivatives and integrals of functions - Days are Laplace transform -Statement of Convolution theorem attion of linear ODE of second order with constant coefficient echniques. ANALYTIC FUNCTIONS Tomplex variable – Analytic functions: Necessary conditions afficient conditions (excluding proofs) – Harmonic and orthough the Harmonic conjugate – Construction of analytic functions +k, kz, 1/z, z², e² and bilinear transformation.	elementa verivative Transfo Initial ts using — Caucl ogonal p s — Conf	ary fury fury and form of and formal and formal and formal and formal fo	neticial interior in al line in aline in al line in al	9+3 ons egral iodic value 9+3 n of 9+3						
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3.	1	s on Laplace transforms and will be able to use Laplace transform in ns of differential and integral equations and other engineering applications.
4.		integration problems and will be exposed to various applications of ons and conformal mapping in engineering.
TEXT	BOOKS:	
1.		Manish Goyal, "A Text book of Engineering Mathematics", Eighth Publications Pvt Ltd., 2011.
2.	Grewal. B.S, "Delhi, 2011.	Higher Engineering Mathematics ", 41 st Edition, Khanna Publications,
REFE	ERENCES:	
1.	Dass, H.K., and Private Ltd., 20	d Er. Rajnish Verma, " Higher Engineering Mathematics ", S. Chand 011.
2.	Glyn James, "A Education, 201	Advanced Modern Engineering Mathematics", 3rd Edition, Pearson 2.
3.	Peter V. O,,Net 2012.	il, "Advanced Engineering Mathematics", 7th Edition, Cengage learning,
4.	Ramana B.V, "Company, New	Higher Engineering Mathematics ", Tata McGraw Hill Publishing v Delhi, 2008.
5.		nna Das P. and Rukmangadachari E., " Engineering Mathematics ", cond Edition, PEARSON Publishing, 2011.

MAPPING	OF CO	Os, Po	Os AN	ID PS	SOs:										
						P	Os						PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2		3					3			3	2	1
CO2	3	2	2		3					3			3	2	1
CO3	3	2	2		3					3			3	2	1
CO4	3	2	2		3					3			3	2	1
Average	3	2	2		3					3			3	2	1
Round off	3	2	2		3					3			3	2	1
3- Strong Co	rrela	tion; 2	2 - Me	edium	Cor	relatio	n; 1 -	- Low	Corr	elatio	n	•		•	

18MES203	PROGRAMMING IN PYTHON	L	T	P	C
		3	0	0	3
OBJECTIV	ES:			L	
•	To know the basics of algorithmic problem solving				
•	To read and write simple Python programs.				
•	To develop Python programs with conditionals and loops.				
•	To define Python functions and call them.				
•	To use Python data structures – lists, tuples, dictionaries.				
•	To do input/output with files in Python.				
UNIT I	ALGORITHMIC PROBLEM SOLVING				
strategies for in a list, insert Hanoi.	flow chart, programming language), algorithmic problem developing algorithms (iteration, recursion). Illustrative problem a card in a list of sorted cards, and guess an integer number in	ems:	fino	d min	imu ers o
UNIT II	DATA, EXPRESSIONS, STATEMENTS				
variables, dist	ustrative programs: exchange the values of two variables, circulance between two points.	late	the v	alues	01 1
variables, dist UNIT III Conditionals: conditional (i return values, string slices,	ance between two points. CONTROL FLOW, FUNCTIONS Boolean values and operators, conditional (if), alternative f-elif-else); Iteration: state, while, for, break, continue, pass; parameters, local and global scope, function composition, immutability, string functions and methods, string module	e (if Fru recu e; I	E-else uitful ursio Lists	e), ch func on; So as a	naine etion tring
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variables, dist UNIT III Conditionals: conditional (i return values, string slices, Illustrative pre	ance between two points. CONTROL FLOW, FUNCTIONS Boolean values and operators, conditional (if), alternative f-elif-else); Iteration: state, while, for, break, continue, pass; parameters, local and global scope, function composition, immutability, string functions and methods, string module ograms: square root, gcd, exponentiation, sum an array of num	e (if Fru recu e; I	E-else uitful ursio Lists	e), ch func on; So as a	naine etion tring array earcl
variables, dist UNIT III Conditionals: conditional (i return values, string slices, Illustrative pre binary search. UNIT IV Lists: list ope parameters; 7 methods; adva	ance between two points. CONTROL FLOW, FUNCTIONS Boolean values and operators, conditional (if), alternative f-elif-else); Iteration: state, while, for, break, continue, pass; parameters, local and global scope, function composition, immutability, string functions and methods, string module ograms: square root, gcd, exponentiation, sum an array of number of the property of the	e (if Fru recu e; I nbers	F-else nitful ursio Lists s, lin onin oper	e), ch func in; Si as a aear se g list	naine etion erray earch
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5.	Represent co	mpound data using Python lists, tuples, and dictionaries.
TEXT	BOOKS:	
1.	Allen B. Dov	vney, "Think Python: How to Think Like a Computer Scientist", 2 nd
	edition, Up	odated for Python 3, Shroff/O,,Reilly Publishers, 2016
	(http://greente	eapress.com/wp/think- python/).
2.	Guido van Ro	ossum and Fred L. Drake Jr, "An Introduction to Python – Revised and
	updated for P	ython 3.2", Network Theory Ltd., 2011.
3.	Dr.A.Kannan	, Dr.L.Sairamesh, "Problem Solving and Python programming", United
	Global Publis	hers Pvt. Ltd., 2017.
REFE	RENCES:	
1.	Robert Sedg	ewick, Kevin Wayne, Robert Dondero, "Introduction to Programming
	in Python: A	An Inter-disciplinary Approach", Pearson India Education Services Pvt.
	Ltd., 2016.	
2.	Timothy A. I	Budd, "Exploring Python", Mc-Graw Hill Education (India) Private
	Ltd., 2015.	
3.	Kenneth A. I	Lambert, "Fundamentals of Python: First Programs", CENGAGE
	Learning, 20	012.

MAPPING	OF C	COs, I	POs A	ND P	SOs:											
						P	Os						PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	3	2	2		3					3			3	2	1	
CO2	3	2	2		3					3			3	2	1	
CO3	3	2	2		3					3			3	2	1	
CO4	3	2	2		3					3			3	2	1	
CO5	3	2	2		3					3			3	2	1	
Average	3	2	2		3					3			3	2	1	
Round off	3	2	2		3					3			3	2	1	
3- Strong C	orrel	ation;	2 - M	lediu	m Co	rrelat	ion; 1	- Lo	w Coi	rrelati	on	ı				

18ZHS	8ZHS204 TECHNICAL ENGLISH L T						
			(Common to MECH, EEE, ECE & CSE)	2	0	0	2
OBJECT	TIVES	S :		1			
•	To be	able	e to acquire vocabulary by way of reading skills.				
•	To be	able	e to write iterative as well as recursive programs.				
•	To be progra		e to represent data in arrays, strings and structures and r	nanipula	te them	thro	ugh a
•	To be structu		e to declare pointers of different types and use them in c	lefining	self- re	ferent	ial
•	To be	able	e to create, read and write to and from simple text files.				
UNIT I		V	CABULARY BUILDING				6
Acquaintar	nce wit	th p	d Formation - Root words from foreign languages a prefixes and suffixes from foreign languages in Engles, and standard abbreviations				
UNIT II		BA	SIC WRITING SKILLS				6
			Use of phrases and clauses in sentences - Importance of Organizing principles of paragraphs in documents - Teo				-
UNIT III	[]	DI	ENTIFYING COMMON ERRORS IN WRIT	TING			6
Subject-ve Redundance	_		ent - Noun-pronoun agreement - Misplaced modifiers - és	Articles	- Prepo	sition	1S -
UNIT IV	7 I	NA	TURE AND STYLE OF SENSIBLE WRITI	NG			6
Describing conclusion		ning	g - Classifying - Providing examples or evidence - Writ	ing intro	duction	and	
UNIT V	1	WF	RITING PRACTICES				6
Comprehe	nsion -	Pré	cis Writing - Essay Writing				
			TOTAL: 30	PERIC	DDS		
OUTCO	MES:	: A	At the end of the course, the students will be ab	le to			
	-		sic proficiency in English including reading and listening skills.	ng comp	rehensi	on,	

2.	Participate effectively in formal and informal conversations; introduce themselves and express their opinions in English.
3.	Comprehend conversations and deliver short talks in English.
4.	Write essays and descriptions of any kind in English.
5.	Prepare reports, graph presentation and Technical writing.
TEXT	BOOKS:
1.	On Writing Well. William Zinsser. Harper Resource Book. 2001
2.	Study Writing. Liz Hamp-Lyons and Ben Heasly. Cambridge University Press. 2006.
3.	Communication Skills. Sanjay Kumar and PushpLata. Oxford University Press. 2011.
REFE	RENCES:
1.	Richards, C. Jack .Interchange Students' Book-2 New Delhi: CUP, 2015.
2.	Bailey ,Stephen. Academic Writing: A Practical guide for students .New York: Rutledge, 2011.
3.	Seely, John. The Oxford guide to writing & Speaking. New York. 1998.
4.	Bhatia M.P , A Handbook of APPLIED GRAMMAR , M.I Publications, AGRA, Sixth Edition

		POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1					3				3						1	
CO2					3				3						1	
CO3					3				3						1	
CO4					3				3						1	
CO5					3				3						1	
Average					3				3						1	
Round off					3				3						1	

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18EMS20	06	CHEMISTRY LABORATORY	L	T	P	C	
		(Common to MECH, EEE, ECE & CSE)	0	0	3	1.5	
OBJECTIV	ES:						
1.	1. To make students conversant with hands on water parameter analyst						
2.	To make t	he student to acquire practical skills in the corrosion in metals.					
3.	3. To acquaint the students with the determination of molecular weight by Ostwald viscometer.						
4.	To make	the student acquire practical skills in analytical instruments	S.				

LIST OF EXPERIMENTS:

- 1. Determination of total hardness of given water sample by EDTA method.
- 2. Determination of alkalinity in given water sample.
- 3. Determination of molecular weight of polyvinyl alcohol using Ostwald viscometer.
- 4. Conductometric titration using mixture of acids and strong base.
- 5. Determination of strength of in given hydrochloric acid using pH meter.
- 6. Estimation of sodium present in water using flame photometer.
- 7. Estimation of Zn present in effluent using Atomic Absorption Spectroscopy(AAS)
- 8. Corrosion experiment weight loss method
- 9. Estimation of iron content of the given solution using potentiometer meter.
- 10. Estimation of iron content of the given sample using Spectro photometer (thiocyanate method).\

(Note: A minimum of SIX experiments shall be offered) List of equipments for a batch of 30 students

- 1. Flame photometer 5 nos
- 2. Weighing balance 5 nos
- 3. Conductivity meter; Potentiometer; pH meter- 9 nos each.
- 4. Ostwald viscometer 30 nos
- 5. Atomic Absorption Spectrophotometer 1 no.

Common apparatus: Pipette, Burette, Burette stand, Standard volumetric flask, funnel, Conical flask, porcelain tiles, dropper, reagent bottles, glass rod, beaker, wash bottle, test tube (30 nos each)

COURS	SE OUTCOMES	At the end of the course students should be able to
1.		ed with hands-on knowledge in the qualitative and ysis of water quality related parameters, corrosion studies,
	heavy metal analysis, etc.	

REFI	ERENCES:	
1.		naford A.J, Smith P.W.G and Tatchel A.R., "Vogel's Textbook of chemistry", LBS Singapore 1994.
2.	00 2	sett J., Mendham J.and Denny vogel's R.C, " Text book of quantitative I analysis" , ELBS 5th Edn. Longman, Singapore publishers,
3.	Kolthoff I.M., San 1980.	dell E.B. et al. "Quantitative chemical analysis", Mcmillan, Madras
4.	Daniel R. Pallero York 2001.	s, "Experimental organic chemistry" John Wiley & Sons, Inc., New

Mapping of	f COs	, POs	and	PSOs	:										
	POs											PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	1	2	1		1			2	1		1	1	1	1	1
Average	1	2	1		1			2	1		1	1	1	1	1
Round off	1	2	1		1			2	1		1	1	1	1	1
3- Strong C	orrel	ation	; 2 - N	Iediu	m Co	rrelat	ion; 1	-Lo	w Coi	rrelat	ion				

18MES207	PROGRAMMING IN PYTHON	L	T	P	C					
	LABORATORY									
		0	0	4	2					
OBJECTIV	ES:									
•	To write, test, and debug simple Python programs.									
•	To implement Python programs with conditionals and loops.									
•	Use functions for structuring Python programs.									
•	Represent compound data using Python lists, tuples, and dictionaries.									
•	Read and write data from/to files in Python.									

LIST OF EXPERIMENTS:

- 1. Compute the GCD of two numbers.
- 2. Find the square root of a number (Newton,,s method).
- 3. Exponentiation (power of a number).
- 4. Find the maximum of a list of numbers.
- 5. Linear search and Binary search.
- 6. Selection sort, Insertion sort.
- 7. Merge sort.
- 8. First n prime numbers.
- 9. Multiply matrices.
- 10. Programs that take command line arguments (word count).
- 11. Find the most frequent words in a text read from a file.
- 12. Simulate elliptical orbits in Pygame.
- 13. Simulate bouncing ball using Pygame.

PLATFORM NEEDED

• Python 3 interpreter for Windows/Linux

		1
		TOTAL: 60 PERIODS
OUTC	OMES:	On completion of this course, students will be able to
1.		and debug simple python programs and Implement with conditionals and
	loops.	
2.	Develop pyth	hon programs step-wise by defining functions and calling them.
3.		lists, tuples, dictionaries for representing compound data and read and
	write data fro	om/to files in python.
COLIDGI		A COLONIA MA A COLOUR

COURSE ARTICULATION MATRIX:

MAPPING OF COs, POs AND PSOs:

						P	Os							PSOs	3
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	2	3		2								2	1	3
CO2		2	3		1									1	3
CO3	2	2	3	2	1								2	1	3
Average	1.3	3	3	.67	1.3								1.3	1	3
Round off	1	3	3	1	1								1	1	3

18ZES208	WORKSHOP PRACTICE	L	T	P	C					
	(Common to MECH, EEE, ECE and CSE Branches)	1	0	4	3					
COURSE OBJECTIVES:										

- To make various basic prototypes in the carpentry trade such as Lap joint, Lap Tee joint, Dove tail joint, Mortise & Tenon joint and Cross-Lap joint
- To make various welding joints such as Lap joint, Lap Tee joint, Edge joint, Butt joint and Corner joint.

LIST OF EXPERIMENTS:

- 1. Introduction to use of tools and equipment in Carpentry, Welding, Foundry and Sheet metal
- 2. Safety aspects in Welding, Carpentry and Foundry
- 3. Half lap Joint and Dovetail Joint in Carpentry
- 4. Welding of Lap joint, Butt joint and T-joint
- 5. Preparation of Sand mold for cube, conical bush, pipes and V pulley
- 6. Fabrication of parts like tray, frustum of cone and square box in sheet metal
- 7. Electrical wiring simple house wiring
- 8. Plumbing
- 9. CNC Machines demonstration and lecture on working principle.
- 10. Additive manufacturing demonstration and lecture on working principle.

Practical: 60 Periods Lecture: 15 Periods Tutorial: 0 Periods Total: 75 Periods COURSE OUTCOMES: on completion of this course, students will be able to Use tools and equipment used in Carpentry, Welding, Foundry and Sheet metal. 2. Make half lap joint dovetail joint in carpentry and welded lap joint, butt joint and T-joint 3 Prepare sand mould for cube, conical bush, pipes and V pulley. Fabricate parts like tray, frustum of cone and square box in sheet metal 4 Carry out minor works/repair related to electrical wiring and plumbing. 5

						P	Os							PSOs	}
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2		3					3			3	2	1
CO2	3	2	2		3					3			3	2	1
CO3	3	2	2		3					3			3	2	1
CO4	3	2	2		3					3			3	2	1
CO5	3	2	2		3					3			3	2	1
Average	3	2	2		3					3			3	2	1
Round off	3	2	2		3					3			3	2	1

18ZH	S209	COMMUNICATION ENG	LISH LAB	L	T	P	C
		(Common to MECH & CS	SE)	0	0	2	1
OBJEC	TIVES	S:					
•	speaki To enl	velop their communicative competency in ng and listening. nance their ability to communicate effection day life communication.					
•		mprehend a different types of accent and	use them in their co	ommun	ication		
UNIT I]	PRONUNCIATTION PRACTICE	E				6
Verbal Al Various le		rticulation of sounds- Intonation-Stress a	nd Rhythm-Conver	rsation	practic	e-liste	ening
UNIT I	[COMMUNICATION AT WORK	PLACE				6
		Writing job applications - cover letter- re ries- interpreting visual texts.	sume- e-mails- me	mos- re	ports.V	Vritir	ıg
UNIT III ENGLISH FOR NATIONAL AND INTERNATIONAL EXAMINATIONS AND PLACEMENTS							6
		lish Language Testing System (IELTS)-Tervice(Language related part) –English f				guage	;
UNIT I	V 1	NTERVIEW SKILLS				6	
Different Body lang		Interview format- answering questions-	offering information	on- moc	k inter	views	S-
UNIT V	7	SOFT SKILLS					6
		ional intelligence-Multiple intelligences- team work- career planning- creative and		- time i	manage	ement	 ;-
		TOTAL HOURS	3	80 Hrs			
OUTCO)MES:	At the end of the course, the studer	nts will be able to	0			
6.	Face in	terviews, group discussions and other lan	nguage parameters	in the jo	ob marl	ket	
7.	Write a	ny competitive examinations which cove	er language part in i	it.			
8.	Take pa	art in any English conversations of any ki	ind in English. Flav	vlessly	withou	t fear	and
9.	Write a	rticles for newspapers and magazines or ses.	any write-up in En	glish w	ithout §	gramı	nar

10.	Come out with leadership qualities, team work and career planning and will also possess critical and creative thinking.
TEXT	BOOKS:
1.	Communication Skills for Engineers and Scientists, PHI Learning PVT.LTD, Delhi, 2014.
2.	Communication Skills and Soft Skills An Integrated Approach, Dorling Kindersley (INDIA) PVT.LTD, New Delhi, 2012.
3.	Soft Skills, MJP Publishers, Chennai, 2010.
REFEI	RENCES:
5.	Craven, Miles. Listening Extra-A resource book of multi-level skills activities. Cambridge University Press, 2004.
6.	Seely, John. The Oxford guide to writing & Speaking. New Delhi: Oxford University Press,20
7.	Comfort, Jeremy, et al. Speaking Effectively: Developing speaking skills for Business English. Cambridge University Press, Cambridge: Reprint 2011.
8.	Dutt P. Kiranmai and RajeevanGeetha. Basic Communication Skills, Foundation Books: 2013

	•				•	P	Os		•	•			•	PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1					3				3						1
CO2					3				3						1
CO3					3				3						1
CO4					3				3						1
CO5					3				3						1
Average					3				3						1
Round off					3				3						1

18M	BS301	TRANSFORMS AND PARTIAL DIFFERENTIAL EQUATIONS	L	T	P	С
			3	1	0	4
OBJE	CTIV	ES				
•		ntroduce Fourier series analysis which is central to many neering apart from its use in solving boundary value prob		in		
•		cquaint the student with Fourier transform techniques use ations.	ed in wide v	ariety	of of	
•	equ	ntroduce the effective mathematical tools for the solution ations that model several physical processes and to develor discrete time systems.				
UNI	ΤΙ	PARTIAL DIFFERENTIAL EQUATIONS				9+3
order p	oartial cons of se	artial differential equations – Singular integrals Solution ifferential equations - Lagrange's linear equation cond and higher order with constant coefficients of boypes.	Linear part	ial c	liffer	ential
UNI	ΓII	FOURIER SERIES				9+3
	nge cos	litions – General Fourier series – Odd and even functions ine series – Complex form of Fourier series – Parser				
UNIT	III	APPLICATIONS OF PARTIAL DIFFERENT EQUATIONS	ΓIAL			9+3
equation	n – One	of PDE – Method of separation of variables - Solutions dimensional equation of heat conduction – Steady state state conduction (excluding insulated edges).				
UNIT	ΓIV	FOURIER TRANSFORMS				9+3
		ourier integral theorem – Fourier transform pair – Fourier Transforms of simple functions – Convolution theorem – I				orms
UNI	ΓV	Z - TRANSFORMS AND DIFFERENCE EQ	UATIONS	5		9+3
	ution th	Elementary properties – Inverse Z - transform (using parteorem - Formation of difference equations – Solution of				
		LECTURE: 45 TUTORIAL: 15 TO)TAL : 60	PE	RIC	DDS
OUTO	COME	S: On completion of this course, students will be able to)			
1.	equation	derstanding of the mathematical principles on transforms would provide them the ability to formulate and some of engineering.	-			

TEX	T BOOKS:
1.	Veerarajan T., "Transforms and Partial Differential Equations", Tata McGraw Hill Education Pvt. Ltd., New Delhi, 3 rd Edition, 2016
2.	Grewal B.S., "Higher Engineering Mathematics", 44 th Edition, Khanna Publishers, Delhi, 2017.
3.	Narayanan S., Manicavachagom Pillay.T.K and Ramanaiah.G "Advanced Mathematics for Engineering Students" Vol. II & III, S.Viswanathan Publishers Pvt Ltd., 1998.
REF	ERENCES:
1.	Bali. N.P and Manish Goyal, "A Textbook of Engineering Mathematics", Laxmi Publications Pvt Ltd, 9 th Edition 2016.
2.	Ramana. B.V., "Higher Engineering Mathematics", Tata McGraw Hill Publishing Company Limited, New Delhi, 2018.
3.	Glyn James, "Advanced Modern Engineering Mathematics", 4 th Edition, Pearson Education, 2016
4.	Erwin Kreyszig, "Advanced Engineering Mathematics", 10 th Edition, Wiley India, 2011.
5.	Ray Wylie C and Barrett .L.C, "Advanced Engineering Mathematics", 6 th Edition, Tata McGraw Hill Education Pvt Ltd, New Delhi, 2012.

MAPPING OF COs, POs AND PSOs:

						P	Os							PSO s	5
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	1		1			1	1	2		2	3	2	
CO2	3	2	1		1			1	1	2		2	3	2	
CO3	3	2	1		1			1	1	2		2	3	2	
CO4	3	2	1		1			1	1	2		2	3	2	
CO5	3	2	1		1			1	1	2		2	3	2	
Average	3	2	1		1			1	1	2		2	3	2	
Round off	3	2	1		1			1	1	2		2	3	2	

18MES	302	ENGINEERING MECHANICS	L	T	P	C					
			3	1	0	4					
OBJEC	TIVE	S									
•		ake the students to apply static equilibrium of rigid bodies both lso in three dimensions.	n in tw	o dii	nens	sions					
•	To comprehend the effect of friction on equilibrium.										
•	To u	nderstand the geometrical properties of surfaces and solids									
•	To u	nderstand various terms involved in Projectiles.									
•	To apply dynamic equilibrium of particles in solving basic problems.										
UNIT I INTRODUCTION TO MECHANICS AND FORCE CONCEPTS 9+											

Principles and Concepts – Laws of mechanics – system of forces – resultant of a force system – resolution and composition of forces –Lami's theorem – moment of a force – physical significance of moment –Varignon's theorem – resolution of a force into force and couple— force in space – addition of concurrent force in space – equilibrium of a particle in space.

UNIT II BASIC STRUCTURAL ANALYSIS ANDFRICTION 9+3

Beams and types of beams -Simple Trusses - Method of Joints - Method of Sections. Friction resistance - classification of friction - laws of friction - coefficient of friction - angle of friction - angle of repose - cone of friction - free body diagram - advantages - equilibrium of a body on a rough inclined plane - non- concurrent force system - ladder friction - rope friction - wedge friction-virtual work method.

UNIT III GEOMETRICAL PROPERTIES OF SECTION 9+3

Centroids – determination by integration – moment of inertia – theorems of moment of inertia – product of inertia – principal moment of inertia of plane areas – radius of gyration- Mass moment inertia of simple solids.

UNIT IV BASICS OF DYNAMICS - KINEMATICS 9+3

Kinematics and kinetics – displacements, velocity and acceleration – equations of motion – rectilinear motion of a particle with uniform velocity, uniform acceleration, varying acceleration – motion curves – motion under gravity –relative motion – curvilinear motion of particles – projectiles – angle of projection – range – time of flight and maximum height-kinematics of rigid bodies.

UNIT V BASICS OF DYNAMICS - KINETICS 9+3

Newton's second law of motion – linear momentum – D'Alembert's principle, dynamics equilibrium – work energy equation of particles – law of conservation of energy – principle of work and energy. Principles of impulse and momentum – equations of momentum – laws of conservation of momentum. impact – time of compression, restitution, collision – co-efficient of restitution – types of impact – collision of elastic bodies by direct central impact and oblique impact – collision of small body with a massive body – kinetic energy of a particle-kinetics of rigid body rotation.

				L	ECT	URI	E: 45	TUT	ORI	AL:	15 T	OTA	L:6	60 PE	CRIO	DS
OUT	COMES	S:	On co	omple	tion o	f this	course	e, stud	lents v	vill be	able	to				
1.	Explain with for			rent p	rincip	les of	mech	anics	and to	solve	engir	neerin	g prob	olems	dealin	ıg
2.	Apply t	he c	oncep	ots of	frictio	n to s	olve v	arious	s prob	lems o	dealin	g with	fricti	on		
3.	Explain	the	diffe	rent g	eomet	rical p	proper	ties o	f vario	ous se	ctions	i				
4.	Solve p	robl	lems i	n rigio	d body	y dyna	mics	(kiner	natic	systen	ns).					
5.	Solve problems in rigid body dynamics (kinetic systems).															
TEX	T BOO	KS	5:													
1.	Beer F.: and Dy	P an	nd Joh nics",	nston 11 th 1	Jr. E. Editio	R., " V n, Tat	r <mark>ector</mark> a McC	Mecl Graw-	hanics Hill P	s for I ublish	E ngin e	eers (l mpan	In SI y, Ne	Units) w Del): Sta t hi (20	tics 15).
2.	Bhavikatti S. S. and Rajashekarappa, K.G., "Engineering Mechanics", New Age International (P) Limited Publishers, 2017.															
3.	Natesan, S.C., "Engineering Mechanics", Umesh publications, New Delhi, 2002															
REF	ERENC	CES	5:													
1.	Hibbell Edition,					-	_	neerii	ng Me	chan	ics: St	atics (and D	ynami	ics", 1	1th
2.	Irving I Dynam									ngine	ering .	Mech	anics	– Stat	tics an	ıd
3.	Meriam Volume									hanics	s- Stat	ics - V	olum	e 1, D	ynam	ics-
4.	Rajasek Dynam												ics St	atics a	and	
5.	Kumar, Publish							nics",	, 3 rd 1	Revise	d Ed	lition,	Tata	и Мс	Graw	-Hill
MAPI	PING C)F (COs,	POs	AN	D PS	Os:									
							P	Os							PSOs	
~~		1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO		3	2	1		1			1	1	2		2	3	2 2	
CO		3	2	1 1		1 1			1	1	2		2	3	2	
CO		3	2	1		1			1	1	2		2	3	2	
CO		3	2	1		1			1	1	2		2	3	2	
							1	1	1							1

3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation

Average

Round off

18MPC303	MANUFACTURING TECHNOLOGY I	L	T	P	C
		3	0	0	3
OBJECTIVES		•	•		

- To help students to acquire knowledge about different metal casting processes.
- To acquire knowledge on various joining processes like welding, brazing, soldering, etc.
- To enable them to understand various bulk deformation processes like forging, rolling, extrusion, etc.
- To understand various operations performed in sheet metals.
- To provide knowledge about various manufacturing techniques to fabricate plastic components.

UNIT I METAL CASTING PROCESSES

9

Introduction to concepts of manufacturing process -sand casting – sand moulds -type of patterns – pattern materials – pattern allowances, simple numerical problems – types of moulding sand – properties – core making – methods of sand testing –riser and gating design, simple numerical problems – moulding machines – types of moulding machines - melting furnaces- principles of special casting processes: shell-investment-pressure die casting-centrifugal casting-co₂ process – sand casting defects

UNIT II JOINING PROCESSES

9

Fusion welding processes – types of gas welding – equipments used – flame characteristics – filler and flux materials - arc welding equipments - electrodes –coating and specifications – principles of resistance welding – spot/butt, friction welding and friction stir welding – percussion welding – flux cored – submerged arc welding – electro slag and gas welding – TIG welding-MIG welding-brazing, soldering and adhesive bonding-weld defects.

UNIT III BULK DEFORMATION PROCESSES

9

Hot working and cold working of metals – forging processes – open and close die forging – types of forging machines – typical forging operations – rolling of metals, simple numerical problems – flat strip rolling – types of rolling mills – tube piercing – principles of extrusion – types of extrusion – hot and cold extrusion – principle of rod and wire drawing.

UNIT IV | SHEET METAL PROCESSES

9

Sheet metal characteristics – shearing, bending and drawing operations – stretch forming operations – formability of sheet metal – test methods –special forming processes-working principle and applications – hydro forming – rubber pad forming – metal spinning – introduction of explosive forming, magnetic pulse forming, peen forming.

UNIT V POW

POWDER METALLURGY AND MANUFACTURE OF PLASTIC COMPONENTS

9

Introduction to powder metallurgy- Production of powders — mixing, blending, compacting, sintering and hot pressing - applications. Types and characteristics of plastics — moulding of thermoplastics and thermosets — working principles and typical applications — injection moulding — plunger and screw machines — compression moulding, transfer moulding —thermoforming.

TOTAL: 45 PERIODS

OUTCOMES: On completion of this course, students will be able to

- 1. Apply the principles of metal casting for engineering applications.
- 2. Select suitable joining process for real time applications.
- 3. Applying bulk deformation processes according to industrial needs.
- 4. Explain and use appropriate metal forming operations in industries.
- 5. | Explore power metallurgy technique and concepts of plastic component manufacturing.

TEXT BOOKS:

- 1. Sharma P.C., "A Text book of Production Technology", S. Chand and Co. Ltd., 2009.
- 2. Kalpakjian S., "Manufacturing Engineering and Technology", Pearson Education India 7thEdition, 2013.
- 3. HajraChoudhary S.K and HajraChoudhury. AK., "Elements of workshop Technology", volume I and II, Media promoters and Publishers Private Ltd, Mumbai, 1997

REFERENCE:

- 1. R.K. Rajput, "A Text Book of Manufacturing Technology", Laxmi Publication Pvt Ltd 2nd Edition, 2017.
- 2. Roy. A. Lindberg, "Processes and Materials of Manufacture", PHI / Pearson Education, 4th Edition, 2008.
- 3. | Gowri P. Hariharan, A.SureshBabu, "Manufacturing Technology I", Pearson Education, 2008.
- 4. M. Adithan and A.B. Gupta, "Manufacturing Technology", New Age International Pvt Ltd, 2003.
- 5. P. N. Rao, "Manufacturing Technology Foundry, Forming and Welding", Tata McGraw Hill 3rd Edition, 2009.

MAPPING OF COs, POs AND PSOs:

		POs									PSOs				
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	1	1		1	1		1	1	2		1	2	2	
CO2	3	1	1		1	1		1	1	2		1	2	2	
CO3	3	1	1		1	1		1	1	2		1	2	2	
CO4	3	1	1		1	1		1	1	2		1	2	2	
CO5	3	1	1		1	1		1	1	2		1	2	2	
Average	3	1	1		1	1		1	1	2		1	2	2	
Round off	3	1	1		1	1		1	1	2		1	2	2	

18MPC	304	ENGINEERING THERMODYNAMICS	L	T	P	C				
			3	1	0	4				
OBJEC'	TIVI	ES								
p	repar	able students to understand the basic principles of classical the them to apply basic conversion principles of mass and encystems.								
• T	o unc	lerstand second law of thermodynamics and apply it to various	s sys	tem	s.					
• T	o mal	ke them aware of various gas laws and thermodynamic relation	ns.							
	-	part knowledge on properties of pure substances and to analyse cycles.	e vai	rious	s vap	our				
• T	o exp	lore various laws of gas mixtures.								
UNIT I	IT I CONCEPT OF THERMODYNAMICS									
UNIT I	1 E	ECOND LAW OF THERMODYNAMICS AND CNTROPY thermodynamics – Kelvin-Plank and Clausius statements-C		ot c	vcle	9+3 – hea				
engines –	refrig	gerators – heat pumps- efficiency and COP – entropy – princibility- reversibility and irreversibility – applications.								
UNIT II		DEAL AND REAL GASES, THERMODYNAMIC	Z			9+3				
reduced p Maxwell r	roper elatio coef	eal gas- ideal and real gas comparison- equations of state for ideal gas- ideal and real gas comparison- equations of state for ideal gas- compressibility factor— generalised compressibility class, Tds equations, difference and ratio of heat capacities, energicient, Clausius Clapeyron equation, phase change	hart rgy e	anc equa	l its tion,	use				
UNIT I	V	PROPERTIES OF STEAM AND VAPOUR POWE	ER			9+3				
-		eam – use of steam tables and Mollier chart – dryness fraction – Rankine cycle with reheating and regeneration – applicatio								

UNIT V

GAS MIXTURES

9+3

Mole and mass fraction, Dalton's and Amagat's Law. Properties of gas mixture – molar mass, gas constant, density, and change in internal energy, enthalpy, entropy and Gibbs function.

		LECTURE: 45 TUTORIAL: 15 TOTAL: 60 PERIODS								
OUT	TCOMES:	On completion of this course, students will be able to								
1.	Apply thermod	dynamic principles to real life thermodynamic problems.								
2.	Analyze the pr	rinciples of entropy generation.								
3.	Explain the ch	aracteristics of gases.								
4.	Appreciate and	d analyze the vapour power cycles.								
5.	Analyze prope	erties of gas mixture.								
TEX	T BOOKS:									
1.	Nag P.K., " En 2017.	gineering Thermodynamics", 6 th Ed., Tata McGraw - Hill, Delhi,								
2.	Yunus Cengel	, "Thermodynamics" Tata McGraw - Hill Company, 8 th Edition, 2014.								
3.	Holman J.P., "	Thermodynamics" Tata McGraw - Hill Company, 2000.								
REF	ERENCES:									
1.	Kothandarama	an C.P., "Thermal Engineering", DhanpatRai & Sons, 2013.								
2.	Arora C.P, " T	thermodynamics", Tata McGraw-Hill, New Delhi, 2007.								
3.	Rajput R.K. "Thermal Engineering" Laxmi Publications 8 th Edition. 2010.									
4.	Ballaney P.L., "Thermal Engineering", Khanna Publisher. 1996.									
5.	Mahesh. M. Rathore, " Thermal Engineering ", Tata McGraw - Hill Education Private Limited 1 st edition, 2010.									

MAPPING	MAPPING OF COs, POs AND PSOs:														
						I	POs						I	PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	1		1				1	2	1	2	3	2	
CO2	3	2	1		1				1	2	1	2	3	2	
CO3	3	2	1		1				1	2	1	2	3	2	
CO4	3	2	1		1				1	2	1	2	3	2	
CO5	3	2	1		1				1	2	1	2	3	2	
Average	3	2	1		1				1	2	1	2	3	2	
Round off	3	2	1		1				1	2	1	2	3	2	
3- Strong Cor	3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation														

18M	SMPC305 FLUID MECHANICS AND FLUID MACHINERY L T P								
				3	0	0	3		
OBJE	CTIVES	S							
•	To enab		dents to understand the basic principles of fluid mechanics an	d bas	sic flu	ıid			
•	To unde	rstanc	l and analyse fluid kinematics and dynamic problems.						
•	To get k analysis		edge on flow through pipes and to know the importance of dis	mens	ional				
•	To cond	uct th	e performance study and selection of pumps for different app	licati	ons				
•	To analy	/se va	rious types of hydraulic turbines.						
UNIT	IT I FLUID PROPERTIES								
- Fluid st UNIT Types of dimension	tatics - To	LUII w and	lity and bulk modulus – Pascal's Law – pressure measurement ressure and centre of pressure on submerged surfaces. D KINEMATICS AND DYNAMICS If flow lines – control volume – continuity equation in one-diagnotential and stream function -energy equation – Eulers of energy equations- flow meters.	mens	ion a	nd th	9 aree		
UNIT			V THROUGH PIPES AND DIMENSIONAL ANA	ALY	SIS		9		
boundary pipes- m	y layer th ninor los of din	ickne ses – iensio	circular conduits and circular annuli-boundary layer coress – Darcy Weisbach equation –friction factor- Moody diagflow through pipes in series and parallel- hydraulic and analysis – dimensionless parameters- application alysis.	gram. energ	con y gra	nmero adien	cial t –		
UNIT	IV P	UMF	PS				9		
- work d	one and	efficie	charge, work done and efficiencies – gear, centrifugal and rec ncies - negative slip - flow separation conditions - air vessels on - savings in work done.	-	_	_	ıps		
UNIT	VH	YDF	RAULIC TURBINE				9		
	- head,	losse	uction, working principles and design of Pelton wheel, Fr s, work done and efficiency - specific speed - operating			_			
			TOTAL: 4	5 P	ERI	ODS	5		
OUTC	OMES	: 0	n completion of this course, students will be able to						
1. Id	entify the	impo	ortance of fluids properties and fluid principles at rest.						

- 2. Explore physical behaviour of fluids system and equations under moving conditions.
- 3. Apply the concept of flow through pipes and dimensional analysis.
- 4. Conduct the performance study and selection of pumps for different applications
- 5. Conduct the performance test on different types of turbines.

TEXT BOOKS:

- 1. Rajput R. K., "A text Book of Fluid Mechanics and Machinery", S. Chand and Company, New Delhi, 2015.
- 2. RamamruthamS."Hydraulics, Fluid Mechanics and Fluid Machines", DhanpatRai Publishing House (P) Ltd, New Delhi, 2012.
- 3. Modi P. N. and Seth S. M., "Hydraulics and Fluid Mechanics including Hydraulic Machines", Standard book house, Delhi, 2004.

REFERENCES:

- 1. Streeter V.L. and Wylie E. B., "Fluid Mechanics", McGraw Hill Publishing Co. 2017.
- 2. Kumar K. L., "Engineering Fluid Mechanics", Eurasia Publishing House(p) Ltd., New Delhi, 2010..
- 3. R.K Bansal "A Textbook of Fluid Mechanics and Hydraulic Machines", Laxmi Publications (p) Ltd., 2017
- 4. Robert W.Fox, Alan T. McDonald, Philip J.Pritchard, "Fluid Mechanics and Machinery", 2011.
- 5. Graebel W.P, "Engineering Fluid Mechanics", Taylor & Francis, Indian Reprint, 2011.

MAPPING OF COs, POs AND PSOs:

						P	Os						PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	1		1				1	2	1	2	3	2	
CO2	3	2	1		1				1	2	1	2	3	2	
CO3	3	2	1		1				1	2	1	2	3	2	
CO4	3	2	1		1				1	2	1	2	3	2	
CO5	3	2	1		1				1	2	1	2	3	2	
Average	3	2	1		1				1	2	1	2	3	2	
Round off	3	2	1		1				1	2	1	2	3	2	

18MES306		BASIC ELECTRONICS ENGINEERING	L	T	P	C
			3	0	0	3
OBJECTIVI	ES:			I.		l
•	To un	nderstand the principles of different diodes.				
		udy about the methods of biasing of BJTs, and the basic applicational amplifiers	catio	ns of		
		troduce the methods of implementing Boolean expression using the pts of transducers.	ng ga	ites,	and	the
UNIT I	1	SEMICONDUCTOR DIODE				9
wave rectifier,	Bridg	Diode approximations and applications, half-wave rectifier ge rectifier, Capacitor filter circuit, Zener diode-Voltage re CD, Photo Transistor, Opto Coupler.				
UNIT II		BIPOLAR JUNCTION TRANSISTORS				9
-	oint, I	mon Base, Common Emitter and Common Collector Characterized Bias, Collector to base bias, Voltage divider Bias, Stabil, MOSFET.				
UNIT III		INTRODUCTION TO OPERATIONAL AMPLI	FIE	RS		9
follower, additi	on, su	erting and non-inverting OPAMP circuits, OPAMP appliabtraction, Integration, differentiation, Comparators, Schmittor, Clipper and Clamper.				_
UNIT IV	,	DIGITAL ELECTRONICS				9
_		OR, NOT, NAND, NOR, Exclusive—OR and Exclusive—NOR. implementations, NAND implementations. Half Adder, Full a	_		ic	
UNIT V	,	TRANSDUCERS				9
Thermistor. Li	near	e Electrical Transducers, Resistive Transducers, Resistance Variable Differential Transformer (LVDT). Active Electrocer, Photoelectric Transducer.				
	ansu					
	Tansu	TOTAL: 45 PER	IOI	DS_		

1.	App	Apply the concept of diode in rectifiers, filter circuits.													
2.	Und	erstan	d the o	conce	ot of I	3JT in	ampl	ifiers.							
3.	Desi	gn sin	nple e	lectro	nic cii	cuits	using	OPAN	MPS.						
4.	Desi	gn and	d impl	emen	t simp	le log	ic fur	ction	using	basic	unive	rsal ga	ites.		
5.	Und	erstan	d the l	oasic _l	orinci	ples of	f diffe	erent ty	pes o	f tran	sduce	rs.			
TEXT BOO	OKS:														
1.		id A.B		Electro	onic D	Device	s and	Circui	its", C	Oxford	Univ	ersity	Press,	5 th	
2.		R.S.Sedha, "A Textbook of Electronic Devices and Circuits", 2 nd Edition, S. Chand Publishing, 2008.													
REFEREN	CES:	ES:													
1.		Robert L. Boylestad and Louis Nashelsky, "Electronic Devices and Circuit Theory", Oth Edition, Pearson Education, 2007.													
2.		D.P.Kothari, I.J. Nagrath, "Basic Electronics", McGraw Hill Education (India) Private Limited, 2014.													
3.	D.Sch	illing	and C	.Belo	ve, " I	Electo	nic C	ircuits	", 3 rd	Editie	on,Mc	Graw	Hill, 1	989.	
4.	Anwa	r A. K	han ai	nd Ka	nchan	K. D	ey, "A	4 First	Cour	se on	Electi	onics	", PH.	I, 200	6.
5.	Singh, Circu							tronic		Devic	res		and	Integ	grated
MAPPING	GOF	COs,	POs	ANI) PS	Os:									
						P	Os							PSO	S
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2	2								3	3		1
CO2	3	1		1								2	2		1
CO3	3	2	3	2								2	2		2
CO4	3	2	3	2								2	2		2
CO5	3	1		1								2	2		1
Average	3	1.6	1.6	1.6								2.2	2.2		1.4
Round off 3- Strong Co	3	2	2	2								2	2		1

18MPC307	FLUID MECHANICS AND FLUID MACHINERY LABORATORY	L	Т	P	C
		0	0	3	1.5

OBJECTIVES

- To help the students in finding the various flow properties of fluids.
- To estimate the flow measurements using flow measuring equipment's.
- To conduct performance tests on pumps and turbines and draw the performance curves.

LIST OF EXPERIMENTS:

- 1. Determination of Darcy's friction factor.
- 2. Determination of the Coefficient of discharge of given Orifice meter.
- 3. Determination of the Coefficient of discharge of given Venturi meter.
- 4. Calculation of the rate of flow using Rota meter.
- 5. Performance study on Gear oil Pump.
- 6. Conducting experiments and drawing the characteristic curves of centrifugal pump/submersible pump.
- 7. Conducting experiments and drawing the characteristic curves of reciprocating pump.
- 8. Conducting experiments and drawing the characteristic curves of Pelton wheel.
- 9. Conducting experiments and drawing the characteristics curves of Francis turbine.
- 10. Conducting experiments and drawing the characteristic curves of Kaplan turbine.

			TOTAL:45 PERIODS						
OUT	COMES:	On completion of this course, students will	be able to						
1.	1. Find the flow properties of fluids.								
2.	Estimate the	flow measurements using flow measuring equ	uipment's.						
3. Conduct performance tests on pumps and turbines and draw the performance curves.									

MAPPING OF COs, POs AND PSOs:

		POs													PSOs				
	1	2	3	12	1	2	3												
CO1	3	2	1					2	1	2	2	2	3	3	1				
CO2	3	2	1					2	1	2	2	2	3	3	1				
CO3	3	2	1					2	1	2	2	2	3	3	1				
Average	3	2	1					2	1	2	2	2	3	3	1				
Round off	3	2	1					2	1	2	2	2	3	3	1				

18MPC308	MACHINE DRAWING	L	T	P	C
		0	0	4	2

OBJECTIVES

- To help the students to get knowledge on Limits, Fits, Tolerances, Geometric Dimensioning and Tolerancing.
- To develop sectional views of fasteners, joints and couplings and various machine elements
- To draw assembly of machine parts using Computer Aided Drawing software's.

LIST OF EXERCISES:

- 1. Introduction to "Limits, Fits, Tolerances, Geometric Dimensioning and Tolerancing" and corresponding symbols.
- 2. Preparation of drawing for keys, keyways and cotter joints.
- 3. Preparation of drawing for knuckle joints and threaded fasteners.
- 4. Preparation of drawing foot step ball bearing, foot step journal bearing.
- 5. Preparation of assembly drawing for screw jack.
- 6. Preparation of drawing of stop valve –safety valve.
- 7. Preparation of drawing of tailstock tool head of shaper machine vice –connecting rod.
- 8. Preparation of drawing for flange and universal coupling (using any CAD software).
- 9. Preparation of part and assembly drawing for Plummer block (using any CAD software).

			TOTAL:60 PERIODS
OUT	COMES:	On completion of this course, students will	be able to
1.	Understand L	imits, Fits, Tolerances, Geometric Dimensio	ning and Tolerancing.
2.	Develop secti	onal views of fasteners, joints and couplings	and various machine elements
3.	Draw assemb	ly of machine parts using Computer Aided D	Orawing software's.

MAPPING OF COs, POs AND PSOs:

				PSOs											
	1	2 3 4 5 6 7 8 9 10 11 1												2	3
CO1	2	2	2	1				2	1		1	1	2	2	1
CO2	2	2	2	1		2		2	1		1	1	2	2	1
CO3	2	2	2	1		2		2	1		1	1	2	2	1
Average	2	2	2	1		1.3		2	1		1	1	2	2	1
Round off	2	2	2	1		1		2	1		1	1	2	2	1

18MPC	8MPC401 THERMALENGINEERING L T P										C							
															3	0	0	3
OBJECT	TIVES																	
•	To enab	le th	the st	udents	s un	der	stanc	d dif	ffere	nt th	erm	odynar	nic cyc	eles.				
•	To unde	rsta	and th	ne prii	ncip	oles	and	wor	king	g of I	C er	ngines.						
•	To intro	duc	ce stu	dents	to t	he v	work	king	of s	team	noz	zzles ar	nd turb	ines.				
•	To desig	n a	and a	nalyse	e dif	ffere	ent ty	ypes	of a	air co	mpi	ressors	with a	nd w	ithou	ıt cle	aranc	e
•	To analy	/se \	vario	us ref	frige	erati	ion a	and a	air-c	ondi	tion	ing sys	tems.					
UNIT	TH	Œ	RM	ODY	ΝA	M	IIC (CY	CL	ES								9
Air standar effective pr													ındard	effici	ency	/ — m	ean	
UNIT I	I I.C	. E	ENG	INE	S													9
I.C engine and lubrica rating of performance	ation syst fuels – ce charac	tem coı teri	n for ombus ristics	spark stion, of I.C	kne kne C. er	nitic lock ngir	on an king nes.	nd co	omp l de	etona	on i	ignition , scave	n engir	nes -C	Cetai	ne an	d Oc	tane
UNIT I	II ST	EA	AM l	NOZ	ZL	ES	SAN	ND	TU	RB	NE	ES						9
Flow throu flow. Impu	-		_									-				-		
UNIT I	V AI	R (CON	IPR	ES	SO	R											9
Reciprocat and perfect											_			ntern	nedia	ite pr	essur	re
UNIT V	RE	FR	RIG	ERA	TI	ON	I AN	ND	AII	R C	ON	DITI	ONIN	IG				9
Air refrige heating. V system - I mixtures b heating and	apour ab Psychom y using o	sor etri cha	rption ic pr art an	n syst operti d exp	tem. ies, oress	Pr psy sion	rincip ycho ns— P	ples omet Psyc	of ric hom	air c chart etric	ond s, I pro	itioning Propert ocess –	g – ty _l y calc adiaba	pes o ulatic atic s	f air ons atur	r con of ai ation	ditio r vaj , sens	ning pour sible
												To	OTAI	. : 45	5 P	ERI	ODS	S
OUTC	OMES	:	On	comp	pleti	ion	of th	nis c	ours	se, sti	ıder	nts will	be abl	e to				
	Explain thand T-S d			_			rmoc	dyna	amic	cyc	es i	ncludir	ig actu	al cyc	eles	and d	lraw l	P-V
2. U	J nderst ar	nd tl	the pi	rincip	les a	and	worl	king	gof	Inter	nal (Combu	stion e	ngine	es.			
1									_			_	_		_	· <u>-</u>	_	
3. A	Analyse t	he f	funct	ioning	g of	ste	am n	10ZZ	le a	nd tu	rbin	es.						
	Analyse to Design an												n and v	vithou	ıt cl	earan	ce.	

	air conditionii	ng system.
TEXT	BOOKS:	
1.	Rajput R.K. "	Thermal Engineering" Laxmi Publications (P) Ltd., 2017.
2.	Domkundwar New Delhi, 20	randKothandaraman C.P. "Thermal Engineering" Khanna Publishers, 010.
3.	Mahesh M Ra	athore, "Thermal Engineering" TataMcGraw Hill, New Delhi, 2010.
REFE	RENCES:	
1.	Rudramoorth	y R. "Thermal Engineering" Tata McGraw-Hill, New Delhi,2017.
2.	Sarkar B. K."	Thermal Engineering" Tata McGraw-Hill, New Delhi, 2017.
3.	Ganesa, V. "In	ternal Combustion Engines" Tata McGraw-Hill, New Delhi, 2017.
4.	Ramalingam 2009.	K.K. "Thermal Engineering" SCITECH Publications (India) Pvt. Ltd.,
5.	Arora C.P. "I	Refrigeration and Air Conditioning"Tata McGraw-Hill Publishers, 2017.

MAPPING OF COs, POs AND PSOs:

				PSOs											
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	2							1		2		3		
CO2	1				2	2			1		2		3		
CO3	2	2							1		1		2		
CO4	2	2	1						1		1		2		
CO5	3	3	2		1	2	2		1		1		3		
Average	2	1.8	0.6		0.6	0.8			1		1.8		2.6		
Round off	2	2	1		1	1			1		2		9		

³⁻ Strong Correlation; 2 - Medium Correlation; 1-Low Correlation

18MI	BS402	2 H	UMAN VALUES AND PROFESSIONAL ETHICS	L	Т	P	C
				3	0	0	3
OBJE	CTIV	ES:					
•			the capacity of making value judgments in real life situati lues encountered in everyday life.	ons an	d to e	overo	come
UNI	ΤI	HUMA	N VALUES				9
Others	– Livin	g Peacefu	cs – Integrity – Work Ethic – Service Learning – Civic Vi Illy – caring – Sharing – Honesty – Courage – Valuing Tir y – Self-Confidence – Character – Spirituality				
UNI	ΓII	ENGIN	EERING ETHICS				9
autonon	ny - Ko	hlberg's t	Ethics' - variety of moral issued - types of inquiry - motheory - Gilligan's theory - consensus and controversy $-$ North action - Self-interest - customs and religion - uses of ethics of the second control of the secon	Iodels	of P	rofes	
UNIT I	II	ENGIN	IEERING AS SOCIAL EXPERIMENTATION	N			9
			ntation - engineers as responsible experimenters - codes o lenger case study	f ethic	s - a	balar	nced
UNIT I	\mathbf{V}	SAFET	TY, RESPONSIBILITIES AND RIGHTS				9
island at	nd cher lentialit	nobyl cas y - confl	nent of safety and risk - risk benefit analysis and reducin e studies. Collegiality and loyalty - respect for authority - icts of interest - occupational crime - professional right hts (IPR) - discrimination.	collec	ctive	barg	aining
UNIT V	V	GLOB.	AL ISSUES				9
engineer leadersh	rs as in the same of M	nanagers- ple code	ons - Environmental ethics - computer ethics - weaper consulting engineers-engineers as expert witnesses and of Ethics like ASME, ASCE, IEEE, Institution of Engin Management, Institution of electronics and telecommunication	d adv eers (I	isors ndia)	-m , Inc	oral lian
			TOTAL :	45 P	ER	IOI	S
OUTO	COMI	ES: On	completion of this course, students will be able to				
1.	develo	p an ethic	cal behavior under all situations				
2.	estima	te the imp	oact of self and organization's actions on the stakeholders	and so	ociety	<i>)</i> .	
TEX	Т ВО	OKS:					
1.	Mike I 1996.	Martin an	d Roland Schinzinger, "Ethics in Engineering", McGraw	-Hill, I	New_	York	
2.		darajan N New Deli	A, Natarajan S, Senthil Kumar V. S, "Engineering Ethics " hi, 2004.	", Pren	tice .	Hall	of

3.	Tripathi A N, "Human values", New Age international Pvt. Ltd., New Delhi, 2002
REF	ERENCES:
1.	Charles D. Fleddermann, "Engineering Ethics", Pearson Education / Prentice Hall, New Jersey, 2004 4.
2.	2. Charles E Harris, Michael S. Protchard and Michael J Rabins, "Engineering Ethics – Concepts and Cases", Wadsworth Thompson Learning, United States, 2000.
3.	3. John R Boatright, "Ethics and the Conduct of Business", Pearson Education, New Delhi, 2003.
4.	Edmund G Seebauer and Robert L Barry, "Fundamentals of Ethics for Scientists and Engineers", Oxford University Press, Oxford, 2001.

MAPPING OF COs, POs AND PSOs:

		POs													PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3			
CO1	2				1								1					
CO2	2				1								1					
CO3	2				1								1					
CO4	2				1								1					
CO5	2				1								1					
Average	2				1								1					
Round off	2				1								1					

³⁻ Strong Correlation; 2 - Medium Correlation; 1-Low Correlation

18MPC40	STRENGTH OF MATERIALS	L	T	P	C
		3	1	0	4
OBJECT	IVES				
•	To make the students to understand the concepts of stress and strai	n.			
•	To draw shear force and bending moment diagrams for different ty	pes o	of bea	ams.	
•	To apply theory of simple bending in beams and to understand the principle stress.	conc	ept c	of	
•	To evaluate slope and deflection different types of beams and to ur theories of long columns.	nders	tand	vario	ous
•	To evaluate stresses induced in the shaft due to torsion.				

Stress and strain at a point-tension, compression, shear stresses - Hooke's law - compound bars - lateral strain - Poisson's ratio -volumetric strain - bulk modulus - relationship among elastic constants - stress strain diagrams for mild steel, cast iron-ultimate stress - yield stress-factor of safety - thermal stresses - thin cylinders - strain energy due to axial force - resilience- stress due to gradual load, suddenly applied load and impact load.

UNIT II SHEAR FORCE AND BENDING MOMENT

STRESS AND STRAIN

UNIT I

Beams – types of beams - types of loads, supports - shear force – bending moment – shear forces and bending moment diagrams for cantilever, simply supported and over hanging beams with concentrated , uniformly distributed and uniformly varying load-relationship between rate of loading, shear force, bending moment- point of contra flexure.

UNIT III THEORY OF BENDING AND COMPLEX STRESSES 9+3

Theory of bending-bending equation-section modulus-stress distribution at a cross section due to bending moment and shear force for cantilever, simply supported beams with point, UDL loads (rectangular, circular, I & T sections only) -combined direct and bending stresses, kernel of section (rectangular, circular sections only). 2D state of stress – 2D normal and shear stresses on any plane-principal stresses and principal planes-principal strains and direction-Mohr's circle of stress.

UNIT IV DEFLECTION OF BEAMS AND THEORY OF LONG COLUMNS 9+3

Determinations of deflection curve – relation between slope, deflection and radius of curvature – slope and deflection of beam at any section by double integration, Moment Area and Macaulay's method - concept of conjugate beam method (theory only)- Euler's theory of long columns-expression of crippling load for various end conditions-effective length-slenderness ratio-limitations of Euler equation - Rankine formula for columns.

UNIT V THEORY OF TORSION 9+3

Torsion of shafts - torsion equation - polar modulus- stresses in solid and hollow circular shafts - torsional rigidity - power transmitted by the shaft - importance of angle of twist - strain energy due to torsion - modulus of rupture -torsional resilience - combined bending and torsion- stresses in helical springs - deflection of helical spring.

9+3

9+3

LECTURE: 45 TUTORIAL: 15 TOTAL: 60 PERIODS On completion of this course, students will be able to **OUTCOMES:** Determine the stress, strain and modulus for different materials. 2. Draw shear force and bending moment diagrams for different beams. 3. Calculate the complex stresses in beams with different loading conditions. 4. Evaluate the deflection behaviour of beams and slender columns. 5. Apply the concepts of torsion in shafts and springs. **TEXT BOOKS:** Bansal R.K., "Strength of Materials", Laxmi Publications (P) Ltd., 2018 1. Ramamrutham S and Narayan R, "Strength of Materials", Dhanpat Rai and Sons, New Delhi, 2. 2000. **REFERENCES:** Hibbeler R.C., "Mechanics of Materials", Pearson Education, Low Price Edition, 2007 1. Jindal U C, "Textbook on Strength of Materials", Asian Books Pvt. Ltd., 2. Learning India, 2013. 3. EgorP.Popov "Engineering Mechanics of Solids" Prentice Hall of India, New Delhi, 2001 4. Subramanian R., "Strength of Materials", Oxford University Press, Oxford Higher Education Series. Sadhu Singh, "Strength of Materials", Khanna Publishers, New Delhi, 2016 5. **MAPPING OF COS, POS AND PSOS:**

						P	Os						PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	3	3	1										3		1	
CO2	3	2	2										3		1	
CO3	3		3		2								3	3	1	
CO4	3		3		1								3	3	1	
CO5	3		2		2								3	3	1	
Average	3	1	2.2		1								3	1.8	1	
Round off	3	1	2		1								3	2	1	

18MPC4	04]	ENGINE		G MAT ALLUI		CRIALS AND L T P							
								3	0	0	3			
OBJECT	IVE	S												
	prov agram		epth know	ledge to s	students	about coi	stitution o	f alloys a	nd pl	nase				
• To	mak	e them	aware of v	arious hea	at treatm	ent and s	urface trea	tment pro	cesse	es				
• To	impa	art know	vledge on f	errous an	nd non-fe	errous me	tals							
• To	acqu	ire kno	wledge on	welding a	and casti	ng metal	urgy							
• To	unde	erstand t	the smart n	naterials										
UNIT I	(CONS	TITUTIO	ON OF	ALLO	YS ANI) PHASI	E DIAG	RA	MS	9			
Constitution diagrams, i	somo	orphous,												
carbide equi	ilibrii	um diag	ram.											
UNIT II Definition - normalising transformati	full full har	HEAT I anneal rdening diagram	TREAT ling, proce and temps s – cool:	ss anneal ering of ng curve	lling, stre steels – es supe	ess relief - austem rimposed	recrystall pering, ma	isation - artemperi diagram-	spheng -	isotl T, C	herma CCR			
	full full f, har ion or y, Jo ng-fl	HEAT I anneal diagram ominy came and	TREAT ling, proce and temp s – cooling and quence	ss anneal ering of ng curve h test - hardenin	lling, stre	ess relief – austem rimposed ardening	recrystall pering, ma on I.T carburisi	isation - artemperi diagram-	spheng -	isotl T, C	zing - herma CCR			
UNIT II Definition - normalising transformati hardenabilit carbonitridi	full full for full full full full full full full ful	HEAT I anneal rdening diagram ominy of ame and FERRO els – all steel - heat re	ting, proce and tempes — coole end quence dinduction OUS AN oy steels — stainless a esistant ste	ss anneal ering of ng curve h test - hardenin D NONe effect of nd tool sels and d	lling, streels - ves super case hang. I-FERR f alloying steels - gdie steels	ess relief - austem rimposed ardening. ROUS M g element gray, whe s. Copper	recrystall pering, ma on I.T carburisi IETALS Is (Mn, Si, te, mallea, aluminium)	isation - artemperi diagram- ng, nitrio Cr, Mo, ble, sphe n, magne	spheng - TT ding, V, l	isotl T, C cyan Ni, T l gra l, tita	zing - herma CCR niding 9 i& W phite nium			
UNIT II Definition - normalising transformati hardenabilit carbonitridi UNIT II Plain carbon on propertic alloy cast in important a	full full full full full full full full	HEAT I anneal rdening diagram ominy of ame and FERRO els – all steel - heat ro - their	ting, proce and tempes — coole end quence dinduction OUS AN oy steels — stainless a esistant ste	ss anneal ering of ng curve h test - hardening D NONe effect of nd tool sels and dion, prop	lling, streels - ves super-case hang. I-FERR f alloying steels - gdie steels perties and streels - general steels - general	ess relief austem erimposed ardening ROUS M g elemen gray, wh s. Copper nd applic	recrystall pering, ma on I.T carburisi IETALS s (Mn, Si, te, mallea aluminium ations - n	isation - artemperi diagram- ng, nitrio Cr, Mo, ble, sphe n, magne naterial s	spheng - TT ding, V, l	isotl T, C cyan Ni, T l gra l, tita	zing - herma CCR niding 9 i& W phite nium			
UNIT II Definition - normalising transformati hardenabilit carbonitridi UNIT II Plain carbon on propertic alloy cast in important a standards.	full-full-fing a full-fing a	HEAT I anneal rdening diagram ominy of ame and FERRO els – all steel – heat ro - their CASTI pure m ot tears and therr	ting, proce and temps — coole end quence dinduction oy steels — stainless a esistant steel composite time. The composite time is and a — heat trainal effects	ss anneal ering of ng curve h test - hardening D NONe effect of nd tool sels and dion, proposition, propositi	lling, streels - ves super-case hang. I-FERR f alloying steels - gdie steels perties and melting - nd structu	ess relief austem rimposed ardening. ROUS M g element gray, wh s. Copper nd applic METAI super h ural chan	recrystall pering, ma on I.T carburisi IETALS IS (Mn, Si, te, mallead, aluminium ations - no ations - no ations - flege. Welda	isation - artemperi diagram- ng, nitric Cr, Mo, ble, sphe n, magne naterial s	spheng - TTling, V, linging a silver of the structure of	Ni, T l gra icatio	zing - herma CCR niding 9 i& W phite nium on and macro ibution			
UNIT II Definition - normalising transformati hardenabilit carbonitridi UNIT II Plain carbon on propertic alloy cast in important a standards. UNIT IV Solidificatio segregation during weld	full-full-fing agef treat	HEAT I anneal rdening diagram ominy of ame and FERRO els – all steel – heat ro - heat ro - their CASTI pure m ot tears and there atment of	ting, proce and temps — coole end quence dinduction oy steels — stainless a esistant steel composite time. The composite time is and a — heat trainal effects	ss anneal ering of ng curve h test - hardening D NONe effect of nd tool sels and dion, proposition by WELI alloys – nunsfer and on parent	lling, streels - ves super-case hang. I-FERR f alloying steels - gdie steels perties and melting - nd structumt metals	ess relief austem erimposed ardening ROUS M g element gray, whis Copper nd applic METAI super h ural chan	recrystall pering, ma on I.T carburisi IETALS IS (Mn, Si, te, mallea aluminium ations - necessarian - necessarian - flege. Weldar factors af	isation - artemperi diagram- ng, nitric Cr, Mo, ble, sphe m, magne naterial s uxing - r bility -	spheng - TTling, V, linging a silver of the structure of	Ni, T l gra icatio	zing - herma CCR niding 9 i& W phite nium on and macro ibution			
UNIT II Definition - normalising transformati hardenabilit carbonitridi UNIT II Plain carbon on propertic alloy cast in important a standards. UNIT IV Solidification segregation during weld - stress relice	- full - full - full - full - fy, Jo ng-fl - n stee - so of - ho ling a - for to so iezoe	HEAT I anneal rdening diagram ominy of ame and FERRO els – all steel – heat re - their CASTI pure m ot tears and there atment of INTRO mart ma electric in	ing, proce and temps — coole end quence dinduction OUS AN oy steels — stainless a esistant stee composite ING ANI etals and a — heat tramal effects of welds ODUCTION TO THE END OF THE EN	ss anneal ering of ng curve h test - hardening D NONe effect of nd tool sels and dion, proposed D WELI alloys - mansfer and on parent on parent on parent shape me	ling, streels - ves super-case hang. I-FERR f alloying steels - gdie steels perties and melting - nd structumt metals OSMAR ions - sm	ess relief austem rimposed ardening. ROUS M g element gray, wh s. Copper nd applic METAI super h ural chan a HAZ nart senso	recrystall pering, ma on I.T carburisi IETALS IS (Mn, Si, te, mallea aluminium ations - number of leating - flage. Weldar factors af IERIAL and actual act	isation - artemperi diagram- ng, nitric Cr, Mo, ble, sphe n, magne naterial s uxing - r bility - fecting H	spheng - TT ling, V, liroida esium pecif	Ni, T l gradication and distriction	zing - herma CCR niding 9 i& W phite nium on and dening generated as a second content of the c			
UNIT II Definition - normalising transformati hardenabilit carbonitridi UNIT II Plain carbon on propertic alloy cast in important a standards. UNIT IV Solidification segregation during weld - stress relice UNIT V Introduction effects of p	- full - full - full - full - fy, Jo ng-fl - n stee - so of - ho ling a - for to so iezoe	HEAT I anneal rdening diagram ominy of ame and FERRO els – all steel – heat re - their CASTI pure m ot tears and there atment of INTRO mart ma electric in	ing, proce and temps — coole end quence dinduction OUS AN oy steels — stainless a esistant stee composite ING ANI etals and a — heat tramal effects of welds ODUCTION TO THE END OF THE EN	ss anneal ering of ng curve h test - hardening D NONe effect of nd tool sels and dion, proposed D WELI alloys - mansfer and on parent on parent on parent shape me	ling, streels - ves super-case hang. I-FERR f alloying steels - gdie steels perties and melting - nd structumt metals OSMAR ions - sm	ess relief austem rimposed ardening. ROUS M g element gray, wh s. Copper nd applic METAI super h ural chan a HAZ nart senso	recrystall pering, ma on I.T carburisi IETALS IS (Mn, Si, te, mallear, aluminium ations - number of the control of the contr	isation - artemperi diagram- ng, nitric Cr, Mo, ble, sphe n, magne naterial s uxing - r bility - fecting H	spheng - TT ling, V, liroida sium pecif	Ni, T l grad, tital cation and distri- and f	zing - herma CCR niding 9 i& W phite nium on and dening 9 reverse ds and			

- 1. Predict the alloy components and composition variation with respect to temperature changes.
- 2. Select suitable materials and heat treatment methods for various industrial applications.
- 3. Explain the ferrous and nonferrous materials and their application.
- 4. Apply the knowledge of casting and welding metallurgy to industrial applications
- 5. Gain the knowledge about smart materials and applications

TEXT BOOKS:

- 1. Sydney H.Avner, "Introduction to Physical Metallurgy", Tata McGraw Hill Book Company, 1994.
- 2. V. Raghavan "Materials Science And Engineering", Fifth Edition, PHI learning 2011.
- 3. Inderjit Chopra, "Smart Structures Theory" Cambridge University press 2014.

REFERENCES:

- 1. | O.P.Khanna, "Material Science And Metallurgy", DhanpatRai Publication, 2011
- 2. William D Callister "Material Science and Engineering", Wiley India pvt Ltd 2007.
- 3. Kenneth G.Budinski and Michael K.Budinski "Engineering Materials" Prentice-Hall of India Private Limited, 4th Indian Reprint, 2002.
- 4. Lakhtin Yu., "Engineering Physical Metallurgy and Heat Treatment", Mir Publisher, 1985.
- 5. Higgins R.A., "Engineering Metallurgy", 5th edition, Elbs, 1983.
- 6. Sindo Kou "Welding Metallurgy", Wiley India pvt Ltd 2003.

MAPPING OF COs, POs AND PSOs:

		POs												PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3		
CO1	3	2		3									3	2			
CO2	3	2	2	3	2						2		3	2			
CO3	3	2		2									3	2			
CO4	3	3	3	3	2								3	2			
CO5	3	2		1	2						2		3	2			
Average	3.0	2.2	5.0	2.4	1.2						0.8		3.0	2.0			
Round off	3	2	1	2	1						1		3	2			

	PC405		KINEMATICS OF MACHINES I	_]	\lceil	P	C
			3	3 1	l	0	4
OBJE	CTIVI	ES					
•	To mak	te the s	tudents to understand the basics of mechanisms.				
•	To drav	v the v	elocity and acceleration diagram for simple mechanisms.				
•	To cons	struct c	am profile for given follower motion.				
•	To und	erstand	basics of gear and to develop gear trains for required applicat	tion.			
•	To get l	knowle	dge to select appropriate type of friction drives for a specific	appli	ca	tion.	
UNI	IT I	BASI	ICS OF MECHANISMS			9)+3
	tion of s	ome co	ank chains – limit positions – mechanical advantage – transrommon mechanisms – quick return mechanisms- solving of size EMATIC ANALYSIS			oble	
	ues- inst		y and acceleration analysis on simple mechanisms – graphical ous center of velocity – Coriolis component – Klein's constru				
UNIT	ГШ	KINI	EMATICS OF CAM MECHANISMS			9) +3
UNIT Classifi uniform motions	ication on velocits layou	of cam ty, par ut of pl	EMATICS OF CAM MECHANISMS s and followers – terminology and definitions – displace abolic, simple harmonic and cycloidal motions – derivativate cam profiles – specified contour cams – circular arc and dercutting – sizing of cams.	es c	of :	liagra follo	am
UNIT Classifi uniform motions	ication on velocities – layoure angle a	of cam ty, par ut of pl and und	s and followers – terminology and definitions – displace abolic, simple harmonic and cycloidal motions – derivativate cam profiles – specified contour cams – circular arc and	es c	of :	liagra follo t can	ams we
UNITE Classification of the control	r IV f toothed f toothed f cation of toothed f toothed f and toothed f toothed f gata f and toothed f toothed f and toothed f toothe	of cam ty, par ut of pl and und GEA d gear r tooth	s and followers – terminology and definitions – displace abolic, simple harmonic and cycloidal motions – derivativate cam profiles – specified contour cams – circular arc and dercutting – sizing of cams.	res contang	of :	follo t can	yens - 0+3
UNITE Classification of the control	re angle a re toother ons—gea ains — Sp	of cam ty, par ut of pl and unc GEA d gear r tooth peed ra	s and followers – terminology and definitions – displace abolic, simple harmonic and cycloidal motions – derivativate cam profiles – specified contour cams – circular arc and dercutting – sizing of cams. RS AND GEAR TRAINS Ing – involutes and cycloidal tooth profiles –spur gear teaction – contact ratio – interference and undercut. Helical	res contang	of :	liagrafollo can	ams wes ns -
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Classifi uniform motions pressure UNIT Law of definition Gear tra UNIT Belt and effect of bearing	r IV f toother ons—gearains — Sp T V d rope drope drope frictions—frictio	of came ty, par ut of pland unce GEA d gear r tooth beed ra FRIC rive – corugal for	s and followers – terminology and definitions – displace abolic, simple harmonic and cycloidal motions – derivative ate cam profiles – specified contour cams – circular arc and dercutting – sizing of cams. RS AND GEAR TRAINS Ing – involutes and cycloidal tooth profiles –spur gear teaction – contact ratio – interference and undercut. Helical tio, train value – parallel axis gear trains – epicyclic gear Train CTION DRIVES Open and cross belt drive – belt materials – creep and slip - ratorce – condition for maximum power – friction in journal beauches – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches-brakes – single plate – multi plate – cone clutches – single plate – multi plate – cone clutches – single plate – multi plate – cone clutches – single plate – multi plate – cone clutches – single plate – multi plate – cone clutches – single plate – multi plate – cone clutches – single plate – multi plate – cone clutches – single plate – multi plate – cone clutches – single plate – multi plate – cone clutches – single plate – multi plate – cone clutches – single pl	ermind, being io of ring shoe	of tendological design of the color of the c	sogy your grake	ams we ns - 1)+3 ancorm 1)+3 ivo anco anco
UNITAL Classification of the control	r IV f toother ons—gearains — Sp T V d rope drope drope frictions—frictio	of cam ty, par ut of pl and und GEA d gear r tooth beed ra FRIC rive – C ugal fo on clut ing bra	s and followers – terminology and definitions – displace abolic, simple harmonic and cycloidal motions – derivative ate cam profiles – specified contour cams – circular arc and dercutting – sizing of cams. RS AND GEAR TRAINS Ing – involutes and cycloidal tooth profiles –spur gear te action – contact ratio – interference and undercut. Helical tio, train value – parallel axis gear trains – epicyclic gear Train CTION DRIVES Open and cross belt drive – belt materials – creep and slip - ratorce – condition for maximum power – friction in journal beauches – single plate – multi plate – cone clutches-brakes – ske only.	ermind, being io of ring shoe	of tendological design of the color of the c	sogy your grake	am we ns -
UNITE Classification of the control	r IV f toother ons—gearains — Sp T V d rope drope drop	of cam ty, par ut of pl and und GEA d gear r tooth beed ra FRIC rive – C ugal fo on clut ing bra	s and followers – terminology and definitions – displace abolic, simple harmonic and cycloidal motions – derivative ate cam profiles – specified contour cams – circular arc and dercutting – sizing of cams. RS AND GEAR TRAINS Ing – involutes and cycloidal tooth profiles –spur gear te action – contact ratio – interference and undercut. Helical tio, train value – parallel axis gear trains – epicyclic gear Train CTION DRIVES Open and cross belt drive – belt materials – creep and slip - ratorce – condition for maximum power – friction in journal bear ches – single plate – multi plate – cone clutches-brakes – ske only. LECTURE: 45 TUTORIAL: 15 TOTAL:	ermind, being io of ring shoe	of tendological design of the color of the c	sogy your grake	am we ns -
UNITE Classification of the control	r IV f toother ons—gearains — Sp T V d rope drof centrifig - friction dexpand	of cam ty, par ut of pl and und GEA d gear r tooth beed ra FRIC rive – C ugal for on clut ing bra S: n simpl	s and followers – terminology and definitions – displaced abolic, simple harmonic and cycloidal motions – derivative atte cam profiles – specified contour cams – circular arc and dercutting – sizing of cams. RS AND GEAR TRAINS Ing – involutes and cycloidal tooth profiles –spur gear teaction – contact ratio – interference and undercut. Helical tio, train value – parallel axis gear trains – epicyclic gear Train CTION DRIVES Open and cross belt drive – belt materials – creep and slip - ratorce – condition for maximum power – friction in journal beauthes – single plate – multi plate – cone clutches-brakes – ske only. LECTURE: 45 TUTORIAL: 15 TOTAL: On completion of this course, students will be able to	ermind, being io of ring shoe	of tendological design of the color of the c	sogy your grake	amawe ns - 1)+3 and orm 1)+3 ivo and

4.

Develop gear trains for required application.

5.	Select appropr	riate type of friction drives for a specific application.
TEX	Γ BOOKS:	
1.	Rattan S. S, "T	Theory of Machines" , Tata McGraw -Hill Publishers, New Delhi, 2014.
2.	Thomas Bevar	n, "Theory of Machines", Pearson Education Limited, 2010
3.	,	Gordan R Penncok& Joseph E Shigley, "Theory of Machines and , Mcgraw Hill Inc,2010.
REFE	RENCES:	
1.	V.P.Singh, "T	heory of Machines'', Dhanapatrai and Sons, 2017
2.	George H.Mar	ritn, "Kinematics and Dynamics of Machines", Waveland PrInc, 2002.
3.	R L Norton, "I	Kinematics and Dynamics of Machinery", McGraw-Hill, 2017.
4.	C. E. Wilson, 1 2014.	P. Sadler, " Kinematics and Dynamics of Machinery" , 3 rd ed., Pearson,

MAPPING OF COs, POs AND PSOs:

5.

		POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	3		2		1								2			
CO2	2	2	2		1								2	2		
CO3	3		2										2			
CO4	2	2			2								2	2		
CO5	3	1	2		2								2	1		
Average	1.6	1	1.8		1.2								2	1		
Round off	8	1	2		1								2	1		

Khurmi, R.S., "Theory of Machines",14th Edition, S Chand Publications, 2005

18ZMC406	ENVIRONMENTAL SCIENCE AND ENGG.	L	T	P	C
	(ECE/EEE/CSE/MECH)	1	0	0	0

OBJECTIVES:

- To finding and implementing scientific, technological, economic and political solutions to environmental problems.
- To study the interrelationship between living organism and environment.
- To study the integrated themes and biodiversity, natural resources, pollution control and waste management.

UNIT I ENVIRONMENT, ECOSYSTEMS AND BIODIVERSITY (CO-a &b)

concept of an ecosystem – structure and function of an ecosystem – producers, consumers and decomposers- types of ecosystem (forest ecosystem, grassland ecosystem, desert ecosystem, aquatic ecosystems (ponds, streams, lakes, rivers, oceans, estuaries) - energy flow in the ecosystem – ecological succession processes –types – Introduction to biodiversity definition: genetic, species and ecosystem diversity – bio-geographical classification of India – value of biodiversity: consumptive use, productive use, social, ethical, aesthetic and option values – India as a megadiversity nation – hot-spots of biodiversity – threats to biodiversity: habitat loss, poaching of wildlife, man-wildlife conflicts – endangered and endemic species of India – conservation of biodiversity: In-situ and ex-situ conservation of biodiversity. Field study of common plants, insects, birds.

Field study of simple ecosystems – pond, river, hill slopes, etc.

UNIT II ENVIRONMENTAL POLLUTION (CO-a &c)

3

7

Definition – causes, effects and control measures of: (a) Air pollution (b) Water pollution (c) Soil pollution (d) Marine pollution (e) Noise pollution (f) Thermal pollution (g) Nuclear hazards—solid waste management: causes, effects and control measures .

Field study of local polluted site – Urban / Rural / Industrial / Agricultural.

UNIT III NATURAL RESOURCES (CO-a &d)

5

Forest resources: Use and over-exploitation, deforestation – Water resources: Use and overutilization of surface and ground water— Mineral resources: Use and exploitation, environmental effects of extracting and using mineral resources – Food resources: World food problems, changes caused by agriculture and overgrazing, effects of modern agriculture, fertilizer-pesticide problems— Energy resources: renewable and non renewable energy sources, use of alternate energy sources.— Land resources- land degradation, man induced landslides, soil erosion and desertification – role of an individual in conservation of natural resources.

Field study of local area to document environmental assets – river / forest / grassland / hill

TOTAL: 15 PERIODS

COURSE OUTCOMES

Environmental Pollution or problems cannot be solved by mere laws. Public participation is an important aspect which serves the environmental Protection. One will obtain knowledge on the following after completing the course.

1. Ability to apply the knowledge of environmental science in identifying, to formulate and to

	solve the environmental problems.

- **2.** Public awareness of environmental function is at infant stage.
- **3.** Ignorance and incomplete knowledge has led to misconceptions.
- **4.** Development and improvement in std. of living has led to serious environmental disasters.

TEXT BOOKS:

- 1. Gilbert M.Masters, "Introduction to Environmental Engineering and Science", 2nd edition, Pearson Education, 2004.
- 2. Benny Joseph, "Environmental Science and Engineering", Tata McGraw-Hill, New Delhi, 2006.

REFERENCES:

- 1 Cunningham, W.P. Cooper, T.H. Gorhani, "Environmental Encyclopedia", Jaico Publ., House, Mumbai, 2001.
- 2 Rajagopalan, R, "Environmental Studies-From Crisis to Cure", Oxford University Press 2005.

MAPPING OF COs, POs AND PSOs:

	POs												PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1			1		1	3			1	2	1	2		2	1	
CO2			1		1	3			1	2	1	2		2	1	
CO3			1		1	3			1	2	1	2		2	1	
CO4			1		1	3			1	2	1	2		2	1	
Average			1		1	3			1	2	1	2		2	1	
Round off			1		1	3			1	2	1	2		2	1	

18MPC407	STRENGTH OF MATERIALS LABORATORY	L	T	P	C
		0	0	3	1.5

OBJECTIVES

- To help the students to practise the procedures for conducting various destructive testing methods like Tension, compression, impact test, etc.
- To analyse hardness of various materials like Mild Steel, Brass, Copper and Aluminium.
- To practice tension and compression test on springs.

LIST OF EXPERIMENTS

- 1. Tension Test on steel rods using Universal Testing Machine.
- 2. Bending Test on rolled steel Joist Beam.
- 3. Double shear test on mild steel rod.
- 4. Torsion Test on Mild steel rod
- 5. Tension and Compression Test on Springs
- 6. Deflection test on simply supported aluminium beam
- 7. Hardness tests on metals like Mild Steel, Brass, Copper and Aluminium
- 8. Bend Test on Steel rod
- 9. Compression Test
- 10. Impact test-Izod and Charpy

			TOTAL : 45 PERIODS					
OUI	TCOMES:	On completion of this course, students will be able to						
1.	Apply knowledge of compression, tension, shear and torsion testing procedures on materials.							
2.	Explore the deflection and bending behaviour of different types of beams.							
3.	Examine the har results.	ardness of different metals and characte	erize materials based their test					

MAPPING OF COs, POs AND PSOs:

		POs											PSOs				
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3		
CO1	3		2	3				2	2	2	2	2	3	2	2		
CO2	3		2	2				2	2	2	2	2	3	2	3		
CO3	3		2	2				2	2	2	2	2	3	2	2		
Average	3		2	2.3				2	2	2	2	2	3	2	2.3		
Round off	3		2	2				2	2	2	2	2	3	2	2		

18MPC408	THERMAL ENGINEERING LABORATORY	L	T	P	С
		0	0	3	1.5

OBJECTIVES:

- To help the students to practise selection of suitable thermal devices for the specified industrial applications.
- To evaluate the performance of I.C engines.
- To conduct experiments on boiler, turbine, compressors, refrigerator and air-conditioner.

LIST OF EXPERIMENTS:

- 1. Valve timing and port timing diagrams of single cylinder diesel and petrol engines.
- 2. Determination of flash point and fire point of various fuels / lubricants.
- 3. Performance test on 4 stroke diesel engine with mechanical loading.
- 4. Performance test on 4 stroke diesel engine with electrical loading.
- 5. Performance test on 4 stroke diesel engine with hydraulic loading.
- 6. Heat balance test on 4 stroke diesel engine.
- 7. Retardation test to find frictional power of a diesel engine.
- 8. Morse test on multi cylinder petrol engine.
- 9. Performance and energy balance test on a steam generator.
- 10. Performance and energy balance test on steam turbine.
- 11. Performance test on single and twin stage reciprocating air compressor.
- 12. Determination of COP of a vapour compression refrigeration system.
- 13. Determination of COP of air –conditioning system.
- 14. Performance test in a vapour absorption refrigeration system.

			TOTAL:45 PERIODS					
OUTCOMES:		On completion of this course, students will	be able to					
1.	1. Select the suitable thermal devices for the specified industrial applications.							
2.	Evaluate the	e performance of I.C engines.						
3.	Conduct ex	periments on boiler, turbine, compressors, re	frigerator and air-conditioner.					

MAPPING OF COs, POs AND PSOs:

	POs													PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3		
CO1	3		2	3				2	2	2	2	2	3	2	2		
CO2	3		2	2				2	2	2	2	2	3	2	3		
CO3	3		2	2				2	2	2	2	2	3	2	2		
Average	3		2	2.3				2	2	2	2	2	3	2	2.3		
Round off	3		2	2				2	2	2	2	2	3	2	2		

18MPC5	MPC501 DESIGN OF MACHINE ELEMENTS L T P										
(Use of PS	G D	esign data book is permitted)	3	1	0	4					
OBJECT	IVES										
•	Го та	ke the students to understand the Design methodology for mac	chine	elem	ents.						
• 7	Го De	sign shafts and couplings for power transmission.									
		sign the threaded fasteners, bolted joints and welded joints for ructures.	press	ure v	essel	S					
		sign the various types of springs like helical, leaf springs and l nt loads and varying loads.	Flywh	eels	unde	r					
• 7	Го De	sign various types of bearings like Rolling contact and Sliding	g conta	ict be	earing	gs.					
UNIT I	I	NTRODUCTION TO MACHINE DESIGN				9					
based on me Theories of	chani failu	e Design process – Factors influencing machine design – sel cal properties - preferred numbers – Limits, Fits, tolerances - re – Factor of safety –stress concentration – Direct, Bendfor variable loading.	Princ	ipal	stress	ses -					
UNIT II	D	ESIGN OF SHAFTS AND COUPLINGS				9					
		and hollow shafts based on strength, rigidity - critical speed $-\mathbf{K}$ d flexible couplings.	eys, k	eywa	ıys aı	nd					
UNIT III	D	ESIGN OF TEMPORARY AND PERMANENT J	TEMPORARY AND PERMANENT JOINTS								
		s - Bolted joints subjected to eccentric loading, Knuckle joints joints, Riveted joints for structures.	s, Cott	er jo	ints –	-					
UNIT IV	D	ESIGN OF ENERGY STORING ELEMENTS				9					
_		els considering stresses in rims and arms, for engine		er s							
UNIT V	D	ESIGN OF BEARINGS				9					
		-		1 1	beari	nos					
_	quatio	and rolling contact bearings - Design of hydrodynamic n. Sommerfield Number, Raimondi & Boyd graphs, - Se	•			0					
McKee's Ed	quatio		electio	on of	Rol	ling					
McKee's Ed	quatio rings.	n. Sommerfield Number, Raimondi & Boyd graphs, - Se TOTAL	electio	on of	Rol	ling					
McKee's Ec Contact bear	quatio rings. IES:	n. Sommerfield Number, Raimondi & Boyd graphs, - Se TOTAL	2:45	PE	RIO	ling					
McKee's Ec Contact bear OUTCON	rings. IES: oly the	n. Sommerfield Number, Raimondi & Boyd graphs, - Se TOTAL On completion of this course, students will be able to	2:45	PE	RIO	ling					
OUTCON 1. App 2. Des	TES:	TOTAL On completion of this course, students will be able to e principles of design to solve problems dealing with static and	2:45	PE	RIO	ling					
OUTCON 1. App 2. Des 3. Esti	TES: oly the ign sh	TOTAL On completion of this course, students will be able to e principles of design to solve problems dealing with static and nafts and couplings for various industrial applications.	2:45	PE	RIO	ling					

TEX	T BOOKS:
1.	Bhandari V.B, " Design of Machine Elements ", Second Edition, Tata McGraw-Hill Book Co, 2007.
2.	Shigley J.E and Mischke C. R., "Mechanical Engineering Design", Sixth Edition, Tata McGraw-Hill, 2003.
3.	Robert C. Juvinall and Kurt M. Marshek, "Fundamentals of Machine Design", 4 th edition, Wiley, 2005
REF	ERENCES:
1.	Sundararajamoorthy T. V. Shanmugam.N., "Machine Design", Anuradha Publications, Chennai, 2003
2.	Orthwein W., "Machine Component Design", Jaico Publishing Co, 2003
3.	Merhyle F. Spotts, Terry E. Shoup and Lee E. Hornberger, "Design of Machine Elements" 8 th Edition, Printice Hall, 2003.
4.	Alfred Hall, Halowenko, A and Laughlin, H., "Machine Design", Tata McGraw-Hill BookCo.(Schaum's Outline), 2010
5.	Robert L. Norton, "Machine design An integrated approach", Fifth edition, Pearson education, 2001

MAPPINO	G OI	F CO	s, Po	Os Al	ND P	SOs:												
	POs														PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3			
CO1	2	2	1	1		1		1			2		2	2				
CO2	2	2	1	1		1		1		2	2		2	2				
CO3	2	2	1	1		1		1		2	2		2	2				
CO4	2	2	1	1		1		1		2	2		2	2				
CO5	2	2	1			1		1			2		2	2				
Average	2	2	1	0.8		1		1		1.2	2		2	2				
Round off	2	2	1	1		1		1		1	2		2	2				
3- Strong C	orrel	ation;	2 - N	Iediu i	n Coi	rrelati	ion; 1	- Lo	w Coi	rrelati	on							

OBJECT	To ma To und To deterelation To ana	ke the students to understand the concept of conduction heat the derstand the convective heat transfer mechanism.	3 cransfe	1 er.	0	4									
•	To made To und To determine To ana	ke the students to understand the concept of conduction heat the derstand the convective heat transfer mechanism.	transfe	er.											
• • • • • UNIT	To und To deterelation To ana	lerstand the convective heat transfer mechanism.	ransfe	er.											
• • • • UNIT	To deternation														
• • • • UNIT	relation To ana		To understand the convective heat transfer mechanism.												
• • UNIT		ermine the amount of radiation heat exchange between surfacture.	es and	d its t	herm	al									
• UNIT	T.	lyse the phase change heat transfer and sizing of heat exchan	ger.												
UNIT	To eva	duate the mass transfer through diffusion and convection med	hanis	m.											
~	I CONDUCTION														
Dimension	nal Stea	tial equation of Heat Conduction— Cartesian and Polar of dy State Heat Conduction — plane and Composite Systems eration — Extended Surfaces — Unsteady Heat Conduction.													
UNIT I	II C	ONVECTION			9+3										
empirical planes, inc	relation clined su	ernal and internal forced convection flows – flat plate, c s for free convection flows – horizontal cylinders, horizontal care and enclosed spaces.			, ver	tical									
UNIT I	II R	ADIATION			9	9+3									
black body surface –	y radiati view fac	radiation – radiation intensity – relation to emission, irradiation – loss of radiation – emissivity – surface emission – Kitcor – radiation exchange between black surfaces – radiation extrical analogy – radiation shields.	rchof	f's la	w –	gray									
UNIT I	V C	ONDENSATION, BOILING AND HEAT EXCH	ANG	ER	S	9+3									
vertical pla	ate – Re	Boiling – Film wise and drop wise condensation – Film egimes of Boiling – Forced convection boiling- Heat Exchan pefficient – Fouling Factors –Heat transfer Analysis: LM	ger T	ypes	- Ov	erall									
UNIT '	$\mathbf{V} \mid \mathbf{M}$	IASS TRANSFER			9	9+3									
Diffusion	- Con	Diffusion Mass Transfer – Fick's Law of Diffusion – Stervective Mass Transfer – Momentum, Heat and Mass Transfer Correlations.	•												
		LECTURE: 45 TUTORIAL: 15 TOTAI	: 60) PE	RIO	DS									
OUTCO	MES:	On completion of this course, students will be able to													
		sic principles of heat conduction to find heat transfer rate in systems.	teady	state	and										
tra	ransient systems.														

3.	Analyze the radiation heat transfer problems and radiation shields.
4.	Analyze the phase change heat transfer and heat exchanger.
5.	Assess different mass transfer systems.
TEX	T BOOKS:
1.	P. K. Nag, " Heat Transfer " Tata McGraw Hill Publishing Company Limited. 3 rd edition 2011.
2.	C. P. Kothandaraman and S. Subramanyan, "Heat and Mass Transfer Data Book",8 th Edition, New Age International Publishers 2014.
REF	ERENCES:
1.	Yunus A. Cengel, " Heat Transfer-A Practical Approach " Tata McGraw Hill Publishing Company Limited. 3 rd edition. 2007.
2.	Frank P. Incropera and David P. Dewitt, "Fundamentals of Heat and Mass Transfer", 8 th Edition, John Wiley & Sons 2016.
3.	Y. V. C. Rao, "Heat Transfer", First Edition, Universities Press (India) Limited, 2001.
4.	Sarit K. Das, "Process Heat Transfer", Narosa Publishing House, 2009.
5.	S. P. Venkateshan, "First Course in Heat Transfer", 6 th edition, Ane Books Publishers, 2004.

	G OF COs, POs AND PSOs:																	
	POs														PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3			
CO1	2	2	1	1				2	1				2	1	1			
CO2	1	2	2					1	1				2	2				
CO3	1	2	2					1	1				2	2	1			
CO4	2	2	2					1	1				2	2	1			
CO5	1	2	1					1	1				2	1				
Average	1.4	2	1.8	0.2				1.2	1				2	1.6	0.6			
Round off	1	2	2	0				1	1				2	2	1			

18MPC5	03		MANUFACTURING TECHNOLOGY II	L	T	P	C
	•			3	0	0	3
OBJECT	IVE	S				l .	
•	To he	elp stud	lents to acquire knowledge about the theory of metal cutting J	proce	SS.		
•	To ac	quire l	knowledge on Lathes, Shaping and planning machines.				
_			nem to understand the principles and operations of Drilling, Bachines.	Broach	ning a	nd	
•	To un	ıdersta	nd principle and working of Milling and Gear generation mad	chines	S.		
•	To pr	ovide l	knowledge about various Modern manufacturing process.				
UNIT I		THE	EORY OF METAL CUTTING				9
materials – o	cuttin	g fluic				tting	
UNIT I	.1	AUI	COMATS, SHAPING AND PLANING MACHI	INES	•		9
construction			d multi - spindle automats - shaping and planning masm - principle of operation - different shaping operation	nachir	nes –	type	
	n - m	echani	sm – principle of operation – different shaping operation	nachir ons -	nes – work	type hol	es –
devices. UNIT II Drilling may broaching —	II chines	DRI s – sp		cool n	nes – work NES omen ng –	type type	es – ding 9 re – s of
UNIT II Drilling may broaching — grinding may	chine-specachine	DRI s – specifications es – g	LLING, BROACHING AND GRINDING MACE ecifications, types - feed mechanism, operations - drill tons, types, tool nomenclature, broaching operations - g	CHI cool n grindi d reco	nes – work NES omen ng –	type type	es – ding 9 re – s of
Drilling made broaching — grinding when grinding when the street of the	chine speciachine leels. V specifi gear ns - cr	DRI s – specification es – g MII ication form utters-	LLING, BROACHING AND GRINDING MACE ecifications, types - feed mechanism, operations - drill tons, types, tool nomenclature, broaching operations - grinding wheels, specifications - bonds - mounting and the second	CHI cool n grindi d reco ES millin d ge	NES omen ng – onditi	type chol aclatu type onin	9 re - s of g of
Drilling made broaching — grinding when grinding when the street of the	chine special specific gearns - ching n	DRI s – specification es – g MIL ication form utters- method	LLING, BROACHING AND GRINDING MACE ecifications, types - feed mechanism, operations - drill tons, types, tool nomenclature, broaching operations - grinding wheels, specifications - bonds - mounting and the second	CHI cool n grindi d reco ES millin d ge	NES omen ng – onditi	type chol aclatu type onin	9 re - s of
Drilling man broaching — grinding man grinding when the control of	chine speciachine eels. V specifi gearns - ching n	DRI s - specification es - g MII ication form utters- nethod NC,	LLING, BROACHING AND GRINDING MACE ecifications, types - feed mechanism, operations - drill tons, types, tool nomenclature, broaching operations - grinding wheels, specifications - bonds - mounting and LLING AND GEAR GENERATING MACHINITIES - types - cutter nomenclature - types of cutters - raing in milling - gear generation - gear shaping and coated tools & inserts- cutting spur and helical gears - bels.	CHI cool n grindi d reco ES millin d ge evel g	NES omen ng – onditi	type clature type coning occess obbin eneral	9 9 9 9 9 10 9 11 9 12 13 14 15 16 16 17 17 18 18 18 18 18 18 18 18 18 18 18 18 18
devices. UNIT II Drilling many broaching — grinding many grinding who will the second process of the second	chine speciachine eels. V specifi gearns - ching n	DRI s - specification es - g MII ication form utters- nethod NC,	LLING, BROACHING AND GRINDING MACE ecifications, types - feed mechanism, operations - drill tons, types, tool nomenclature, broaching operations - grinding wheels, specifications - bonds - mounting and the second	CHI cool n grindi d reco ES millin d ge evel g	NES omen ng – onditi g pro ar ho ear go	type clature type coning conin	9 re - s of g of g of g - g - g - g - g - g - g - g - g - g

1.	Apply the theor	ry of metal cutting in real life machining.
2.	Explore the ope	erating mechanisms of lathe, shaping and planning machine.
3.	Compare the w	orking principles of drilling, boring and grinding machines.
4.	Understand the	principles, operation and working of milling and gear generating machine.
5.	Explain the cor	ncept of NC,CNC and RPT.
TEX	T BOOKS:	
1.		S. K. and Bose S. K., "Workshop Technology Vol II" , Media Promoters Pvt. Ltd., Bombay, 2004
2.	P.N. Rao, " Ma McGraw - Hill	nufacturing Technology Foundry, Forming and Welding" , Tata 3 rd Edition, 2009
REF	ERENCES:	
1.		ian and Steven R. Schmid, "Manufacturing Engineering and Technology", ntice Hall, 2013.
2.	Jain R. K. and 1999.	Gupta S. C., " Production Technology ", Khanna Publishers, New Delhi,
3.		be, John E. Neely, Roland O. Merges and Warren J.White, "Machine Tool Edition,Pearson, 2005.
4.	Roy. A. Lindbe Pearson Educa	rg, "Process and Materials of Manufacture" , Fourth Edition, PHI / ation 2006.
5.		"A Text Book of Production Technology", S.Chand& Company Ltd., New ised edition, 2010

			MA	PPIN	IG O	F CO	os, P	Os A	ND I	PSOs	:						
		POs													PSOs		
	1	1 2 3 4 5 6 7 8 9 10 11 12												2	3		
CO1	2	1	1			1		1			2	1	2	2	1		
CO2	2	1	1			1		1			2	1	2	1	1		
CO3	1	1	1			1		1			2	1	2	2	1		
CO4	1	2	1			1		1			2	1	2	2	1		
CO5	1	1	1			1		1			1	1	1	1			
Average	1.4	1.2	1			1		1			1.8	1	1.8	1.6	0.8		
Round off	1	1	1			1		1			2	1	1	2	1		
3- Strong Cor	relati	on; 2	- Med	lium (Corre	lation	; 1 – I	Low (Corre	lation	1						

	C504	METROLOGY AND MEASUREMENTS	L	T	P	C
			3	0	0	3
OBJEC	TIVE	NS .			l l	
•	To m	ake the students to understand the basics of metrology.				
•	To e	xplore different types of linear and angular measuring instrume	ents.			
•	To u	nderstand the various form measurement techniques.				
•	To g	et knowledge on various power, flow and temperature measure	ments.	•		
•	To p	rovide them the latest advances in metrology.				
UNIT	I	BASICS OF METROLOGY				9
Reliabilit UNIT	y.	rds – Introduction to interferometry - Reliability and Calibratio	лі — К	<u> </u>		9
Projector UNIT		ip gauges, Comparators -Mechanical, Electrical, Optical and			. 1	
		ANGULAR AND FORM MEASUREMENTS				9
measuren	Applic nent, g	ANGULAR AND FORM MEASUREMENTS g instruments - Bevel protractor, Spirit level, Sine bar, Au ations. Principles and Methods of straightness – Flatness mea gear measurement, surface finish measurement, Roundnes timit gauges.	asuren	nent	- Th	ngl
measuren	Applic nent, g ons – L	g instruments - Bevel protractor, Spirit level, Sine bar, Au ations. Principles and Methods of straightness – Flatness mea gear measurement, surface finish measurement, Roundness	asuren	nent	- Th	ngl
Measuren Applicati UNIT Force, tor Venturi n	Application Applic	g instruments - Bevel protractor, Spirit level, Sine bar, Au ations. Principles and Methods of straightness — Flatness measurement, surface finish measurement, Roundnessimit gauges. MEASUREMENT OF POWER, FLOW AND	asuren ss me	nent easur easu	- Theremen	angle areac nt - 9 ent:
Measuren Applicati UNIT Force, tor Venturi n	Application Applic	g instruments - Bevel protractor, Spirit level, Sine bar, Au ations. Principles and Methods of straightness — Flatness measurement, surface finish measurement, Roundnessimit gauges. MEASUREMENT OF POWER, FLOW AND TEMPERATURE ower - mechanical, Pneumatic, Hydraulic and Electrical type. Forifice meter, rota meter, pitot tube — Temperature: bimetallic straightness — Spirit level, Sine bar, Au ations. — Flatness measurement, Roundnessimit gauges.	asuren ss me	nent easur easu	- Theremen	anglenreacht - 9
Measuren Applicati UNIT Force, tor Venturi n Electrical UNIT Tool ma Automati	Application Applic	g instruments - Bevel protractor, Spirit level, Sine bar, Au ations. Principles and Methods of straightness — Flatness measurement, surface finish measurement, Roundnessimit gauges. MEASUREMENT OF POWER, FLOW AND TEMPERATURE ower - mechanical, Pneumatic, Hydraulic and Electrical type. Forifice meter, rota meter, pitot tube — Temperature: bimetallic strace thermometer — Pressure measurement.	asuren ss me	nent easur neasu nermo	- Theremen	ngloareacht - 9 ent: ples
Measuren Applicati UNIT Force, tor Venturi n Electrical UNIT Tool ma Automati	Application Applic	g instruments - Bevel protractor, Spirit level, Sine bar, Au ations. Principles and Methods of straightness — Flatness measurement, surface finish measurement, Roundnessimit gauges. MEASUREMENT OF POWER, FLOW AND TEMPERATURE ower - mechanical, Pneumatic, Hydraulic and Electrical type. Forifice meter, rota meter, pitot tube — Temperature: bimetallic struce thermometer — Pressure measurement. ADVANCES IN METROLOGY microscope - Computer controlled CMM - Universal measurement inspection machine - Computer aided inspection	asuren ss me flow m trip, th	nent easur neasu nermo	reme	9 ent: pless 9
Measuren Applicati UNIT Force, tor Venturi n Electrical UNIT Tool ma Automati	Application Applic	g instruments - Bevel protractor, Spirit level, Sine bar, Au ations. Principles and Methods of straightness — Flatness mea gear measurement, surface finish measurement, Roundnes imit gauges. MEASUREMENT OF POWER, FLOW AND FEMPERATURE ower - mechanical, Pneumatic, Hydraulic and Electrical type. Forifice meter, rota meter, pitot tube — Temperature: bimetallic st nce thermometer — Pressure measurement. ADVANCES IN METROLOGY microscope - Computer controlled CMM - Universal meanultidimensional inspection machine - Computer aided inspectistem -Laser interferometer — Introduction to Clean room. TOTAL	asuren ss me flow m trip, th	nent easur neasu nermo	reme	9 ent: pless 9
Measuren Applicati UNIT Force, tor Venturi n Electrical UNIT Tool ma Automati measuren OUTCO	Application Applic	g instruments - Bevel protractor, Spirit level, Sine bar, Au ations. Principles and Methods of straightness — Flatness mea gear measurement, surface finish measurement, Roundnes imit gauges. MEASUREMENT OF POWER, FLOW AND FEMPERATURE ower - mechanical, Pneumatic, Hydraulic and Electrical type. Forifice meter, rota meter, pitot tube — Temperature: bimetallic st nce thermometer — Pressure measurement. ADVANCES IN METROLOGY microscope - Computer controlled CMM - Universal meanultidimensional inspection machine - Computer aided inspectistem -Laser interferometer — Introduction to Clean room. TOTAL	asuren ss me flow m trip, th	nent easur neasu nermo	reme	9 ent: pless 9

3.	Identify and compare various form measurement techniques.
4.	Explain the principle of measuring power, flow and temperature.
5.	Discuss the recent advances in metrology.
TEX	T BOOKS:
1.	Jain.R.K., "Engineering Metrology", Khanna Publishers, Delhi, 2004.
2.	Gupta. I.C., "Engineering Metrology", Dhanpatrai Publications, 2005.
3.	Mikell Groover "Automation, Production Systems, and Computer-integrated Manufacturing" Pearson, edition four, 2016.
REF	ERENCES:
1.	Charles Reginald Shotbolt, "Metrology for Engineers", 5th edition, Cengage Learning EMEA, 1990.
2.	Gayler G. N. and Shotbolt C. R., "Metrology for Engineers", ELBS 2000.
3.	Thomas G. Beckwith, Roy D, Marangoni, John H.Lienhard V., "Mechanical Mesurements", Addison WeleyPublishing Company, 2004.
4.	W. Whyte, "Clean Room Technology, Fundamental of Design, Testing and Operation" second edition, 2010.
5.	Herbert Freeman, "Machine Vision for Inspection and Measurement", Academic Press, INC, 1989.

MAPPING	G OI	F CO	s, PC)s Al	ND P	SOs:									
		POs													
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	1	1								1		2	1	
CO2	2	1	1								1		2		1
CO3	2	1	1								1		2		1
CO4	2	1	1								1		2		1
CO5	2										1		2		1
Average	2	0.8	0.8								1		2	0.2	0.8
Round off	2	1	1								1		2	0	1
3- Strong C	orrel	ation;	2 - M	lediu	m Coi	relati	ion; 1	- Lo	w Coi	rrelati	on				

18MPC506	MANUFACTURING AND METROLOGY LABORATORY	L	Т	P	С
		0	0	4	2
OBJECTIVE	S	•			

- To study and practice the various operations that can be performed in lathe, drilling, milling and shaping machines.
- To do Gear cutting using milling and hobbing machines and to perform operations in Grinding machines.
- To familiarize the students on the working of various measuring instruments and to perform measurements of parts to check the quality.

LISTOFEXPERIMENTS:

MANUFACTURING LABORATORY

- 1. Facing, plain, step and taper turning.
- 2. Knurling and chamfering and thread cutting (external).
- 3. Counter sinking ,drilling and boring
- 4. Contour milling using vertical milling machine.
- 5. Spur gear cutting in milling machine.
- 6. Gear generation in Hobbing machine.
- 7. Plain Surface grinding.

METROLOGY LABORATORY

- 1. Tool Maker's Microscope
- 2. Comparator
- 3. Sine Bar
- 4. Gear Tooth Vernier Caliper
- 5. Surface Finish Measuring Equipment
- 6. Vernier Height Gauge
- 7. Temperature, Force and torque Measurement
- 8. Machine Vision Measurement systems

			TOTAL:45 PERIODS					
OUI	TCOMES:	On completion of this course, students will	be able to					
1.	1. Demonstrate and fabricate different types of components using the machine tools.							
2.	Set up machines like lathe shaper, grinding and milling machine for various applications.							
3.	Handle differer parts.	nt measurement instrument and to perform m	neasurements to check quality of					

		POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	2	1	2	1				2	1		1	1	2	2	1	
CO2	2	1	2	1				2	1		1	1	2	2	1	
CO3	2	1	2	1				2	1		1	1	2	2	1	
Average	2	1	2	1				2	1		1	1	2	2	1	
Round off	2	1	2	1				2	1		1	1	2	2	1	

18MPC	HEAT AND MASS TRANSFER LABORATORY	L	T	P	C				
		0	0	3	1.5				
OBJEC	TIVES	<u>.</u>							
•	To make the students to perform experiments on heat transfer applications.								
•	To analyse the performance of a refrigeration systems.								
To understand and perform experiments on air conditioning system.									

LIST OF EXPERIMENTS:

HEAT TRANSFER EXPERIMENTS:

- 1. Thermal conductivity measurement using guarded plate apparatus.
- 2. Thermal conductivity measurement of pipe insulation using lagged pipe apparatus.
- 3. Determination of heat transfer coefficient under natural convection from a vertical cylinder.
- 4. Determination of heat transfer coefficient under forced convection from a tube.
- 5. Determination of Thermal conductivity of composite wall.
- 6. Determination of Thermal conductivity of insulating powder.
- 7. Heat transfer from pin-fin apparatus (natural & forced convection modes).
- 8. Determination of Stefan Boltzmann constant.
- 9. Determination of emissivity of a grey surface.
- 10. Effectiveness of Parallel/counter flow heat exchanger.

REFRIGERATION AND AIR CONDITIONING EXPERIMENTS:

- 1. Determination of COP of a refrigeration system.
- 2. Experiments on Psychometric processes.
- 3. Performance test on a Reciprocating air compressor.
- 4. Performance test in a HC Refrigeration System.
- 5. Performance test in a Fluidized Bed Cooling Tower
- 6. Devices for thermal collectors and storage

			TOTAL: 45 PERIODS					
OUT	COMES:	On completion of this course, students wi	ll be able to					
1.	Apply the fundamental principles of heat transfer to predict the thermal conductivity and heat transfer coefficient.							
2.								
3.	Determine the	e amount of heat transfer in conduction, cor	nvection and radiation.					

MAPPING	G OI	F CO	s, PO)s Al	ND P	SOs:									
			PSOs												
	1	1 2 3 4 5 6 7 8 9 10 11 12											1	2	3
CO1	2	2	2	1				2	1		1	1	2	2	1
CO2	2	2	2	1		2		2	1		1	1	2	2	1
CO3	2	2	2	1		2		2	1		1	1	2	2	1
Average	2	2	2	1		1.3		2	1		1	1	2	2	1
Round off	2	2	2	1		1		2	1		1	1	2	2	1
3- Strong C	orrel	ation;	2 - N	Iediu i	m Co	rrelati	ion; 1	- Lo	w Coi	relati	on				

18MP	R508 PROJECT I / WINTER INTERNSHIP	L	T	P	C			
		0	0	3	1.5			
OBJE	CTIVES			•				
•	To provide opportunity to explore a problem or issue of particular professional interest.	perso	nal o	r				
•	To address the problem or issue through focused study and applie direction of a faculty member.	l rese	arch u	ındeı	the			
•	To synthesize and apply the knowledge and skills acquired in his/her academic program to real-world issues and problems.							
•	To improve ability to think critically and creatively, to solve practical problems,							
•	To make reasoned and ethical decisions, and to communicate effe	ctivel	٧.					

The students in a group of 3 to 4 works on a topic approved by the head of the department under the guidance of a faculty member and prepare a comprehensive project report after completing the work to the satisfaction of the supervisor. The progress of the project is evaluated based on a minimum of three reviews in that any one review will be conducted with external examiner.

The review committee may be constituted by the Head of the Department. A project report is required at the end of the semester. The project work is evaluated based on oral presentation and the project report jointly by external and internal examiners constituted by the Head of the Department.

(or)

A Minimum of 2 weeks internship in reputed organization during summer vacation

			TOTAL: 45 PERIODS						
OU'.	FCOMES:	On completion of this course, students will be able to							
1	1 Identify the real time Engineering problems in their day to day life.								
2	Apply the knowledge and skills acquired in their courses to a specific problem or issue								
3	•	y and creatively to address and help solurther development.	ve these professional or social						
4	Refine research skills and demonstrate their proficiency in written and oral communication skills.								
5		allenges of teamwork, prepare a preser all aspects of design work.	ntation in a professional manner,						

MAPPINO	G OF	r CO	s, PC	s AN	ND P	SOs:										
		POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	3	3	2	3	1	1	2	3	3	2	3	2	3	3	2	
CO2	3	3	3	3	1	1	2	3	3	2	3	2	3	3	2	
CO3	3	3	3	3	2	2	2	3	3	3	3	2	3	3	2	
CO4	3	3	3	3	2	2	2	3	3	3	3	2	3	3	2	
CO5	2	2	2	1	2	2	3	3	3	2	3	2	3	3	2	
Average	2.8	2.8	2.6	2.6	1.6	1.6	2.2	3	3	2.4	3	2	3	3	2	
Round off	3	3	3	3	2	2	2	3	3	2	3	2	3	3	2	
3- Strong C	orrela	ation;	2 - M	lediur	n Cor	relati	on; 1	– Lov	v Cor	relati	on					

18MPC	601	DYNAMICS OF MACHINERY	L	T	P	C
			3	1	0	4
OBJECT	TIVES					
•	To ma	ke the students to understand the concepts of dynamics of recip	proca	ting	engin	es.
•	To und and en	derstand the balancing procedures for rotating and reciprocating gines.	g mas	sses,	rotor	S
•	To ana	alyse the effect of free and forced vibration.				
•	To und	derstand the governor mechanism for speed control of machine	es.			
•	To giv	e insight effect of gyroscope and its application.				
UNIT I	[F	ORCE ANALYSIS			9	9+3
Analysis in	recipr	nalysis – Inertia force and Inertia torque – D Alembert's proceeding engines – Gas forces – Inertia effect of connecting roce – Turning moment diagrams –Fly Wheels.				
UNIT I	I B	ALANCING			9)+3
Primary an	nd seco	c balancing – balancing of rotating masses–Balancing of Recindary unbalanced forces-partial balancing of unbalanced primotives-Variation of tractive force, Swaying couple and Hami	imary	for		
UNIT II		REE VIBRATION			9)+3
natural free	quency	vibratory systems –degrees of freedom– free vibration – equ – types of damping – damped vibration - critical speeds : single, two rotor systems.				
UNIT I	VF	ORCED VIBRATION			9)+3
	e caus	degree of freedom systems to periodic forcing – Harmon ed by unbalance – Support motion –transmissibility – V				
vibration m	icasurc	ment.				
vibration m		IECHANISMS FOR CONTROL			9)+3
UNIT V Governors governors	Type - Cha	IECHANISMS FOR CONTROL es – Centrifugal governors – Gravity controlled and spring contracteristics – Effect of friction – Controlling force curves and torques – Gyroscopic stabilization – Gyroscopic effect	es. C	Jyros	ntrif scope	ugal s –
Governors governors Gyroscopic	Type - Cha	IECHANISMS FOR CONTROL es – Centrifugal governors – Gravity controlled and spring contracteristics – Effect of friction – Controlling force curves and torques – Gyroscopic stabilization – Gyroscopic effect	es. C	Syros Auto	entrif scope emob	ugal s – iles,
Governors governors Gyroscopic	Type - Type - Cha c forces irplane	res – Centrifugal governors – Gravity controlled and spring contracteristics – Effect of friction – Controlling force curves and torques – Gyroscopic stabilization – Gyroscopic effects. LECTURE: 45 TUTORIAL: 15 TOTAL	es. C	Syros Auto	entrif scope emob	ugal s – iles,
UNIT V Governors governors Gyroscopic ships and a	Type - Cha c forces irplane	res – Centrifugal governors – Gravity controlled and spring contracteristics – Effect of friction – Controlling force curves and torques – Gyroscopic stabilization – Gyroscopic effects. LECTURE: 45 TUTORIAL: 15 TOTAL	es. C	Syros Auto	entrif scope emob	ugal s – iles,
OUTCO: 1. Ar 2. Ap	Type - Type - Cha c forces irplane MES:	rescription of this course, students will be able to	ts in	Auto PE	entrificope omob	ugal es – iles,

4.	Analyze forced vibrations of machines, engines and structures.
5.	Calculate the gyroscopic couple on various vehicles and apply concept of governors.
TEX	T BOOKS:
1.	Rattan, S.S, "Theory of Machines", 3 rd Edition, Tata McGraw-Hill, 2009.
2.	Uicker, J.J., Pennock G.R and Shigley, J.E., " Theory of Machines and Mechanisms ", 3 rd Edition, Oxford University Press, 2009.
3.	Thomas Bevan, "Theory of Machines", 3 rd Ed., CBS Publishers and Distributors, 2005
REF	ERENCES:
1.	Ghosh. A and Mallick, A.K., "Theory of Mechanisms and Machines", Affiliated East-West Pvt. Ltd., New Delhi, 1988.
2.	V.Ramamurthi, ''Mechanics of Machines'', Narosa Publishing House, 2002
3.	Khurmi, R.S., "Theory of Machines", 14th Edition, S Chand Publications, 2005.
4.	Cleghorn. W. L, "Mechanisms of Machines", 2 nd Edition, Oxford University Press, 2015
5.	Robert L. Norton, "Kinematics and Dynamics of Machinery", 5 th Edition, Tata McGraw-Hill, 2012.

MAPPING	GOF	COs	, PO	s AN	D PS	SOs:									
	POs													PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	3	2		1						1		3	2	
CO2	3	3	1		2						1		3	1	
CO3	3	3	2		1						1		3	3	
CO4	3	3	1		1						1		3	3	
CO5	3	3	2		3						1		3	3	1
Average	3.0	3.0	1.6		1.6						1.0		3.0	2.4	0.2
Round off	3	3	2		2						1		3	2	0
3- Strong Co	orrela	tion;	2 - Mo	edium	Cori	elatio	n; 1 -	- Low	Cori	relatio	n				

18MPC	C602	FINITE ELEMENT ANALYSIS	L	T	P	\mathbf{C}	
			3	1	0	4	
OBJECT	TIVES	5					
•	To ma	ike the students to understand the basics concepts of finite elements	ment a	naly	sis.		
•	To pro	ovide them in depth knowledge in approximate methods in streems.	uctura	l med	chani	ics	
•	To und	derstand one dimensional finite element analysis with various	types	of el	emei	nts.	
•	_	exposed to plane problems in engineering analysis including element analysis.	two d	imen	sion	al	
•	To und	derstand the usage of higher order element in finite element ar	nalysis	١.			
UNIT I INTRODUCTION							
refinement	t, conve	ound-basic concept of FEM – discretization of 1D, 2D and ergence requirements - gradient and divergence theorems - be simple case studies.					
UNIT I	II C	HARACTERISTIC MATRICES AND LOAD VE	TCT()DC		9+3	
		TIANACTERISTIC MATRICES AND LOAD VI	2010	INS		713	
variation c	calculus	governing equations - structural and heat transfer problems - s — weighted residual methods - Galerkin's method - Ritz moach - principle of minimization of potential energy - simple of	variat nethod	ional - ge	met nera	hod-	
variation c	calculus e's appro	governing equations - structural and heat transfer problems - — weighted residual methods - Galerkin's method - Ritz m	variat nethod	ional - ge	met nera	hod- lized	
variation coordinate UNIT II Derivation function ch	calculus c's appro II O n of shap haracter	governing equations - structural and heat transfer problems - s - weighted residual methods - Galerkin's method - Ritz moach - principle of minimization of potential energy - simple controls.	variate thod case story of Marrian	ional - ge udies	met nera s.	hod- lized 9+3 hape	
variation coordinate UNIT II Derivation function chewalls and	calculus e's appro II O n of shap haracter fins -	governing equations - structural and heat transfer problems - s - weighted residual methods - Galerkin's method - Ritz moach - principle of minimization of potential energy - simple concept of the problems of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of minimization of potential energy - simple concept of the principle of th	variate thod case story of Marrian	ional - ge udies	met nera s. es - s omp	hod- lized 9+3 hape	
variation of coordinate UNIT II Derivation function of walls and studies. UNIT I Derivation matrices a	calculus e's appro II O n of shap haracter fins - V T n of sha and force Structu	governing equations - structural and heat transfer problems - s - weighted residual methods - Galerkin's method - Ritz method - principle of minimization of potential energy - simple of the DIMENSIONAL PROBLEMS pe functions, Stiffness matrices and force vectors - Assembly ristics - problems in axial load members, trusses, heat transfer Gauss elimination and Cholesky'smethods of solving equations.	variatinethod case strained of Mar through unation	ional - ge udies atrice igh c s-sim	met nerals.	hod- lized 9+3 hape osite case 9+3 fness axi-	
variation of coordinate UNIT II Derivation function of walls and studies. UNIT II Derivation matrices a symmetry.	calculus e's appro II O n of shap haracter fins - V T n of sha and forc structures.	governing equations - structural and heat transfer problems - s - weighted residual methods - Galerkin's method - Ritz method - principle of minimization of potential energy - simple of the DIMENSIONAL PROBLEMS pe functions, Stiffness matrices and force vectors - Assembly ristics - problems in axial load members, trusses, heat transfer Gauss elimination and Cholesky'smethods of solving equations for CST and LST triangular and rectangular ce vectors-Pascal's triangle- concept of plane stress and property of the problems are stress and property of the problems are stress and problems.	variatinethod case strained of Mar through unation	ional - ge udies atrice igh c s-sim	met nerals. es - s omposite and - sin	hod- lized 9+3 hape osite case 9+3 fness axi- mple	
Variation of coordinate UNIT II Derivation function of walls and studies. UNIT II Derivation matrices a symmetry, case studie UNIT II Natural coelements	realculus e's appro II O n of shap haracter fins - V T n of sha and force Structures. V H o-ordina — One a	governing equations - structural and heat transfer problems - s - weighted residual methods - Galerkin's method - Ritz method - principle of minimization of potential energy - simple of the DIMENSIONAL PROBLEMS pe functions, Stiffness matrices and force vectors - Assembly ristics - problems in axial load members, trusses, heat transfer Gauss elimination and Cholesky'smethods of solving equations for CST and LST triangular and rectangular are vectors-Pascal's triangle- concept of plane stress and parall and heat transfer application -introduction to coupled fie	variatinethod case structured of Mar through the case of Mar through the case of the case	ional - ge udies atrice igh c s-sim	met nerals. es - s omposite and - sin	hod- lized 9+3 hape osite case 9+3 fness aximple 9+3 etric	
Variation of coordinate UNIT II Derivation function of walls and studies. UNIT II Derivation matrices a symmetry, case studie UNIT II Natural coelements	realculus e's appro II O n of shap haracter fins - V T n of sha and force Structures. V H o-ordina — One a	governing equations - structural and heat transfer problems - weighted residual methods - Galerkin's method - Ritz method - principle of minimization of potential energy - simple of the principle of minimization of potential energy - simple of the principle of minimization of potential energy - simple of the principle of minimization of potential energy - simple of the principle of minimization of potential energy - simple of the principle of t	variatinethod case structured of Mar through the case of Mar through the case of the case	ional - ge udies atrice igh c s-sim ents, crain ilysis d La	met nerals. es - s omposite Stiff and - sin	hod- lized 9+3 hape osite case 9+3 fness axi- mple 9+3 etricagian	
Variation of coordinate UNIT II Derivation function of walls and studies. UNIT II Derivation matrices a symmetry, case studie UNIT II Natural coelements	calculus e's appro II O n of shap haracter fins - V T n of sha and forc es. V H o-ordina Numer	governing equations - structural and heat transfer problems - s - weighted residual methods - Galerkin's method - Ritz method - principle of minimization of potential energy - simple of the principle of minimization of potential energy - simple of the principle of minimization of potential energy - simple of the principle of minimization of potential energy - simple of the principle of minimization of potential energy - simple of the principle	variatinethod case structured of Mar through the case of Mar through the case of the case	ional - ge udies atrice igh c s-sim ents, crain ilysis d La	met nerals. es - s omposite Stiff and - sin	hod- lized 9+3 hape osite case 9+3 fness axi- mple 9+3 etricagian	
Variation of coordinate UNIT II Derivation function chewalls and studies. UNIT II Derivation matrices a symmetry. case studie UNIT II Natural coelements elements -	calculus e's appro II O n of shap haracter fins - IV T n of sha and force structures. IV H o-ordina - One a - Numer	governing equations - structural and heat transfer problems - s - weighted residual methods - Galerkin's method - Ritz method - principle of minimization of potential energy - simple of the principle of minimization of potential energy - simple of the DIMENSIONAL PROBLEMS pe functions, Stiffness matrices and force vectors - Assembly ristics - problems in axial load members, trusses, heat transfer Gauss elimination and Cholesky'smethods of solving equations for CST and LST triangular and rectangular are vectors-Pascal's triangle- concept of plane stress and pural and heat transfer application -introduction to coupled field the graph of the problems of the systems - Isoparametric elements - Shape functions and two dimensions - Jacobian transformation - Serendip rical integration - Matrix solution technique - simple case study the basic fundamental equations of elasticity and solving limite the basic fundamental equations of elasticity and solving limited.	variatinethod case strong of Mar through unation stelld analysis for sity and lies.	ional - ge udies atrice igh c s-sim ents, rain llysis isopa d La	met nerals. es - s omposite and - sin aram agram	hod-lized 9+3 hape osite case 9+3 fness aximple 9+3 etricagian	

3.	Solve one dimensional structural and heat transfer problems.
4.	Analyze and solve two dimensional problems.
5.	Solve problems using higher order elements.
TEX	TT BOOKS:
1.	Tirupathi R. Chandrupatla and Ashok D. Belegundu,"Introduction to Finite Element in Engineering", PearsonEducation ,2003
2.	Reddy. J.N., "An Introduction to the Finite Element Method" , 3 rd Edition, Tata McGraw-Hill,2005
3.	Seshu, P, " Text Book of Finite Element Analysis ", Prentice-Hall of India Pvt. Ltd., New Delhi, 2007.
REF	ERENCES:
1.	BhattiAsghar M, "Fundamental Finite Element Analysis and Applications", John Wiley &Sons, 2005 (Indian Reprint 2013)
2.	Larry J. Segerlind, "Applied Finite element Analysis", 2 nd Ed, John Wiley & Sons, 1987
3.	David V.Hutton"Fundamentals of finite element Analysis" McGraw Hill Inc, Newyork, 2004.
4.	Robert D. Cook, David S. Malkus, Michael E. Plesha, Robert J. Witt, "Concepts and Applications of Finite Element Analysis", 4th Edition, Wiley Student Edition, 2002.
5.	Singiresu.S.Rao, "The Finite Element Method in Engineering", ButterWorth Heinemann, 2001.

						P	Os						PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	3	2	1							3		3	3	
CO2	3	3	2	1							2		3	2	
CO3	3	3	2	1							2		3	2	
CO4	3	3	2	1							2		3	3	
CO5	3	3	2	1							2		3	1	
Average	3.0	3.0	2.0	1.0							2.2		3.0	2.2	
Round off	3	3	2	1							2		3	2	

18MPC603	3	ADDITIVE MANUFACTURING	L	T	P	C
	•		3	0	0	3
OBJECTIV	ES	: :				
		the students to know the principle methods, areas of us ns as well as environmental effects of the Additive Mar				
		iarise the characteristics of the different materials those turing.	are used in	Add	itive	
• To fa	mil	iarize with Liquid based and Solid based additive manu	facturing to	echno	logie	es.
	-	se to other additive manufacturing technologies like 3D Shape deposition modelling, Reverse engineering.	printer, bal	listic	parti	cle
• To fa		iarize with the post processing and tooling methods of a gies.	additive ma	nufac	turin	g
UNIT I	IN	NTRODUCTION				9
		ry – Need-Classification -Additive Manufacturing Techerials for Additive Manufacturing Technology – Toolin				
UNIT II	C	AD & REVERSE ENGINEERING				9
Model Slicing MIMICS, MA UNIT III	GIC L	Tool path Generation – Software's for Additive MacS. IQUID BASED AND SOLID BASED ADDITATION OF THE PROPERTY O		g Te	chno]	ogy 9
advantages an	– L	Liquid based system – Stereo-lithography Apparatus (applications - Solid based system –Fused Depositions and Applications, Laminated Object Manufacturing.	n Modellii	_	_	
UNIT IV		OWDER BASED ADDITIVE MANUFACTI YSTEMS	URING			9
	cipl	intering — Principles of SLS process - Process, advantage, process, advantages and applications - Laser Engineeralting.	-	-		
UNIT V	M	IEDICAL AND BIO-ADDITIVE MANUFAC	CTURIN	G		9
	-	nts and prosthesis: Design and production - Bio-Additirissue Engineering (CATE) – Case studies.	ve Manufa	turin	g-	
		TOTA	AL: 45 P	ERI	ODS	5
OUTCOME	ES:	On completion of this course, students will be able to)			
1. Comp	are	different methods and discuss the effects of the Additive	e Manufact	uring		

2.	Learn the applications of CAD in tool path generation.
3.	Gain knowledge about liquid and solid based additive manufacturing systems.
4.	Analysing about powder based additive manufacturing systems.
5.	Understand the medical and bio additive manufacturing systems.
TEX	T BOOKS:
1.	Chua C.K., Leong K.F., and Lim C.S., "Rapid prototyping: Principles and applications", 3 rd Edition, World Scientific Publishers, 2010.
2.	Gebhardt A., "Rapid prototyping", Hanser Gardener Publications, 2003.
3.	Steinar Westhrin Kill "Additive Manufacturing: Design, Methods, and Processes", Pan Stanford Publishing Pte.Ltd.2017.
REF	ERENCES:
1.	Liou L.W. and Liou F.W., "Rapid Prototyping and Engineering applications: A tool box forprototype development", CRC Press, 2007.
2.	Kamrani A.K. and Nasr E.A., "Rapid Prototyping: Theory and practice", Springer, 2006.
3.	Hilton P.D. and Jacobs P.F., "Rapid Tooling: Technologies and Industrial Applications", CRCpress, 2000.
4.	Ian Gibson, David Rosen, Brent Stuck, "Additive Manufacturing Technologies: 3D Printing, Rapid Prototyping, and Direct Digital Manufacturing", Springer, 2015.
5.	AmitBandyopadhyay, Susmita Bose, "Additive Manufacturing", CRC Press, 2015.

18MP	C606	SIMULATION LABORATORY	L	T	P	C				
			0	0	3	1.5				
OBJE	CTIVE	S								
•	To make the students to analyse various structural problems using CAE software's.									
•	To analyse various thermal and heat transfer problems using CAE software's.									
•	To solve simple problems using Mat lab, CFD and Multi body dynamics software's.									

LISTOFEXPERIMENTS:

A. SIMULATION

- 1. MATLAB basics, Dealing with matrices, Graphing-Functions of one variable and two variables.
- 2. Use of Mat lab to solve simple problems in vibration.
- 3. Mechanism Simulation using Multi body Dynamic software.

B. ANALYSIS

- 1. Force and Stress analysis using link elements in Trusses, cables etc.
- 2. Stress and deflection analysis in beams with different support conditions.
- 3. Stress analysis of flat plates and simple shells.
- 4. Stress analysis of axi symmetric components.
- 5. Thermal stress and heat transfer analysis of plates.
- 6. Thermal stress analysis of cylindrical shells.
- 7. Vibration analysis of spring-mass systems.
- 8. Model analysis of Beams.
- 9. Harmonic, transient and spectrum analysis of simple systems.
- 10. Buckling analysis of column.
- 11. Coupled thermal and structural analysis.
- 12. Simple CFD analysis problems.

TOTAL:45 PERIODS								
OUTCOMES: On completion of this course, students will be able to								
1.	Get expos	ure to software tools needed to analyse engine	eering problems.					
2.	2. Apply simulation and analysis software tools to find solution for different real time Problems.							
3.	3. Carry out simple flow problems using simulation and analysis software's.							

MAPPING OF COs, POs AND PSOs:														
	POs									PSOs				
	1	1 2 3 4 5 6 7 8 9 10 11 12								1	2	3		
CO1	3	2	3	3	1		2			2		3	3	1
CO2	3	2	3	3	1		1			2		3	3	1
CO3	3	1	3	3	1		1			2		3	3	1
Average	3.0	1.7	3.0	3.0	1.0		1.3			2.0		3.0	3.0	1.0
Round off	Round off 3 2 3 3 1 1 2 3 3 1													
3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation														

18MI	PC607	DYNAMICS OF MACHINERY LABORATORY	L	T	P	C	
			0	0	3	1.5	
OBJE	ECTIVES						
•	To make the students to understand and demonstrate the principles of kinematic mechanisms.						
•	To perform experiments on governors and gyroscope systems and able to analyse its efficiencies.						
•	To understand the principles of vibrating system and to determine the performance of a vibrating system.						

LIST OF EXPERIMENTS

- 1. a) Study of gear parameters.
 - b) Experimental study of velocity ratios of simple, compound, Epicyclic and differential gear trains.
- 2. a) Kinematics of Four Bar, Slider Crank, Crank Rocker, Double crank, Double rocker, Oscillating cylinder Mechanisms.
 - b) Kinematics of single and double universal joints.
- 3. a) Determination of Mass Moment of Inertia using bifilar suspension and compound pendulum.
- 4. Motorized gyroscope Study of gyroscopic effect and couple.
- 5. Governor Determination of range sensitivity, effort etc., for Watt, Porter, Proell, and Hartnell Governors.
- 6. Cams Cam profile drawing, Motion curves and study of jump phenomenon.
- 7. Determination of natural frequency of a spring mass system.
- 8. Determination of torsional natural frequency of single and Double Rotor systems.
- 9. Vibration of Equivalent Spring mass system undamped and damped vibration.
- 10. Whirling of shafts Determination of critical speeds of shafts with concentrated loads.
- 11. a) Balancing of rotating masses.
 - b) Balancing of reciprocating masses.
- 12. a) Transverse vibration of Free-Free beam with and without concentrated masses.
 - b) Forced Vibration of Cantilever beam Mode shapes and natural frequencies.
 - c) Determination of transmissibility ratio using vibrating table.

			TOTAL: 45 PERIODS						
OUT	COMES:	On completion of this course, students wil	l be able to						
1.	Demonstrate	he principles of kinematics of machinery.							
2.	Demonstrate the principles of dynamics of machinery.								
3.	Use the measuring devices for dynamic testing.								

MAPPING	MAPPING OF COs, POs AND PSOs:														
	POs										PSOs				
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	3		1		1				2		3	3	1
CO2	3	2	3		1		1				2		3	3	1
CO3	3	1	3	3	1		1				2		3	3	1
Average	3.0	1.7	3.0	1.0	1.0		1.0				2.0		3.0	3.0	1.0
Round off	Round off 3 2 3 1 1 1 2 3 3 1														
3- Strong Co	3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation														

18HSC608		SOFT SKILLS AND PERSONALITY DEVELOPMENT LABORATORY	L	T	P	С					
		(BE - MECH)	0	0	3	1.5					
OBJECTIV	ES										
•	To	nelp the students to improve the listening, speaking, reading an	d wri	ting s	kills	•					
•	To	make them prepare for national and international examinations	and p	lacer	nent	s.					
•	To	nelp them to face the interviews and to improve soft skills.									
UNIT I	UNIT I LISTENING AND SPEAKING SKILLS 9										
Conversational skills (formal and informal)-making effective presentations using computers, listening/watching debates, documentaries. Listening to lectures, discussions from TV/ Radio/ Podcast.											
UNIT II	F	EADING AND WRITING SKILLS		9)						
Applications a	Reading different genres of tests ranging from newspapers to creative writing. Writing different types of Applications and complaints- Writing reviews – film appreciation- thesis writing –posture making-advertisement-magazine preparation										
UNIT III		ENGLISH FOR NATIONAL AND INTERNATIO XAMINATIONS AND PLACEMENTS	NAI		9						
International E	Englis	h Language Testing System (IELTS) - Test of English as a For	eign	Lang	uage	;					
(TOEFL) - Civ	vil Se	rvice (Language related)- Verbal Ability.									
UNIT IV	S	OFTSKILLS			9						
Motivation- er thinking.	notio	nal intelligence-Multiple intelligences career planning -creat	ive ar	nd cri	tical						
UNIT V	E	MPLOYABILITY AND CORPORATE SKILLS			9						
Discussion lea	dersl	ypes of interview, preparation for interview, mock interview. Coip and co-ordination. Time management and effective planning stress relief techniques			anag	gement					
			PE		DS						
OUTCO	ME	S: On completion of this course, students will be	able t	0							
1		Make presentations and participate in group discussions.	Make presentations and participate in group discussions.								
2		Take international examinations such as IELTS and TOEFL.									
3		Successfully answer questions in interviews.									
4		Create postures, advertisements and magazine making which are the parts of writing skills.									
5		Write film – appreciation, book review and Thesis writing which are the part of analytical thinking and creative writing									

MAPPING	MAPPING OF COs, POs AND PSOs:														
		POs											PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1					1		1	3	3						3
CO2					1		1	3	3						3
CO3					1		1	3	3						3
Average					1.0		1.0	3.0	3.0						3.0
Round off					1		1	3	3						3
3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation															

18MI	PC701	L	T	P	C			
			3	0	0	3		
OBJEC	CTIVES							
•	To unders Manufactu	tand the importance of automation in the of field machine tool uring.	based					
•	To get the systems.	knowledge of various elements of hydraulic system and design	ning n	ew h	ydraı	ulic		
•	To explore pneumatic systems and designing fluid power circuits							
•	To programme programmable logic controllers.							
•	To design	simple mechatronics systems.						

UNIT I INTRODUCTION TO AUTOMATION

8

Basic concepts of automated system -Elements of Automation - Advanced automated functions - Levels of automation - Current trends - Advantages and Limitations of Automation -CAD, CAM, CIM - Rigid automation: Part handling, Machine tools - Flexible automation: Computer control of Machine Tools and Machining Centers -Adaptive Control, Automated Material handling - Flexible fixturing - Low Cost Automation - Assembly Automation.

UNIT II HYDRAULIC SYSTEMS

9

Industrial Hydraulics: Principles of hydraulics, Hydraulic fluids, Filtration technology, Hydraulic pumps, Hydraulic valves, and hydraulic actuators, Proportional valves. Hydraulic Systems: Design considerations for hydraulic circuit, Standards in circuit diagram representation, Power pack design layout, Basic hydraulic circuits such as regenerative circuits, sequencing circuit, meter in and meter out circuit, Design of reservoir based on heat transfer considerations, Design of accumulators and intensifiers, Selection of standard components for hydraulic circuits.

UNIT III PNEUMATIC SYSTEMS AND DESIGN OF FLUID POWER CIRCUITS

10

Operational principles and application of pneumatic systems, air compressors, Pneumatic cylinders and air motors, Pneumatic valves, Design of pneumatic circuits, hydro-pneumatic, Control in pneumatic system. Design of Fluid Power Circuit: Design method consideration for sequential circuits - intuitive circuit design method - cascade method - sequential logic circuit design using KV method - compound circuit design -step counter design.

UNIT IV PROGRAMMABLE LOGIC CONTROLLERS

9

PLC Hardware- Electrical Design and Construction - Logical Sensors - Presence detection-Continuous Sensor-continuous actuators- PLC operation - Latches, Timers, Counters, Internal relays, Shift Registers, Master and Jump Controls, Analog Inputs and Outputs - PLC- programming-Programming Methods - Programming the PLC using Ladder diagram - Design Cases.

UNIT V MECHATRONICS SYSTEM DESIGN

9

Introduction and components of mechatronics, sensors, and actuators. Mechanical & Electro mechanical Systems, Pneumatics and Hydraulics, Mechatronics in Engineering Design, Traditional and mechatronics design, Applications - Pick and Place robots, Car park barriers, Bar code reader, Wind screen wiper wing stepper motor control—Traffic Control interface - IOT applications — Industry

4.0.C	ase studies: Coin	n counters, Robot walking machine.							
			TOTAL: 45 PERIODS						
OU	TCOMES:	On completion of this course, students will be	e able to						
1.	-	ensive picture of computer based automation	of manufacturing operations						
	Explain the key	y elements of automation.							
2.	2. Explain the various elements of hydraulic systems and designing new hydraulic power circuits								
3.	3. Design fluid power circuits								
4.	Understand the	PLC and develop programs using ladder log	ic.						
5.	Design the med	chatronics systems for various applications.							
TE	XT BOOKS:								
1.	Mikell P. Groo	ver, "Automation, Production Systems, and	d Computer-integrated						
	Manufacturing", Pearson Education, 5 th Edition, 2018.								
2.		'Automatic Manufacturing Systems Actua l New York, 1994.	tors, Controls and Sensors",						
3.	Hugh Jack,"Au 2005.	itomating Manufacturing Systems with PL	Cs", Free Software Foundation,						
RE	FERENCES:								
1.	W. Bolton, "Me Engineering",	echatronics: Electronic Control Systems in Pearson,2011.	Mechanical and Electrical						
2.	David W. Pesse York, 1990.	en, "Industrial Automation Circuit Design a	and Components", John Wiley, New						
3.	Rajput R. K., "Robotics and Industrial Automation", S. Chand and Company, 2008.								
4.	Rohner. P, "Automation with Programmable Logic Controllers", Macmillan /McGraw Hill, New York, 1996.								
5.	Mujumdar S.R. Education, 200	, "Oil Hydraulic Systems: Principles and M 22.	aintenance",. Tata McGraw-Hill						

MAPPING O	MAPPING OF COs, POs AND PSOs:														
		POs									PSOs				
	1	1 2 3 4 5 6 7 8 9 10 11 12									12	1	2	3	
CO1	2	2	1	1	2	1			1	2	1	2	3	2	
CO2	2	2	1	1	2	1			1	2	1	2	3	2	
CO3	2	2	1	1	2	1			1	2	1	2	3	2	
CO4	2	2	1	1	2	1			1	2	1	2	3	2	
CO5	2	2	1	1	2	1			1	2	1	2	3	2	
Average	2	2	1	1	2	1			1	2	1	2	3	2	
Round off	Round off 2 2 1 1 2 1 2 3 2														
3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation															

18M	18MPC702 DESIGN OF TRANSMISSION SYSTEMS L T P									
(Use o	of PSG I	Design data book is permitted)	3	0	0	3				
OBJE	CTIVE	S								
•	To m	ake the students to understand and design the flexible element.	ts of a	rans	miss	ion				
•	To do	esign clutch and brake system.								
•	To u	nderstand and design spur and helical gears of transmission sy	stem.							
•	To u	nderstand and design bevel and worm gears.								
•	To do	esign and develop gear box for different applications.								
UNI	[T I]	DESIGN OF FLEXIBLE ELEMENTS				9				
Design of Flat belts and pulleys - Selection of V belts and pulleys - Selection of hoisting wire ropes and pulleys - Design of Transmission chains and Sprockets.										
UNI	UNIT II FRICTION CLUTCHES AND BRAKES									
Design of plate clutches – axial clutches-cone clutches - Band and Block brakes - external shoe brakes – Internal expanding shoe brakes.										
UNI	гш (SPUR AND HELICAL GEARS				9				
strengtl strengtl	h - Factor h and we	d number of teeth-Force analysis -Tooth stresses - Dynam of safety - Gear materials - Design of straight tooth spur &h ar considerations - Pressure angle in the normal and transinology - estimating the size of the pair of crossed-helical gea	elical g verse p	gears	base	ed on				
UNI	r IV	BEVEL AND WORM GEARS				9				
estimat Termin	ing the d	ear: Tooth terminology, tooth forces and stresses, equivalent imensions of pair of straight bevel gears. Worm Gear: Menermal Capacity, Materials-forces and stresses, efficiency, early.	erits aı	nd de	emer	its –				
UNI	TV	GEAR BOX				9				
Geometric progression - standard step ratio - ray diagram, kinematic layout - design of sliding mesh and constant mesh gear box - introduction to planetary gear box.										
		TOTAL	: 45	PEF	RIO	DS				
OUT	COMES	On completion of this course, students will be able to								
1.	Design	various flexible elements of a machine.								
2.	Apply tl	ne concept of clutch and brake in new design.								
3.	Design	spur and helical gears for various applications.								
4.	Design	Bevel and worm gears of a transmission system.								
5.	Develop	and design gear box for various applications.								

TEX	T BOOKS:						
1.	Bhandari V.B,	"Design of Machine Elements", 3 rd Ed., Tata McGraw-Hill, 2010.					
2.	Shigley J.E and McGraw-Hill,	d Mischke C. R., "Mechanical Engineering Design", Sixth Edition, Tata 2003.					
3.	Robert C. Juvin edition, Wiley,	nall and Kurt M. Marshek, "Fundamentals of Machine Design", 4 th 2005.					
REF	ERENCES:						
1.	Sundararajamo 2003.	porthy T. V. Shanmugam.N., "Machine Design", AnuradhaPublications,					
2.	Orthwein W, ".	Machine Component Design", Jaico Publishing Co, 2003.					
3.		otts, Terry E. Shoup and Lee E. Hornberger, "Design of Machine Edition, Printice Hall, 2003.					
4.		alowenko, A and Laughlin, H., "Machine Design", Tata McGraw-Hill um's Outline), 2010.					
5.	Robert L. Norton, "Machine design An integrated approach", Fifth edition, Pearson education, 2001.						

MAPPING OF COs, POs AND PSOs:															
						P	Os						PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2		2	1			1	2	1	2	3	2	
CO2	3	2	2		2	1			1	2	1	2	3	2	
CO3	3	2	2		2	1			1	2	1	2	3	2	
CO4	3	2	2		2	1			1	2	1	2	3	2	
CO5	3	2	2		2	1			1	2	1	2	3	2	
Average	3	2	2		2	1			1	2	1	2	3	2	
Round off	3	2	2		2	1			1	2	1	2	3	2	
3- Strong C	3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation														

18MPC706	CAD/CAM AND MECHATRONICS LABORATORY	L	Т	P	C
		0	0	4	2

OBJECTIVES

- To help the students to develop 2D and 3D models of machine elements using modelling software.
- To prepare CNC part programming and to perform manufacturing in CNC machines.
- To apply the fundamental principles of programmable controllers to the solution of practical problems.

LIST OF EXPERIMENTS

3D GEOMETRIC MODELING

1. Introduction of 3D Modelling software

Creation of 3D assembly model of following machine elements using 3D Modelling software

- 2. Plummer Block
- 3. Screw Jack
- 4. Universal Joint
- 5. Stuffing box
- 6. Connecting rod

MANUAL PART PROGRAMMING

- (i) Part Programming CNC Machining Centre
- a) Linear Cutting.
- b) Circular cutting.
- c) Cutter Radius Compensation.

(ii) Part Programming - CNC Turning Centre

- a) Straight, Taper and Radius Turning.
- b) Thread Cutting.
- c) Rough and Finish Turning Cycle.

MECHATRONICS

- 1. Stepper motor interface.
- 2. Speed control of DC motor.
- 3. Modelling and analysis of basic hydraulic, pneumatic and electrical circuits.
- 4. PLC control of electro-pneumatic and electro-hydraulic systems.

TOTAL:60 PERIO							
OUT	COMES:	On completion of this course, students will	be able to				
1.	Develop 2D ar	nd 3D models using modelling software.					
2.	Prepare CNC p	part programming and perform manufacturing	g in CNC machines.				
3.	Apply the fund problems.	damental principles of programmable control	llers to the solution of practical				

		POs												PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2	3	1	1		2	1		1	1	2	2	1
CO2	3	2	2	3	1	1		2	1		1	1	2	2	1
CO3	3	2	2	3	1	1		2	1		1	1	2	2	1
Average	3	2	2	3	1	1		2	1		1	1	2	2	1
Round off	3	2	2	3	1	1		2	1		1	1	2	2	1

³⁻ Strong Correlation; 2 - Medium Correlation; 1 - Low Correlation

18MPR	R707	L	T	P	C						
	0 0 6 3										
OBJEC	TIVE	ES									
-	-	ovide opportunity to explore a problem or issue of particular p sional interest.	ersor	nal or	•						
		lress the problem or issue through focused study and applied on of a faculty member.	resea	rch u	nder 1	he					
-	-	nthesize and apply the knowledge and skills acquired in his/he m to real-world issues and problems.	r aca	demi	c						
•	To imp	prove ability to think critically and creatively, to solve practic	al pro	oblen	ns,						
To make reasoned and ethical decisions, and to communicate effectively.											

It is intended to start the project work early in the seventh semester and carry out both design and fabrication of a mechanical device whose working can be demonstrated. The design is expected to be completed in the seventh semester and the fabrication and demonstration will be carried out in the eighth semester.

The students in a group of 3 to 4 works on a topic approved by the head of the department under the guidance of a faculty member and prepare a comprehensive project report after completing the work to the satisfaction of the supervisor. The progress of the project is evaluated based on a minimum of three reviews in that any one review will be conducted with external examiner.

The review committee may be constituted by the Head of the Department. A project report is required at the end of the semester. The project work is evaluated based on oral presentation and the project report jointly by external and internal examiners constituted by the Head of the Department.

	TOTAL: 90 I							RIOI	DS
OU'.	FCOMES:	On compl	letion	of this course	, stude	nts will be ab	le to		
1	1 Identify the real time Engineering problems in their day to day life.								
2	Apply the know	wledge and	skill	s acquired in t	heir co	urses to a spe	cific problem	or iss	sue
3	Think critically issues and to fu		•		help s	olve these pro	ofessional or	social	
4	Refine research communication		and	demonstrate	their	proficiency	in written	and	oral
5	Take on the ch and document	_			a pres	entation in a p	professional 1	nanne	er,

MAPPING OF COs, POs AND PSOs:															
						P	Os						PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	3	2	3	1	1	2	3	3	2	3	2	3	3	2
CO2	3	3	3	3	1	1	2	3	3	2	3	2	3	3	2
CO3	3	3	3	3	2	2	2	3	3	3	3	2	3	3	2
CO4	3	3	3	3	2	2	2	3	3	3	3	2	3	3	2
CO5	2	2	2	1	2	2	3	3	3	2	3	2	3	3	2
Average	2.8	2.8	2.6	2.6	1.6	1.6	2.2	3	3	2.4	3	2	3	3	2
Round off	3	3	3	3	2	2	2	3	3	2	3	2	3	3	2
3- Strong C	3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation														

18MPR	R804	L	T	P	C						
	$egin{array}{ c c c c c c c c c c c c c c c c c c c$										
OBJEC	TIVE	ES									
		ovide opportunity to explore a problem or issue of particular p sional interest.	ersor	nal or	•						
-		lress the problem or issue through focused study and applied on of a faculty member.	resea	rch u	nder t	he					
- 1	-	nthesize and apply the knowledge and skills acquired in his/he m to real-world issues and problems.	r aca	demi	ic						
•	To imp	prove ability to think critically and creatively, to solve practic	al pro	obler	ns,						
•	To make reasoned and ethical decisions, and to communicate effectively.										

It is intended to start the project work early in the seventh semester and carry out both design and fabrication of a mechanical device whose working can be demonstrated. The design is expected to be completed in the seventh semester and the fabrication and demonstration will be carried out in the eighth semester.

The students in a group of 3 to 4 works on a topic approved by the head of the department under the guidance of a faculty member and prepare a comprehensive project report after completing the work to the satisfaction of the supervisor. The progress of the project is evaluated based on a minimum of three reviews in that any one review will be conducted with external examiner.

The review committee may be constituted by the Head of the Department. A project report is required at the end of the semester. The project work is evaluated based on oral presentation and the project report jointly by external and internal examiners constituted by the Head of the Department.

	TOTAL: 180 PER								RIO	DS
OU'.	FCOMES:	On comp	letion	of this course	, stude	nts will be ab	le to			
1	1 Identify the real time Engineering problems in their day to day life.									
2	Apply the know	wledge and	skills	s acquired in t	heir co	urses to a spe	cific	problem	or iss	sue
3	Think critically issues and to fu		•		help so	olve these pro	ofessi	ional or s	social	
4	Refine research communication		and	demonstrate	their	proficiency	in	written	and	oral
5	Take on the ch and document	_			a preso	entation in a p	orofe	ssional n	nanne	r,

MAPPING OF COs, POs AND PSOs:															
						P	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	3	2	3	1	1	2	3	3	2	3	2	3	3	2
CO2	3	3	3	3	1	1	2	3	3	2	3	2	3	3	2
CO3	3	3	3	3	2	2	2	3	3	3	3	2	3	3	2
CO4	3	3	3	3	2	2	2	3	3	3	3	2	3	3	2
CO5	2	2	2	1	2	2	3	3	3	2	3	2	3	3	2
Average	2.8	2.8	2.6	2.6	1.6	1.6	2.2	3	3	2.4	3	2	3	3	2
Round off	3	3	3	3	2	2	2	3	3	2	3	2	3	3	2
3- Strong	3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation														

18MI	PE001 INTERNAL COMBUSTION ENGINES L T P C									
1			3	0	0	3				
OBJE	CTIVES	S:								
•		e the students to understand the underlying principles of operat and components.	tion of	f diff	eren	t IC				
•	To unde	erstand the working of engine auxiliary systems.								
•	To anal	yse the combustion aspects of SI Engines.								
•	To unde	erstand the combustion aspects of CI Engines.								
•	To prov	ide knowledge on pollutant formation, control, alternate fuel et	tc.							
UNI	UNIT I SPARK IGNITION ENGINES 9									
Chambe	etion - No	Multipoint injection – Gasoline Direct Injection – Ignition rmal and Abnormal combustion-Knock - Factors affecting knock				stion				
UNIT	ΓII	COMPRESSION IGNITION ENGINES				9				
		etion Systems - Stages of combustion — Knocking — Factors ect injection systems — Combustion chambers — Fuel Spray								
	e and spra	y penetration – Air motion - Introduction to Turbocharging. OLLUTANT FORMATION AND CONTROL		vioui	_ s	9				
UNIT Pollutar Smoke a Catalyti	e and spra FIII P nt – Source and Particle Reduct	y penetration – Air motion - Introduction to Turbocharging.	Oxide	s of iters,	Nitro Sele	9 ogen, ctive				
UNIT Pollutar Smoke a Catalyti	r III P nt – Source and Particle c Reduct c cycles. E	es – Formation of Carbon Monoxide, Unburnt hydrocarbon, Culate matter – Methods of controlling Emissions – Catalytic coion and Particulate Traps – Methods of measurement – En	Oxide	s of iters,	Nitro Sele	9 ogen, ctive				
UNIT Pollutar Smoke a Catalyti Driving UNIT Alcohol	r III P nt – Source and Partice ic Reduct cycles. E r IV A l, Hydroge	POLLUTANT FORMATION AND CONTROL es – Formation of Carbon Monoxide, Unburnt hydrocarbon, Callate matter – Methods of controlling Emissions – Catalytic colon and Particulate Traps – Methods of measurement – En GR – Lean burning.	Oxide conver missic	s of iters,	Nitro Sele	9 ogen, ctive and				
UNIT Pollutar Smoke a Catalyti Driving UNIT Alcohol	r III P nt – Source and Partice ic Reduct g cycles. E r IV A l, Hydroge ies, Suitab	POLLUTANT FORMATION AND CONTROL es – Formation of Carbon Monoxide, Unburnt hydrocarbon, Coulate matter – Methods of controlling Emissions – Catalytic colon and Particulate Traps – Methods of measurement – En GR – Lean burning. LITERNATIVE FUELS en, Compressed Natural Gas, Liquefied Petroleum Gas and Biological Controlling Catalytics (Compressed Natural Gas, Liquefied Petroleum Gas and Biological Catalytics)	Oxide conver missic	s of iters,	Nitro Sele	9 ogen, ctive and				
Pollutari Smoke a Catalyti Driving UNIT Alcohol Properti UNIT Air ass Geomet	r III P nt – Source and Partice ic Reduct cycles. E r IV A l, Hydroge ies, Suitab r V R sisted Co try turboc	POLLUTANT FORMATION AND CONTROL These — Formation of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engraph — Lean burning. The Land Burning. The Land Burning is a surface of the carbon of t	Oxide: conver missic o Dies	s of iters, on no	Nitro Selectorms Vari	9 ogen, ctive and 9				
Pollutari Smoke a Catalyti Driving UNIT Alcohol Properti UNIT Air ass Geomet	r III P nt – Source and Partice ic Reduct cycles. E r IV A l, Hydroge ies, Suitab r V R sisted Co try turboc	POLLUTANT FORMATION AND CONTROL The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning. The search of Carbon Monoxide, Unburnt hydrocarbon, Carbon and Particulate Traps — Methods of measurement — Engrand Burning	Oxide onver mission o Dies Engines	s of ters, on no	Nitro Sele orms Vari ehic	9 ogen, ctive and 9				
Pollutar Smoke a Catalyti Driving UNIT Alcohol Properti UNIT Air ass Geomet NOx ad	r III P nt – Source and Partice ic Reduct cycles. E r IV A l, Hydroge ies, Suitab r V R sisted Co try turboc	OLLUTANT FORMATION AND CONTROL es – Formation of Carbon Monoxide, Unburnt hydrocarbon, Coulate matter – Methods of controlling Emissions – Catalytic control and Particulate Traps – Methods of measurement – Engraph GR – Lean burning. LITERNATIVE FUELS en, Compressed Natural Gas, Liquefied Petroleum Gas and Biomility, Merits and Demerits - Engine Modifications. RECENT TRENDS mbustion, Homogeneous Charge Compression Ignition Enhargers – Common Rail Direct Injection Systems - Hybrid Enboard Diagnostics. TOTAL:	Oxide onver mission o Dies Engines	s of ters, on no	Nitro Sele orms Vari ehic	9 ogen, ctive and 9				
Pollutar Smoke a Catalyti Driving UNIT Alcohol Properti UNIT Air ass Geomet NOx ad	r III P nt – Source and Partice ic Reduct cycles. E r IV A l, Hydroge ies, Suitab r V R sisted Co bry turboc dsorbers - C	OLLUTANT FORMATION AND CONTROL es – Formation of Carbon Monoxide, Unburnt hydrocarbon, Coulate matter – Methods of controlling Emissions – Catalytic control and Particulate Traps – Methods of measurement – Engraph GR – Lean burning. LITERNATIVE FUELS en, Compressed Natural Gas, Liquefied Petroleum Gas and Biomility, Merits and Demerits - Engine Modifications. RECENT TRENDS mbustion, Homogeneous Charge Compression Ignition Enhargers – Common Rail Direct Injection Systems - Hybrid Enboard Diagnostics. TOTAL:	Oxide onver mission o Dies Engines	s of ters, on no	Nitro Sele orms Vari ehic	9 ogen, ctive and 9				
UNIT Pollutar Smoke a Catalyti Driving UNIT Alcohol Properti UNIT Air ass Geomet NOx ad	r III P nt – Source and Partice ic Reduct g cycles. E r IV A l, Hydroge ies, Suitab r V F sisted Co bry turboc dsorbers - C COMES Analyse	DULLUTANT FORMATION AND CONTROL es – Formation of Carbon Monoxide, Unburnt hydrocarbon, Carlute matter – Methods of controlling Emissions – Catalytic control and Particulate Traps – Methods of measurement – Engraphical En	Oxide onver mission o Dies Engines	s of ters, on no	Nitro Sele orms Vari ehic	9 ogen, ctive and 9				
Pollutar Smoke a Catalyti Driving UNIT Alcohol Properti UNIT Air ass Geomet NOx ad	r III P nt – Source and Partice ic Reduct g cycles. E r IV A l, Hydroge ies, Suitab r V F sisted Co try turboc dsorbers - C COMES Analyse Evaluate	TOTAL: OLLUTANT FORMATION AND CONTROL res – Formation of Carbon Monoxide, Unburnt hydrocarbon, Catalytic control and Particulate Traps – Methods of measurement – Engraphic GR – Lean burning. LITERNATIVE FUELS ren, Compressed Natural Gas, Liquefied Petroleum Gas and Biomility, Merits and Demerits - Engine Modifications. RECENT TRENDS mbustion, Homogeneous Charge Compression Ignition Engraphics – Common Rail Direct Injection Systems - Hybrid Dinboard Diagnostics. TOTAL: On completion of this course, students will be able to the combustion characteristics of SI engine.	Oxide: onverimission o Dies Engines Electr	s of ters, on no	Nitro Sele orms Vari ehic	9 ogen, ctive and 9				

5.	Apply the lates	Apply the latest technologies of engine system.										
TEX	T BOOKS:											
1.	Ganesan, "Inte	ernal Con	nbustion En	gines",2 nd Editio	on, TMH, 2	002.						
2.	Ramalingam. Publications, 20		"Internal	Combustion	Engine	Fundamentals",Scitech						
3.	S. S. Thipse, "I	Internal (Combustion	Engines", Jaico	Publishing	g House, 2010.						
REF	ERENCES:											
1.	Mathur. R.B. at 2007.	nd R.P. Si	harma, "Inté	ernal Combustio	n Engines	",DhanpatRai& Sons						
2.	Duffy Smith, "A	Auto Fuel	l Systems", T	The Good Heart	Willcox Co	ompany, Inc., 1987.						
3.	Eric Chowenitz	, "Autom	obile Electr	onics", SAE Pul	olications,	1995						
4.	H. N. Gupta, "F Learning Pvt. I			rnal Combustion	n Engines'	, 2 nd Edition, PHI						
5.	Shyam K. Agra	wal "Inte	ernal Combu	stion Engines",	пежадери	blishers, 2006.						

MAPPIN	G OF	CO	s, PC	s AN	ND P	SOs:									
	POs										PSOs				
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	1											2		
CO2	3	2											2		
CO3	2	1				3							1		3
CO4	2	1				3							2		3
CO5	2	1				3							2		3
Average	2.2	1.2				1.8							1.8		1.8
Round off	2	1				2							2		2
3- Strong C	orrela	ation;	2 - M	lediun	n Cor	relati	on; 1	- Lov	v Cor	relatio	n	•	1		1

18MPE002		MECHATRONICS SYSTEMS	L	T	P	\mathbf{C}	
			3	0	0	3	
OBJEC	TIVES	5:					
	_	rt knowledge about the various elements and techniques involonics systems.	ved in	l			
• '	To unde	rstand the working of 8085 microprocessor and 8051 microcol	ntrolle	er.			
• '	To provi	de knowledge on programmable peripheral interface.					
• '	To unde	rstand the working of programmable logic controller.					
	To provi applicati	de knowledge on actuators and to design mechatronic systems on.	s for a	give	en		
UNIT	I II	NTRODUCTION				9	
Transduce	ers: Stati	Emerging areas of Mechatronics – Classification of Mechatric and dynamic Characteristics of Sensor, Potentiometers – L'gauges – Eddy current sensor – Hall effect sensor – Temperat	VDT -	- Ca	pacit	ance	
UNIT	II N	MICROPROCESSOR AND MICROCONTROLL	ER			9	
		chitecture of 8085 – Pin Configuration – Addressing Modes – f 8085 – introduction to 8051, Arduino, Case studies.	Instru	ction	set,		
UNIT I	NIT III PROGRAMMABLE PERIPHERAL INTERFACE						
		chitecture of 8255, Keyboard interfacing, LED display –interfacemperature Control – Stepper Motor Control – Traffic Control	_		C an	d	
UNIT I	UNIT IV PROGRAMMABLE LOGIC CONTROLLER						
		sic structure – Input and output processing – Programming – Nand internal relays – Data handling – Selection of PLC.	Inem	onics	s –		
UNIT	V A	CTUATORS AND MECHATRONIC SYSTEM D	ESI	GN		9	
Disadvant concepts	tages. D - Case s	r and Servo motors — Construction — Working Principle resign process-stages of design process — Traditional and Metudies of Mechatronics systems — Pick and place Robot — Etic car park barrier.	I echat	ronic	es de	esign	
		TOTAL:	45 P	ER	IOD	S	
OUTCO)MES:	On completion of this course, students will be able to					
C		the interdisciplinary applications of Electronics, Electrica r Systems for the Control of Mechanical, Electronic Sygy.					

3. Discuss Programmable Peripheral Interface, Architecture of 8255 PPI, and various device interfacing. Explain the architecture, programming and application of programmable logic controllers 4. to problems and challenges in the areas of Mechatronic engineering. 5. Discuss various Actuators and Mechatronics system using the knowledge and skills acquired through the course and also from the given case studies. **TEXT BOOKS:** Bolton, "Mechatronics", Printice Hall, 2008. 1. 2. Ramesh S Gaonkar, "Microprocessor Architecture, Programming, and Applications with the 8085", 5th Edition, Prentice Hall, 2008. Bradley D.A, Dawson D, Buru N.C and Loader A.J, "Mechatronics", Chapman and Hall, 3. 1993. **REFERENCES:** Michael B.Histand and Davis G.Alciatore, "Introduction to Mechatronics and 1. Measurement systems", McGraw Hill International edition, 2007. 2. Smaili.A and Mrad.F , "Mechatronics Integrated Technologies for Intelligent Machines", Oxford University Press, 2007. 3. DevadasShetty and Richard A. Kolk, "Mechatronics Systems Design", PWS publishing company, 2007. 4. Krishna Kant, "Microprocessors & Microcontrollers", Prentice Hall of India, 2007. 5. Clarence W, de Silva, "Mechatronics" CRC Press, First Indian Re-print, 2013.

	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	1											2		
CO2	3	2											2	1	
CO3	2	1											2	2	
CO4	3	1											2	2	
CO5	3	1											2	2	
Average	2.6	1.2											2		
Round off	3	1											2	1.4	

18Ml	PE003	E003 MICROPROCESSORS IN AUTOMATION L T P								
				3	0	0	3			
OBJE	CTIVES	S:								
•	To help	the students to understand the fundamentals of micr	roprocessoi	rs.						
•	To learn	various cycles and interfacing methods.								
•	To get k	nowledge on assembly language programming.								
•	To Fam	iliarise different types of convertors and data commu	unication n	netho	ds.					
•	To explo	ore digital control techniques.								
UNI	T I F	UNDAMENTALS OF MICROPROCESS	SORS				9			
Sequent	tial logic	codes, digital electronics: Logic Gates, combination circuits design: Counters, Shift registers. Introductions, ALU, Bus systems, Timing and control signals.		•	-	-				
UNI	LII C	CYCLES AND INTERFACING					9			
Machine	•	nstruction cycle and timing states, instruction timing	g diagrams	, Men	nory	•				
UNIT	T III A	SSEMBLY LANGUAGE PROGRAMMI	NG				9			
Interrup	ots, Interr	es, Instruction set, simple programs in 8085; Coupt structure, Multiple Interrupt requests and the er; Interfacing peripherals: Programmable peripheral	eir handli	ing, F	rogr					
UNIT	TIV C	CONVERTORS AND DATA COMMUNIC	CATION	ſ			9			
segment	ts LED	og to Digital Converter & Digital to Analog c display systems, Stepper Motor Control, Data (8251), Programmable Timers (8253); 8086/808	Communic	ation:	Sei	ial	Data			
UNI	$\Gamma V \mid D$	OIGITAL CONTROL					9			
		igital Control: Sampling theorem, Signal conversion I Filters, Implementation of Digital Algorithm.	and Proce	essing,	Z					
		Т	OTAL:	45 P	ER	IOD	S			
OUTC	COMES	On completion of this course, students will be ab	le to							
1.	Understa	nd the fundamentals of microprocessors.								
2.	Analyse	various cycles and interfacing methods.								
3.	Perform	assembly language programming.			_	_				
4.	Design d	ifferent types of convertors and data communication	n methods.							
5.	Explore	various digital control techniques.								

TEX	T BOOKS:	
1.	Nagoorkani, "I Hill Educatinp	MICROPROCESSORS & MICROCONTROLLERS", Tata McGraw vt.Ltd. 2012.
2.	Godse A. P., "1 (2016)	Microprocessors & Microcontrollers", TECHNICAL PUBLICATION
3.	A K Guptha, "2013.	Industrial Automation and Robotics", Laxmi Publications-New Delhi,
4.	Bradley D.A, I 1993.	Dawson D, Buru N.C and Loader A.J, "Mechatronics", Chapman and Hall,
REF	ERENCES:	
1.		tand and Davis G.Alciatore, "Introduction to Mechatronics and systems", McGraw Hill International edition, 2007.
2.	DevadasShetty company, 2007	and Richard A. Kolk, "Mechatronics Systems Design", PWS publishing
3.	Krishna Kant,	"Microprocessors & Microcontrollers", Prentice Hall of India, 2013
4.	S. G. Tzafe Control",Sprin	estas, "Microprocessors in Signal Processing, Measurement and ager, 2011.
5.	John Crisp, "In	troduction to Microprocessors and Microcontrollers", Elsevier, 2004

						P	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3												2		
CO2	3	1								2			2		
CO3	3	1								2			2	1	
CO4	3	1								2			2	1	
CO5	2	3											3	2	
Average	2.8	1.2											2.2	0.8	
Round off	3	1								1.2			2	1	

18M	PE004	PROCESSING OF COMPOSITE MATERIALS	L	T	P	С
			3	0	0	3
OBJE	CTIVES	:	•			
•	To make composi	the students to understand different processing methods and tes.	variou	ıs typ	pes o	f
•	To get k	nowledge on processing of polymer matrix composites.				
•	To explo	ore various types of metal matrix composites and their process	ing te	chni	ques.	

- To familiarise ceramic matrix composites and special composites.
- To study the mechanics used to analyse the composites.

UNIT I INTRODUCTION TO COMPOSITES

Fundamentals of composites – need for composites – enhancement of properties – classification of composites - Matrix-Polymer matrix composites (PMC), Metal matrix composites (MMC), Ceramic matrix composites (CMC) - Reinforcement - particle reinforced composites, Fibre reinforced composites. Applications of various types of composites. Fibber production techniques for glass, carbon and ceramic fibres. Introduction to Nano composites.

UNIT II POLYMER MATRIX COMPOSITES

Polymer resins - thermosetting resins, thermoplastic resins - reinforcement fibres - rovings woven fabrics – non woven random mats – various types of fibres. PMC processes – hand layup processes – spray up processes – compression moulding – reinforced reaction injection moulding – resin transfer moulding - Pultrusion - Filament winding - Injection moulding. Fibre reinforced plastics (FRP), Glass Fibre Reinforced Plastics (GFRP). Laminates- Balanced Laminates, Symmetric Laminates, Angle Ply Laminates, Cross Ply Laminates.-applications of PMC in aerospace, automotive industries.

UNIT III METAL MATRIX COMPOSITES

Characteristics of MMC, various types of metal matrix composites, alloy vs. MMC, advantages of MMC, limitations of MMC, Reinforcements – particles – fibres. Effect of reinforcement – volume fraction – rule of mixtures. Processing of MMC – powder metallurgy process – diffusion bonding - stir casting - squeeze casting, a spray process, Liquid infiltration In-situ reactions-Interfacemeasurement of interface properties- applications of MMC in aerospace, automotive industries.

CERAMIC MATRIX COMPOSITES AND SPECIAL **UNIT IV** COMPOSITES

9

Engineering ceramic materials - properties - advantages - limitations - monolithic ceramics need for CMC – ceramic matrix – various types of ceramic matrix composites- oxide ceramics – non oxide ceramics - aluminium oxide - silicon nitride - reinforcements - particles- fibreswhiskers. Sintering – Hot pressing – Cold isostatic pressing (CIPing) – Hot isostatic pressing (HIPing). Applications of CMC in aerospace, automotive industries- Carbon /carbon composites – advantages of carbon matrix - limitations of carbon matrix carbon fibre - chemical vapour deposition of carbon on carbon fibre perform. Sol-gel technique- Processing of Ceramic Matrix composites.

UNIT V MECHANICS OF COMPOSITES

9

Lamina Constitutive Equations: Lamina Assumptions – Macroscopic Viewpoint. Generalized Hooke's Law. Reduction to Homogeneous Orthotropic Lamina – Isotropic limit case, Orthotropic Stiffness matrix (Qij), Definition of stress and Moment Resultants. Strain Displacement relations. Basic Assumptions of Laminated anisotropic plates. Laminate Constitutive Equations – Coupling Interactions, Balanced Laminates, Symmetric Laminates, Angle Ply Laminates, Cross Ply Laminates. Laminate Structural Moduli. Evaluation of Lamina Properties from Laminate Tests. Quasi Isotropic Laminates. Determination of Lamina stresses within Laminates.

			TOTAL: 45 PERIODS
OUT	COMES:	On completion of this course, students will b	e able to
1.		d different techniques to process different type of each process.	s of composites and know the
2.	Learn the 1	processing techniques of polymer matrix comp	oosites.
3.	Understan	d various types of metal matrix composites and	d their processing techniques.
4.	Get knowl composite	edge on processing techniques of ceramic mats	rix composites and special
5.	Use of Ma Laminates	thematical techniques to predict the macroscop.	pic properties of different
TEX	т воок	S:	
1.	M. Balasul May 2017	bramanian, "Composite Materials and Proce	essing", CRC Press; 1 edition (16
2.	Chawla K.	K., "Composite materials", Second Edition,	Springer – Verlag, 1998.
3.		F. L. and Rawlings R. D., "Composite Materia, Chapman and Hall, London, England, 1994.	als: Engineering and Science",
REF	ERENCE	S:	
1.	G. Piatti, " (1978).	Advances in composite materials", Applied	Science Publishers Ltd., London,
2.		Kaw, "Mechanics of Composite Materials", Tition (2006).	Γaylor & Francis- india; Second
3.	Srinivasan	K., "Composite Material: Production Prop	perties Testing", Narosa (2009).
4.		tiev and E.V. Morozov, "Mechanics and Anacience Ltd, (2001).	lysis of Composite Materials",
5.	K.K. Chav (1993).	vala, "Ceramic matrix composites", Chapma	n & Hall, London, 1st ed.,

	POs													PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	2												2			
CO2	2									2			3			
CO3	3	1					1			2			3			
CO4	3	1					1			2			3			
CO5	3	1					1			1			3			
Average	2.8	0.6					0.6			1.4			2.8			
Round off	3	1					1			1			3			

³⁻ Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation

18MI	PE005		COMPUTER AIDED DESIGN	L	T	P	C
				3	0	0	3
OBJE	CTIVE	S:					
•	To ma	ake the	e students to understand fundamentals of computer graph	ics.			
•	To ga	in kno	wledge on geometric modelling techniques.				
•	To lea	arn var	ious visual realism techniques and algorithms.				
•	To fa	miliari	se assembly modelling.				
•	To un	dersta	nd various cad standards.				
UNI	T I F	UND	AMENTALS OF COMPUTER GRAPHICS				9
CAD sy	stem arch	nitectur	process- sequential and concurrent engineering- Computer re- Computer graphics – co-ordinate systems- 2D and 3D res - Line drawing -Clipping- viewing transformation.			_	
UNI	L II C	GEON	METRIC MODELLING				9
Techniq	ues for si	urface odeling	rves- Hermite curve- Bezier curve- B-spline curve modeling – surface patch- Coons and bicubic patches- Eg techniques- CSG and B-rep.				pline
UNIT			AL REALISM				9
			Solid removal algorithms – shading – colouring – compu	iter ai	nima	tion.	
UNIT			MBLY OF PARTS				9
			interferences of positions and orientation – tolerance anal mechanism simulation and interference checking.	lysis-	mass	3	
UNI	ΓΥ	CAD S	STANDARDS				9
images- Open G		ibrary		LSet	c		
		1	TOTAL:	45]	PER	RIO!	DS
OUTC	COMES	: On	completion of this course, students will be able to				
1.			damentals computer graphics.				
2.			geometric modelling techniques.				
3.			alism techniques and hidden line, surface and solid remo	val al	gorit	thms	•
4.			embly modelling techniques and tolerance analysis.				
5.	Explore	various	s cad standards.				
TEX	r Bool	XS:					

1.	Zeid Ibrahim, ' International E	'CAD/CAM Theory and Practices ", 2 nd Edition, McGraw Hill dition, 2009.
2.		an and S. Subramanyan, Raju. V., "CAD/CAM/CIM" New Age) Ltd, New Delhi – 2002.
3.	Mikell P. Groo Education, Nev	ver, Emory W. Zimmers, Jr. "CAD/CAM", 5 th Impression Pearson v Delhi, 2008.
REF	ERENCES:	
1.		mann and Robert F.Sproul "Principles of Computer Graphics", McGraw ingapore, 1989.
2.		non and Jimmie Browne "CAD/CAM Principles", "Practice and g management" Second Edition, Pearson Education, 1999.
3.	David Bedwort Delhi,1998	th, "Computer Integrated Design and Manufacturing", TMH, New
4.	Foley, Wan Da Pearson Educa	m, Feiner and Hughes - '' Computer graphics principles & practice'' ation - 2003.
5.	Donald Hearn	and M. Pauline Baker, "Computer Graphics", Prentice Hall Inc., 2002.

	POs												PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3												3		
CO2	3												3		
CO3	3												3		
CO4	3												3		
CO5	3												3		
Average	3												3		
Round off	3												3		

)06				OP	ERAT	ΓION	NS R	ESE	ARC	Ή			L	T	P	\mathbf{C}
														3	0	0	3
OBJECTIV	VES:												•				
•	To pr	ovi	ide s	uden	ts the	knowle	edge	of opt	imiza	tion to	echn	iques	and ap	proa	ches		
•	To en	abl	le the	m to	unde	rstand t	the va	arious	transp	ortat	ion a	and ne	twork	mod	els.		
•	To un	nde	erstan	d the	diffe	rent Inv	vento	ry moo	dels.								
•	To stu	udy	y the	vario	us qu	eueing	mode	els and	l its a _l	pplica	tion	s.					
•	To un	ıde	erstan	d the	diffe	rent dec	cision	n mode	els and	d app	ly th	em fo	r optir	nizat	ion.		
UNIT I	I	LIN	NEA	$\mathbf{R} \mathbf{N}$	1OD	ELS											9
Introduction t method – Sim	-						_		_			cal Fo	rmula	tion -	– Gra	aphic	cal
UNIT II	Γ	ΓR	RAN	SPO	RTA	TION	N AN	ND N	ETV	VOR	K	MOD	ELS				9
Transportation – Minimal space Critical path s	anning t	tree	e - N				_		-								
			· ·														
UNIT II	I I	N		TO	RY I	MODI	ELS	}									9
UNIT II Inventory mo models – Stoo	dels – V	Var	VEN	Costs	and (Concep	ots – l	EOQ -	- Dete	rmini	istic	inven	tory m	odel	s – P	rodu	
Inventory mo	dels – V	/ari	VEN	Costs	and (Concep	ots – l er stoc	EOQ -	- Dete	rmini	istic	inven	cory m	odel	s – P	rodu	
Inventory mo models – Stoo	dels – Vehastic I	Vari Inv QU Que	VEN rious vento JEU euein on in	Costs ry mo EIN g sys out —	s and odels - G M tems	Concep - Buffe ODEI and str	ots – ler stoc LS	EOQ - ck. res - N	Votati	on pa	ram	eter –	Single	e ser	ver a	and n	ction 9 nulti-
Inventory mo models – Stoo UNIT IV Queueing mo server models	dels – Vehastic I dels - Centre dels - Cent	Vari Inv Que sso cin	VEN rious vento JEU euein on inj ng mo	Costs ry mo EIN g sys out — odels.	s and odels - G M tems Expo	Concep - Buffe ODEI and str	ots – ler stoc LS ructur l serv	EOQ - ck. res - N	Votati	on pa	ram	eter –	Single	e ser	ver a	and n	ction 9 nulti-
Inventory mo models – Stoo UNIT IN Queueing mo server models Simulation –	dels – Vehastic la dels – Central de	Vari Inverse Que Que Ssso cin DE Gar	VEN rious vento VEU eueimon injug mo	Costs ry mo g sys out — odels. ION heory	s and odels - G M tems Expo I MC	Concep - Buffe ODEI and structure on ential DDEL wo per on - R	LS ructur l serv S erson Replace	EOQ - ck. res - N vice - zero cemen	Notati Cons sum	on pa	aram rate	eter – servic	Single – In	e ser finite	ver a	and noulat	9 nulti- ion –
Inventory mo models – Store UNIT IV Queueing mo server models Simulation – UNIT V Decision models solution – Line	dels – Vehastic la dels – Central de	Vari Inverse Variable Que Que Ssso cin DE Garabert Garabert Garabe	VEN rious vento VEU eueimon injug mo	Costs ry mo g sys out — odels. ION heory	s and odels - G M tems Expo I MC	Concep - Buffe ODEI and structure on ential DDEL wo per on - R	LS ructur l serv S erson Replace	EOQ - ck. res - N vice - zero cemen	Notati Cons sum	on pa	aram rate	eter – service Graph odels	Single – In	e ser finite oluti on	ver a	and moulate	9 nulti- ion – 9 braic ife –
Inventory mo models – Store UNIT IV Queueing mo server models Simulation – UNIT V Decision models solution – Line	dels – V dels - C dels - C Sequence dels – C	Variation Variat	VEN rious vento JEU euein on inj ng mo ECIS ame ramm / Mu	Costs ry mo g sys out — odels. ION theory ing so	s and odels - G M etems Expo I MC y - T solution	Concep - Buffe ODEI and structure on ential DDEL wo per on - R	LS ructur l serv S erson Replace	EOQ - ck. res - N vice - zero cemen nique.	Notati Cons sum t mod	on pa tant r game:	ram rate s – M	eter – service Graph odels TO	Single – In	e ser finite oluti on	ver a	and moulate	9 nulti- ion – 9 braic ife –
Inventory mo models – Stood UNIT IV Queueing moserver models Simulation – UNIT V Decision mos solution – Lin Economic life	dels – V dels - C dels - C Sequence dels – C	Variante de la constante de la	VEN rious vento VEU euein on inj ng mo CCIS	Costs ry mo g sys out — odels. ION theory ing s lti van	s and odels - G M tems Expo I MC y - T solution	Concep Buffe ODEI and str onential DDEL wo pe on — R search of this	LS ructur l serv S erson Replace techn	EOQ - ck. res - N vice - zero cemen nique.	Notati Cons sum ; t mod	on pa tant r games dels -	ram rate s – M	eter – service Graph odels TO	Single – In	e ser finite oluti on	ver a	and moulate	9 nulti- ion – 9 braic ife –
Inventory mo models – Stood UNIT IV Queueing moserver models Simulation – UNIT V Decision mos solution – Lin Economic life OUTCOM 1. In	dels – V chastic l dels – C s – Pois Sequence dels – C dels – C dels – C dels – C des – Sing	Variante Var	VEN rious vento JEU euein on inj ng mo ECIS ame ramm / Mu On o	Costs ry mo g sys out — odels. ION theory ing s lti van comp	s and odels - G M tems Expo I MC y - T solution itable	Concep Buffe ODEI and str onential DDEL wo pe on — R search of this inear pr	LS ructur l serv S erson Replace techn cour	EOQ - ck. res - N vice - zero cemen nique. rse, stu	Notati Cons sum ; t mod	on pa tant r games dels -	ram rate s – M be al	Graphodels TO'	Single – In	oluti	ver a por on- servi	Alge	9 nulti- ion – 9 braic ife –
Inventory mo models – Stood UNIT IV Queueing moserver models Simulation – UNIT V Decision mode solution – Lin Economic life OUTCOM 1. In 2. A	dels – Vehastic I dels – Vehastic I dels – Ces – Pois Sequence dels – Ces – Sing MES: nterpret	Que Que cin DE Garage it the me c	VEN rious vento JEU euein on inj ng mo CCIS ame ramm / Mu On one conce	Costs ry mo g sys out — odels. ION theory ing s lti van comp	s and odels - G M tems Expo I MC y - T solution riable CPM	Concep Buffe ODEI and str onential DDEL wo pe on — R search of this inear pr	LS ructur l serv S erson Replace techn rogra Γ and	res – Novice – zero cemen nique.	Notati Cons sum ; t mod	on pa tant r games dels -	ram rate s – - M be al	eter – service Graphodels TO' ble to	Single – In	oluti on : 45	ver a e por on- servi	Algeice 1	9 nulti- ion – 9 braic ife –
Inventory mo models – Stood UNIT IV Queueing moserver models Simulation – UNIT V Decision modes solution – Line Economic life OUTCOM 1. In 2. A 3. E	dels – Vehastic I dels – Vehastic I dels – Ces – Pois Sequence dels – Ces – Sing MES: hear Pro hear	Que Que Garage Garage The Control of	VEN rious vento JEU euein on inj ng mo CCIS ame ramm / Mu On one conce	Costs ry mo g sys odels. ION theory ing s lti van comp. comp. cepts	s and odels - G M tems Expo I MC y - T solution riable CPM of diff	Concep-Buffe ODEI and stronential ODELS Two per on — R search of this inear pr ferent Ir	LS ructur l serv S erson Replace techn rogra Γ and nvent	res - Novice - zero cemen nique. rse, stu umming l seque tory m	Notati Cons sum s t mod	on pa tant r games dels -	s - M be al	Graphodels TO' Dle to plicat	Single – In	oluti on : 45	ver a e por on- servi	Algeice 1	9 nulti- ion – 9 braic ife –

TEXT B	OOKS:	
1.	Sharma, S	5. D. "Operations Research", 2 nd Ed., kedarNath Ram Nath& Co. Meerut, 1998.
2.		ta, D. S. Hira, "Problems in Operations Research (Principles and)", S. Chand & Co. Ltd., 2003.
3.	TahaHan	ndy A., "Operations Research", 8 th Ed., Prentice Hall of India Pvt. Ltd., 2007.
REFER	ENCES:	
1.		Yenkatakrishnan. S. "Operations Research" (Principles and Problems) , 5 th Yeerthi Publishing House Pvt. Ltd., 1996.
2.		hillips, Ravindren, A and James Solberg ," Operations Research" , 2 nd Edition, by & Sons, 1987.
3.	Hillier an	d Libeberman, "Operations Research" , Holden Day, 1986
4.	Budnick F Irwin, 199	7. S., "Principles of Operations Research for Management", 2 nd Richard D 00.
5.	Panneerse	elvam. K, "Operation Research" , 2 nd Edition, Prentice Hall of India, 2006.

						POs								PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3												3		
CO2	3												3		
CO3	3					1							3		
CO4	2					2							3		3
CO5	2					3							3		3
Average	2.6					0.8							3		1.2
Round off	3					1							3		1

18MI	PE007	THEORY OF METAL CUTT	ING	L	T	P	С
				3	0	0	3
OBJE	CTIVES	5:					
•	To make	the students to understand the concept and bas	sic mechanics o	f meta	al cu	tting	Ţ .
•	To unde	rstand the nomenclature of standard machine to	ools.				
•	To unde	rstand the various thermal aspects of cutting flu	iids.				
•	To analy	se the cutting tool materials, tool life and tool	wear.				
•	To desig	n the cutting tools.					
UNI	TI O	RTHOGONAL CUTTING					9
breakers Merchan	s - Expres nt Upper b	chining fundamentals – Metal Cutting - Chip sion for Shear plane angle - Cutting force and cound solution - Lee and Shaffer Lower bound 1 Strain in the chip - Energy consideration in m	l velocity relate solution - Oxlo	ionshi	p -]	Erns	t and
UNIT	O II T	BLIQUE CUTTING					9
	-	flow - Normal, Velocity and Effective Rake and tios in oblique cutting - Shear angle and Veloc	-	-			
UNIT	TIII	HERMAL ASPECTS AND CUTTING	G FLUIDS				9
tool tem		in machining - Experimental determination an Cutting fluids - Effects of cutting fluid - Fund ng Fluids.	•				_
UNIT		UTTING TOOL MATERIALS, TOO ÆAR	L LIFE AN	D TC	OOI		9
	-	nents of tool materials – development of tool m Economics of metal machining - Theory of Cha		wear a	ınd 🛚	Γool	life
UNI	$\Gamma V \mid D$	ESIGN OF CUTTING TOOLS					9
Nomeno Milling		Single point and Multi point cutting tools - Des	ign of Turning	tool, l	Drill	s and	d
			TOTAL:	45 P	ER	OI	S
OUTC	COMES:	On completion of this course, students will be	e able to				
1.	Applying	the orthogonal metal cutting theory in enginee	ring.				
2.	Evaluatin	g the oblique metal cutting theory in engineering	ng.			_	
3.	Learn He	at distributions in machining and cutting fluids	•				
4.	Understa	nd the essential requirements of tool material an	nd its life.				
5.	Design th	e cutting tools for metal removal process.					

TEXT	BOOKS:	
1.	Bhattacharyya Calcutta, 1984.	A., "Metal Cutting Theory and Practice", Central Book Publishers,
2.		khon G. S., "Fundamentals of Metal Cutting and Machine Tools", New nal (P) Limited, 1995.
3.	Shaw M C., "N	Metal Cutting Principles", Oxford Press, 1984.
REFI	ERENCES:	
1.	David A. Steph 2006.	enson, John S. Agapio, "Metal Cutting Theory and Practice", CRC Press,
2.	Armarego E.J.	A., Brown R.H., ''The Machining of Metals'', Prentice Hall Inc., 1969.
3.	•••	royd, Knight W.A., ''Fundamentals of Machining and Machine Tools'', New York, 1989.
4.	Rodin P., "Des	ign and Production of Cutting Tools", MIR Publishers, 1968.
5.	P C Sharma, ". Delhi 2008.	A Textbook of Production Engineering", S. Chand & Company Ltd. New

MAPPIN	G OI	F CO	s, PO)s Al	ND P	SOs:									
						P	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2												3		
CO2	3					2							3		
CO3	3												3		
CO4	3												3		
CO5	3					3							3		
Average	2.8					1							3		
Round off	3					1							3		
3- Strong C	orrel	ation;	2 - N	Iediu	m Coi	relati	ion; 1	- Lo	w Coi	relati	on	ı	1	1	

18MF	PE008		WELDIN	NG TE	CHNC	LOGY	Y		L	T	P	C
									3	0	0	3
OBJE	CTIV	S:										
•	To	ake the stud	dent to under	rstand th	ne basics	of weld	ling t	echnolo	ogy.			
•	То	nderstand th	e basic conc	cepts of	welding	metalluı	rgy.					
•	То	nderstand w	elding techn	niques fo	or variou	s materia	als.					
•	То	arn the vari	ous advance	ed weldir	ng proce	sses.						
•	То	quire the k	nowledge of	testing	of weldr	nents.						
UNI	TI	GAS AND	ARC WI	ELDIN	IG PRO	OCESS	SES					9
Shielded	d metal	rc welding	Air-acetylene , Submerged ocesses - adv	d arc we	elding, 7	ΓIG & N	ИIG	weldin	g, Plas			_
UNI	ΓII	RESISTA	NCE WE	LDIN	G PRO	CESSI	ES					9
-	ion wel		g, Projectio h frequency		_							_
UNIT	III	SOLID ST	TATE WE	ELDIN	G PRO	CESS	ES					9
	, Roll		nding, Explo d Hot pres		_			_			_	_
UNIT	IV	THER V	WELDIN(G PRO	CESSI	ES						9
stir weld	ding, U	lerwater we	drogen weld ding, Weld and explosi	ling auto	mation		_				_	
UNIT	V		OF WELI FOF WEI		,	ELDA	BII	LITY	AND			9
	•	_	Heat affecte ctive testing			bility of	diffe	erent m	aterial	s - W	eld de	fects
]	OTA	L:4	5 PE	RIO	DS
OUTC	COME	: On com	pletion of th	is cours	e, studer	nts will b	oe ab	le to				
1.	Learn	d Compare	different ty	pes of W	Velding 1	processe	s.					
2.	Analys	the princip	les of resista	ance wel	ding pro	cesses.						
3.	Unders	and the con	cept of solid	state we	elding p	rocess.						
4.			lity and weld									
5.	Learn	fferent testi	ng methods	for weld	dment.							

TEX	T BOOKS:	
1.	Parmer R.S., "NewDelhi, 200	Welding Engineering and Technology", 1st edition, Khanna Publishers, 8.
2.	Parmer R.S., "1992.	Welding Processes and Technology", Khanna Publishers, New Delhi,
3.		Yelding and welding Technology" , Tata McGraw Hill Publishing Co., i, 34 th reprint, 2008.
REF	ERENCES:	
1.	Schwartz M.M.	"Metals Joining Manual". McGraw Hill Books, 1979.
2.	Tylecote R.F. " London,1968.	The Solid Phase Welding of Metals". Edward Arnold Publishers Ltd.
3.	Nadkarni S.V. 2005.	"Modern Arc Welding Technology", 1st edition, Oxford IBH Publishers,
4.	Christopher Do	avis. "Laser Welding- Practical Guide".Jaico Publishing House, 1994.
5.	Davis A.C., "T Cambridge,199	the Science and Practice of Welding", Cambridge University Press,

MAPPIN	G OI	F CO	s, PC)s A	ND P	SOs:	}								
						P	Os							PSOs	}
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2										3	2	
CO2	3	2	1										3	2	
CO3	3	2	1										3	2	
CO4	3	2	3										3	3	
CO5	3	2	1										3	2	
Average	3.0	2.0	1.6										3.0	2.2	
Round off	3	2	2										3	2	
3- Strong C	orrel	ation;	; 2 - N	Iediu	m Co	rrelat	ion; 1	-Lo	w Co	rrelati	ion			ı	

18M	PE009	REFRIGERATION AND AIR CONDITIONING	L	Т	P	C
			3	0	0	3
OBJE	CTIVE	S:				
•	To mak Operati	te the students to understand vapour compression and vapour at on.	bsorpt	ion s	ystei	m
•	To anal	yse the refrigeration cycles and methods for improving Perforn	nance	•		
•	To acqu	uire the knowledge on components of refrigeration systems.				
•	To desi	gn air conditioning systems using cooling load calculations.				
•	To expl	lore the application of refrigeration and air conditioning system	ıs.			
UNI	TII	NTRODUCTION				9
		Refrigeration - Unit of Refrigeration and C.O.P. – Ideal cycles-laties – Classification - Nomenclature - ODP & GWP.	Refrig	geran	ts	
UNI	T II V	VAPOUR COMPRESSION REFRIGERATION SY	YSTI	EM		9
Conden	iseis, Exp	ansion devices, Evaporators.				
UNIT Workin refriger	ΓΙΙΙ (ag princip tation- Ej	DTHER REFRIGERATION SYSTEMS Deles of Vapour absorption systems and adsorption cooling systems refrigeration systems. Thermoelectric refrigeration-				9 n je
UNIT Workin refriger	g princip ation- Ej ic -Vorte	OTHER REFRIGERATION SYSTEMS bles of Vapour absorption systems and adsorption cooling systems refrigeration systems.	Air r			9 n je
Workin refriger Magnet UNIT	g princip ation- Ej ic -Vortes FIV I ies of moon, Relandodynamic	OTHER REFRIGERATION SYSTEMS bles of Vapour absorption systems and adsorption cooling systems refrigeration systems. Thermoelectric refrigeration- ax and Pulse tube refrigeration systems.	Air r SES peratu bulb	efrig re, I ten	Pegre apera	9 m jer on -
Workin refriger Magnet UNIT	g princip ation- Ej ic -Vortex FIV I ies of moon, Reladynamic es, mixing	DTHER REFRIGERATION SYSTEMS The soft Vapour absorption systems and adsorption cooling systems and Pulse tube refrigeration systems. PSYCHOMETRIC PROPERTIES AND PROCESS Dist Air-Gibbs Dalton law, Specific humidity, Dew point temperative humidity, Enthalpy, Humid specific heat, Wet wet bulb temperature, Psychometric chart, P	Air r SES peratu bulb	efrig re, I ten	Pegre apera	9 m je on - 9 ee ot ture
Workin refriger Magnet UNIT Propert saturation Thermosprocess UNIT Air cor Solar Reselection calculate distribution	g princip ation- Ej ic -Vorter FIV I ies of moon, Rela odynamic es, mixing adiation- in-fresh ation of settion system.	DITHER REFRIGERATION SYSTEMS Deles of Vapour absorption systems and adsorption cooling systems refrigeration systems. Thermoelectric refrigeration and Pulse tube refrigeration systems. PSYCHOMETRIC PROPERTIES AND PROCESS Dist Air-Gibbs Dalton law, Specific humidity, Dew point tempative humidity, Enthalpy, Humid specific heat, Wet wet bulb temperature, Psychometric chart, Psychometric g of airstreams. AIR CONDITIONING SYSTEMS AND LOAD	SES peratu bulb of air thromeat longerat	agh abad-Aure	Degree addition with the control of	n jet on - 9 ee of ture, oning ture- ratus hart-
Workin refriger Magnet UNIT Propert saturation Thermosprocess UNIT Air cor Solar Reselection calculate distribution	g princip ation- Ej ic -Vorter FIV I ies of moon, Rela odynamic es, mixing adiation- in-fresh ation of settion system.	DTHER REFRIGERATION SYSTEMS bles of Vapour absorption systems and adsorption cooling systems refrigeration systems. Thermoelectric refrigeration- ax and Pulse tube refrigeration systems. PSYCHOMETRIC PROPERTIES AND PROCESS bist Air-Gibbs Dalton law, Specific humidity, Dew point temperative humidity, Enthalpy, Humid specific heat, Wet wet bulb temperature, Psychometric chart, Psychometric g of airstreams. AIR CONDITIONING SYSTEMS AND LOAD ESTIMATION Is loads- Outside and inside design conditions- Heat transfer Electrical appliances- Infiltration and ventilation- internal hear load-Human comfort & IAQ principles- effective temperature winter air conditioning load- Classifications- Lay tem- Filters- Air-conditioning Systems with Controls- Temperature.	SES peratu bulb of air	ugh pad-Aure of pl	Degree and the control of the contro	9 ee of ture- ratus hart- Aine and
Workin refriger Magnet UNIT Propert saturation Thermosprocess UNIT Air con Solar R selection calculated distribution Humidian Control of the	g princip ation- Ej ic -Vorter IV I ies of moon, Relanded in the princip additioning addit	DTHER REFRIGERATION SYSTEMS Description of Vapour absorption systems and adsorption cooling systems of Vapour absorption systems. Thermoelectric refrigeration and Pulse tube refrigeration systems. PSYCHOMETRIC PROPERTIES AND PROCESS Dist Air-Gibbs Dalton law, Specific humidity, Dew point temperative humidity, Enthalpy, Humid specific heat, Wet wet bulb temperature, Psychometric chart, Psychometric go fairstreams. AIR CONDITIONING SYSTEMS AND LOAD ESTIMATION Is loads- Outside and inside design conditions- Heat transfer Electrical appliances- Infiltration and ventilation- internal heair load-Human comfort & IAQ principles- effective temperature & Winter air conditioning load- Classifications- Lay tem- Filters- Air-conditioning Systems with Controls- Temperatures, Actuators & Safety controls.	SES peratu bulb of air	ugh pad-Aure of pl	Degree and the control of the contro	9 m je on 9 ee of ature oning 9 ture ratus hart. Ain and

2.	Understand the concept of vapor compression refrigeration system.
3.	Learn the components and working of other refrigeration and air conditioning systems
4.	Evaluate different psychometric properties and processes.
5.	Perform heating and cooling load calculations.
TEXT	BOOKS:
1.	Arora, C. P., "Refrigeration and Air Conditioning", 3 rd ed., McGraw Hill, Delhi, 2010.
2.	Manohar Prasad., "Refrigeration and Air Conditioning", 2 nd ed., New Age Int., 2011.
3.	Rex Milter, Mark R.Miller, "Air conditioning and Refrigeration", McGraw Hill 2006.
REFE	CRENCES:
1.	Roy J. Dossat, "Principles of Refrigeration", 4 th edition, Pearson Education Asia, 2009.
2.	Stoecker, W. F. and Jones J. W., ''Refrigeration and Air Conditioning'', McGraw Hill, New Delhi, 1986.
3.	AhmadulAmeen., " Refrigeration and Air Conditioning ", 1 st edition, prentice-hall of India Private limited New Delhi 2006.
4.	Jones W. P., "Air conditioning engineering", 5 th edition, Elsevier Butterworth- Heinemann, 2001.
5.	Wilbert F. Stoecker, Jerold W. Jones., "Refrigeration and Air Conditioning", McGraw-Hill 1982.

MAPPIN	G OI	F CO	s, PO)s Al	ND P	SOs:									
						P	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2												2		1
CO2	3					2							3		3
CO3	3					2							3		3
CO4	3					2							3		3
CO5	3					3							3		3
Average	2.8					1.8							2.8		2.6
Round off	3					2							3		3
3- Strong C	orrel	ation;	; 2 - N	Iediu	m Coi	rrelati	ion; 1	- Lo	w Coi	rrelati	on				

	PE010	POWER PLANT ENGINEERING L	T	P	C
		3	0	0	3
OBJEC	CTIVES	5:			
•	To help	the students to learn the various cycles of coal based thermal powe	r plai	nts.	
•	To gain	knowledge on diesel, gas turbine and combined cycle power plants			
•	To fami	iarise the basics of nuclear engineering and various types of reacto	rs.		
•	To learn	how to get power from renewable energy sources.			
•	To Unde	erstand energy, economic and environmental issues of power plants	•		
UNIT	ГΙ С	OAL BASED THERMAL POWER PLANTS			9
Boilers, 7	Turbines lling, Dra	mprovisations, Layout of modern coal power plant, Super Critic Condensers, Steam & Heat rate, Subsystems of thermal power pught system, Feed water treatment. Binary Cycles and Cogeneration	lants	– Fu	iel and
UNIT		IESEL, GAS TURBINE AND COMBINED CYCLE OWER PLANTS			9
Turbine p	power pla	&Brayton Cycle - Analysis & Optimisation. Components of Diese ants. Combined Cycle Power Plants. Integrated Gasifier based Com			
systems.					
UNIT		UCLEAR POWER PLANTS			9
UNIT Basics o Nuclear Deuterium	III Not Nuclear Reactors m- Uran	UCLEAR POWER PLANTS IT Engineering, Layout and subsystems of Nuclear Power Plant: Boiling Water Reactor (BWR), Pressurized Water Reactor (um reactor (CANDU), Breeder, Gas Cooled and Liquid Metal Cor Nuclear Power plants.	(PW)	R),C	ting of
UNIT Basics o Nuclear Deuterium	III Not Nuclea Reactors m- Urani leasures f	r Engineering, Layout and subsystems of Nuclear Power Plar : Boiling Water Reactor (BWR), Pressurized Water Reactor um reactor (CANDU), Breeder, Gas Cooled and Liquid Metal C	(PW)	R),C	ting of
UNIT Basics o Nuclear Deuterium Safety me UNIT Hydro El Turbines	III Not n	er Engineering, Layout and subsystems of Nuclear Power Plan : Boiling Water Reactor (BWR), Pressurized Water Reactor cum reactor (CANDU), Breeder, Gas Cooled and Liquid Metal Cor Nuclear Power plants.	(PW)	R),C.d Re	ting of ANada eactors 9 cluding
UNIT Basics o Nuclear Deuterium Safety me UNIT Hydro El Turbines	of Nuclear Reactors m- Urani reasures for the lectric Post. Princip, Geo The Event Post.	er Engineering, Layout and subsystems of Nuclear Power Plant: Boiling Water Reactor (BWR), Pressurized Water Reactor (um reactor (CANDU), Breeder, Gas Cooled and Liquid Metal Cor Nuclear Power plants. OWER FROM RENEWABLE ENERGY Ower Plants – Classification, Typical Layout and associated compole, Construction and working of Wind, Tidal, SolarPhoto Volta	coole coole conent ic (S	R),Cad Red	ting of ANada eactors 9 cluding
UNIT Basics o Nuclear Deuteriun Safety mo UNIT Hydro El Turbines Thermal, UNIT Power ta Relative	III Not Nuclea Reactors m- Urani leasures for the season of the season o	er Engineering, Layout and subsystems of Nuclear Power Plar : Boiling Water Reactor (BWR), Pressurized Water Reactor (um reactor (CANDU), Breeder, Gas Cooled and Liquid Metal Cor Nuclear Power plants. OWER FROM RENEWABLE ENERGY Ower Plants – Classification, Typical Layout and associated compole, Construction and working of Wind, Tidal, SolarPhoto Volta ermal, Biogas and Fuel Cell power systems. NERGY, ECONOMIC AND ENVIRONMENTAL IS	onentic (S	R),C.d Red Red Red Red Red Red Red Red Red Re	ing of ANada actors. 9 eluding, Solar 9
UNIT Basics o Nuclear Deuteriur Safety me UNIT Hydro El Turbines Thermal, UNIT Power ta Relative	III Not Nuclea Reactors m- Urani leasures for the season of the season o	Engineering, Layout and subsystems of Nuclear Power Plant: Boiling Water Reactor (BWR), Pressurized Water Reactor (um reactor (CANDU), Breeder, Gas Cooled and Liquid Metal Coor Nuclear Power plants. OWER FROM RENEWABLE ENERGY Ower Plants – Classification, Typical Layout and associated compole, Construction and working of Wind, Tidal, SolarPhoto Voltaermal, Biogas and Fuel Cell power systems. NERGY, ECONOMIC AND ENVIRONMENTAL IS FOWER PLANTS S, Load distribution parameters, load curve, Comparison of site sea demerits, Capital & Operating Cost of different power plants. If	onentic (S	es incessory)	ing of ANada actors 9 cluding, Solar 9 criteria contro
UNIT Basics o Nuclear Deuterium Safety me UNIT Hydro El Turbines Thermal, UNIT Power ta Relative technolog	of Nuclea Reactors m- Urani leasures for the lectric Potes. Princip, Geo The Countriff types merits & gies included	Engineering, Layout and subsystems of Nuclear Power Plant: Boiling Water Reactor (BWR), Pressurized Water Reactor (um reactor (CANDU), Breeder, Gas Cooled and Liquid Metal Cor Nuclear Power plants. OWER FROM RENEWABLE ENERGY Ower Plants – Classification, Typical Layout and associated compole, Construction and working of Wind, Tidal, SolarPhoto Voltaernal, Biogas and Fuel Cell power systems. NERGY, ECONOMIC AND ENVIRONMENTAL IS FOWER PLANTS St., Load distribution parameters, load curve, Comparison of site set demerits, Capital & Operating Cost of different power plants. Ending Waste Disposal Options for Coal and Nuclear Power Plants.	onentic (S	es incessory)	ing of ANada actors 9 cluding, Solar 9 criteria contro
UNIT Basics o Nuclear Deuterium Safety me UNIT Hydro El Turbines Thermal, UNIT Power ta Relative technolog	of Nuclea Reactors m- Urani leasures for the lectric Post. Princip, Geo The Couriff types merits & gies inclusion.	Engineering, Layout and subsystems of Nuclear Power Plant: Boiling Water Reactor (BWR), Pressurized Water Reactor (um reactor (CANDU), Breeder, Gas Cooled and Liquid Metal Coor Nuclear Power plants. OWER FROM RENEWABLE ENERGY Ower Plants – Classification, Typical Layout and associated composite, Construction and working of Wind, Tidal, SolarPhoto Volta ermal, Biogas and Fuel Cell power systems. NERGY, ECONOMIC AND ENVIRONMENTAL IS OF POWER PLANTS S., Load distribution parameters, load curve, Comparison of site set demerits, Capital & Operating Cost of different power plants. Ending Waste Disposal Options for Coal and Nuclear Power Plants. TOTAL: 45	onentic (S	es incessory)	ing of ANada actors 9 cluding, Solar 9 criteria contro
Basics o Nuclear Deuterium Safety me UNIT Hydro El Turbines Thermal, UNIT Power ta Relative technolog OUTCO	of Nuclea Reactors m- Urani leasures for the lectric Potes. Princip, Geo The Couriff types merits & gies included of the learn	Engineering, Layout and subsystems of Nuclear Power Plant: Boiling Water Reactor (BWR), Pressurized Water Reactor (um reactor (CANDU), Breeder, Gas Cooled and Liquid Metal Coor Nuclear Power plants. OWER FROM RENEWABLE ENERGY Ower Plants – Classification, Typical Layout and associated compole, Construction and working of Wind, Tidal, SolarPhoto Voltaermal, Biogas and Fuel Cell power systems. NERGY, ECONOMIC AND ENVIRONMENTAL IS OF POWER PLANTS 5, Load distribution parameters, load curve, Comparison of site set demerits, Capital & Operating Cost of different power plants. It is ding Waste Disposal Options for Coal and Nuclear Power Plants. TOTAL: 45 On completion of this course, students will be able to	onentic (S	es incessory)	ing of ANada actors 9 cluding, Solar 9 criteria control

4.	Design power p	plants to get energy from renewable energy sources.
5.	Analyse energy	, economic and environmental issues of power plants.
TEX	KT BOOKS:	
1.	Nag. P.K., "Po Company Ltd., 2008.	wer Plant Engineering", Third Edition, Tata McGraw – Hill Publishing
2.	Arora.S.C and Delhi, 2015.	Domkundwar.S, "Power Plant Engineering", DhanpatRai& Sons, New
3.	Ramalingam.K	.K, "Power Plant Engineering", Scitech Publication Pvt. Ltd, 2015.
REF	TERENCES:	
1.	El-Wakil. M.M. Ltd.,2010.	, "Power Plant Technology", Tata McGraw – Hill Publishing Company
 1. 2. 	Ltd.,2010.	, "Power Plant Technology", Tata McGraw – Hill Publishing Company n, Springer, "Power Plant Engineering", 1996.
	Ltd.,2010. Black & Veatch Thomas C. Elli	
2.	Ltd.,2010. Black & Veatch Thomas C. Elli Second Edition Godfrey Boyle,	a, Springer, "Power Plant Engineering", 1996. ott, Kao Chen and Robert C. Swanekamp, "Power Plant Engineering",

		G OF COs, POs AND PSOs: POs									PSOs				
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	1											2		
CO2	3	2											2		
CO3	2	1				3							1		3
CO4	2	1				3							2		3
CO5	2	1				3							2		3
Average	2.2	1.2				1.8							1.8		1.8
Round off	2	1				2							2		2

18MPE01	18MPE011 GAS DYNAMICS AND JET PROPULSION L T P									
		(Use of Approved Gas table is Permitted)	3	0	0	3				
OBJECTI	VES	5:								
	-	ovide students with an insight into the applications of compression and propulsion system.	sible f	lows	and	the				
		able them to formulate and solve problems in one –dimensional essible flow.	al stea	dy						
		ive the conditions for change in pressure, density and temperath normal and oblique shocks.	ature f	or flo	ows					
• To	To analyse the performance of jet propulsion system.									
• To	o ana	llyse the performance of space propulsion system.								
UNIT I	В	ASIC CONCEPTS				9				
	Effe	entum equations of compressible fluid flows – Stagnation state ct of Mach number on compressibility – Isentropic flow throusers.								
UNIT II	F	LOW THROUGH DUCTS				9				
Flows through Variation of f		nstant area ducts with heat transfer (Rayleigh flow) and Friction properties.	on (Fa	nno i	flow) —				
UNIT III	N	ORMAL AND OBLIQUE SHOCKS				9				
		ons – Variation of flow parameters across the normal and obli- lations – Applications.	que sh	ocks	· —					
UNIT IV	\mathbf{J}	ET PROPULSION				9				
principle, cyc	le ar	pulsion – Thrust equation – Thrust power and propulsive efficiently allysis and use of stagnation state performance of ram jet, turbes – Applications of jet propulsion.	•	-		_				
UNIT V	S	PACE PROPULSION				9				
• •	lsion	engines – Propellants-feeding systems – Ignition and comb a – Performance study – Staging – Terminal and chara- ace flights.				•				
		TOTAL	: 45]	PER	lOI	DS				
OUTCOM	ES:	On completion of this course, students will be able to								
1. Expl	ain t	he basic concepts of compressible flow and jet propulsion.								
2. Solve	pro	blems of Rayleigh and Fanno flow.		_	_					
3. Appl	y the	e concept of normal and oblique shocks for various application	ns.							
4. Appl	y the	e concept of jet propulsion in turbojet, turbofan and turboprop	engin	es.						
5. Anal	yse t	he concept of space propulsion of rockets.								

TEX	T BOOKS:	
1.		Fundamentals of Compressible Flow'' , 6 th Edition, New Age P) Limited, NewDelhi, 2018.
2.	Somasundaram InternationalPu	a. PR. S. L., "Gas Dynamics and Jet Propulsions", New Age ablishers, 1996.
3.	Ganesan. V., "	Gas Turbines", Tata McGraw Hill Publishing Co., New Delhi, 1999.
REF	ERENCES:	
1.	Anderson, J. D	., ''Modern Compressible flow'', 3rd Edition, McGraw Hill, 2003.
2.	Babu. V., '' Fu	ndamentals of Gas Dynamics'', ANE Books India, 2008.
3.		Peterson, "Mechanics and Thermodynamics of Propulsion", Addison— ting company, 1992.
4.	Zucrow. N. J., 1970.	"Principles of Jet Propulsion and Gas Turbines", John Wiley, New York,
5.	Shapiro. A. H., wiley, New Yor	"Dynamics and Thermodynamics of Compressible fluid Flow", John k, 1953.

MAPPING	FOF	COs	, PO	s AN	D PS	Os:									
	POs										PSOs				
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2	1											2		
CO2	3	2											2	1	
CO3	2	1											2	2	
CO4	3	1											2	2	
CO5	3	1											2	2	
Average	2.6	1.2											2		
Round off	3	1											2	1.4	
3- Strong Co	rrelat	ion; 2	2 - Me	dium	Corr	elatio	n; 1 –	Low	Corr	elatio	n	ı		1	I

18MI	PE012		PROCESS PLANNING AND COST ESTIMATION	L	T	P	С			
				3	0	0	3			
OBJE	CTIVES	S:								
•	To he	lp the s	tudents to understand the method of process planning	5 .						
•	To ex	plore v	arious process planning activities.							
•	To lea	rn imp	ortance of costing and estimation and different types	of estin	nates	•				
•	To evaluate production cost estimation of different types of shops.									
•	To cal	culate	machining time for different machining processes.							
UNIT I INTRODUCTION TO PROCESS PLANNING 9										
	ntroduction- methods of process planning-Drawing interpretation-Material evaluation – steps in process selection Production equipment and tooling selection.									
UNI	NIT II PROCESS PLANNING ACTIVITIES 9									
	planning-	case s	urance methods - Set of documents for process platudies. Introduction to CAPP and ERP.	8						
			DDUCTION TO COST ESTIMATION				9			
Importa estimate	nce of cores – Estin	sting a	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- adepreciation cost.				es of			
Importa estimate	ince of coles – Estin	sting a nating ion of	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- a				es of			
Importa estimate charges UNIT	nce of cores – Esting – Calculation	sting a nating ion of o	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- adepreciation cost. UCTION COST ESTIMATION Types of Jobs - Estimation of Forging Shop, Estimation	llocation	n of	over	es of head			
Importa estimate charges UNIT	nce of cores – Esting – Calculate P IV P ion of Diffion of Four	sting a nating ion of a ROD ferent '	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- adepreciation cost. UCTION COST ESTIMATION Types of Jobs - Estimation of Forging Shop, Estimation	llocation	n of	over	es of head			
Importa estimate charges- UNIT Estimate Estimate UNIT Estimate Machine	ince of cores – Esting – Calculation of Diffication of Four Ming Time	ROD ferent ' IACH Iachini	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- adepreciation cost. UCTION COST ESTIMATION Types of Jobs - Estimation of Forging Shop, Estimation.	on of Wation- (eldir	over	es of head 9 nop, 9 n of			
Importa estimate charges- UNIT Estimate Estimate UNIT Estimate Machine	ince of cores – Esting – Calculation of Diffication of Four Ming Time	ROD ferent ' IACH Iachini	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- adepreciation cost. UCTION COST ESTIMATION Types of Jobs - Estimation of Forging Shop, Estimation of the company of the company of the cost of t	on of Wation- (- Ma	eldir	over	es of head phop,			
Importa estimate charges- UNIT Estimate Estimate UNIT Estimate Machine Calculate	ince of cores – Esting – Calculation of Diffication of Four Ming Time	ROD ferent and the formula for filling,	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- adepreciation cost. UCTION COST ESTIMATION Types of Jobs - Estimation of Forging Shop, Estimation. INING TIME CALCULATION Ing Time - Importance of Machine Time Calculation Different Lathe Operations ,Drilling and Boring Shaping and Planning -Machining Time Calculation	on of Wation- (- Ma	eldir	over	es of head phop,			
Importa estimate charges- UNIT Estimate Estimate UNIT Estimate Machine Calculate	ince of cores — Esting — Calculating TIV Prior of Four Prior of Ming Time tion for M	ROD ferent and for for filling,	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- adepreciation cost. UCTION COST ESTIMATION Types of Jobs - Estimation of Forging Shop, Estimation of Shop. INING TIME CALCULATION Ing Time - Importance of Machine Time Calculation Shaping and Planning -Machining Time Calculation TOTA	on of Wation- (- Mafor Grin L: 45	eldir	over	es of head phop,			
Importa estimate charges- UNIT Estimati Estimati Machini Calculat	ion of Diffion of Foundation for M	ROD ferent and for for filling, On the proces	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- adepreciation cost. UCTION COST ESTIMATION Types of Jobs - Estimation of Forging Shop, Estimation of the completion of this course, students will be able to	on of Wation- (- Mafor Grin L: 45	eldir	over	es of head phead			
Importa estimate charges- UNIT Estimate Estimate UNIT Estimate Machine Calculate OUTC 1	ion of Diffion of Foundation for Months Ecomes - Estimates - Calculation of Diffion of Foundation of Months Ecomes: Select the Prepare property of the Select the Ecomes - Estimates - Es	ROD ferent and some for silling, On the process	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- adepreciation cost. UCTION COST ESTIMATION Types of Jobs - Estimation of Forging Shop, Estimation of the completion of Machine Time Calculation of Time - Importance of Machine Time Calculation Shaping and Planning -Machining Time Calculation TOTA completion of this course, students will be able to ses, equipment and tools for various industrial productions.	on of Wation- (- Mafor Grin L: 45	eldir	over	9 nop,			
Importa estimate charges- UNIT Estimate Estimate Estimate Machine Calculate OUTC 1 2	ion of Diffiction of Four Ming Time tion for Ming T	ROD ferent and some for silling, On the process the continuous string and st	nd estimation –methods of costing-elements of cost procedure- Estimation labor cost, material cost- adepreciation cost. UCTION COST ESTIMATION Types of Jobs - Estimation of Forging Shop, Estimation of Programment of Programment of Programment of Programment of Programment of Machine Time Calculation of Programment Calculation of Programment of Machine Time Calculation of Programment of Machine Time Calculation of Programment of Programment of Machine Time Calculation of Calculation of Programment of Calculation of Programment of Programment of Programment of Programment of Programment of Programment of Calculation of Programment of Programme	on of Wation- (- Mafor Grin L: 45	eldir	over	es of head phead			

TEX	T BOOKS:
1.	Peter scalon, "Process planning, Design/Manufacture Interface", Elsevier science technology Books, Dec 2002.
2.	Sinha B.P, "Mechanical Estimating and Costing", Tata-McGraw Hill publishing co, 1995.
3.	B. Vijayaramanath, C.Elanchezhian, R.Kesavan, "Process Planning and Cost Estimation", New Age International (P) Limited, (2008).
REF	ERENCES:
1.	Chitale A.V. and Gupta R.C., "Product Design and Manufacturing", 2nd Edition, PHI, 2002.
2.	Ostwalal P.F. and Munez J., "Manufacturing Processes and systems", 9th Edition, John Wiley, 1998.
3.	Russell R.S and Tailor B.W, "Operations Management", 4th Edition, PHI, 2003.
4.	Mikell P. Groover, "Automation, Production, Systems and Computer Integrated Manufacturing", Pearson Education 2001.
5.	K.C. Jain & L.N. Aggarwal, "Production Planning Control and Industrial Management", Khanna Publishers 1990.

MAPPING	GOF	COs,	, POs	s AN	D PS	Os:									
		POs											PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3												2		
CO2	3	1								2			2		
CO3	3	1								2			2	1	
CO4	3	1								2			2	1	
CO5	2	3											3	2	
Average	2.8	1.2											2.2	0.8	
Round off	3	1								1.2			2	1	
3- Strong Co	rrelat	ion; 2	2 - Me	edium	Corr	elatio	n; 1 –	- Low	Corr	elatio	n				

18MI	PE013	LEAN MANUFACTURING	L	T	P	C				
			3	0	0	3				
OBJE	CTIVES	:								
•	To make	the students to study the concept and implementation of lean	manu	factı	ıring	•				
•	To learn	the Sustainable engineering concepts.								
•	To analy	se the multi attributes decision making methods								
•	To unde	rstand the concept of lean manufacturing management.								
•	To explo	ore the applications in lean manufacturing.								
UNI	LI II	NTRODUCTION				9				
		f lean manufacturing-key principles and implications of lean manufacturing traditional ufacturing – Lean benefits.								
UNIT	TII L	LEAN MANUFACTURING CONCEPTS 9								
pull pro	duction-c	eation and waste elimination- Major kinds of waste- pull production – different models of luction-continuous flow – Kaizen – Worker involvement; Part family- Production flow – Composite part concept – Machine cell design -Case studies.								
UNIT	'III L	EAN MANUFACTURING TOOLS & METHODO	OLO	GI	ES	9				
visual	controls-c	ommunication of standard work to employees -standard work uality at the source- 5S principles —preventive maintener productive maintenance -changeover/setup time -batch size re	ance	-tota						
UNIT	IV	ALUE STREAM MAPPING				9				
		m-the future state map-application to the factory simulary oka- Kanban – overall equipment effectiveness -JIT - element								
UNI	$\Gamma \mathbf{V} \mid \mathbf{I}$	MPLEMENTING LEAN				9				
	-	management Involvement-best practices- reconciling lean with system-lean six sigma-lean and ERP-lean with ISO9001:2000		er sy	stem	S -				
		TOTAL:	45 P	ER	OD	S				
OUTC	JTCOMES: On completion of this course, students will be able to									
1.	1. Evaluate the objectives and benefits of lean manufacturing.									
2.		nd various lean manufacturing concepts with case studies.								
3.	Learn va	ious lean manufacturing tools and methodologies.								
4.		about value stream mapping techniques.								
5.	Learn the best practices used for implementation of lean manufacturing system.									

TEXT BOOKS:

1.	Michael L George, David T Rowlands, Bill Kastle, "What is Lean Six Sigma", McGraw Hill Inc., New York, 2004.							
2.	Askin R.G, Goldberg J.B, "Design and Analysis of Lean Production Systems", JohnWiley & Sons, New York, 2003.							
3.	S. R. Devadasan, V. Sivakumar, R. Murugesh, P. R. Manufacturing: Theoretical, Practical and Research Private limited, New Delhi, 2012. Shalij, "Lean and Agile Futurities", PHI Learning							
REF	ERENCES:							
1.	Joseph A De Feo, William W BearnardJuran Institute, "Six Sigma Break Throughand Beyond", Tata McGraw Hill, New Delhi, 2004.							
2.	Richard B Chase F Robert Jacobs and Nicholas J Aquilano, "Operations Management for Competitive Advantage", McGraw Hill Inc., New York, 10 th Edition, 2003.							
3.	Dennis P. Hobbs, "Lean Manufacturing Implementation: A Complete Execution Manual for Any Size", J. Ross Publishing, 2005.							
4.	Micheal Wader, "Lean Tools: A Pocket guide to Implementing Lean Practices", Productivity and Quality Publishing Pvt Ltd, 2002.							
5.	Akhilesh N. Singh, "Lean Manufacturing: Principles to Practice", L.B. Associates, 2010.							

MAPPING	OF	COs	, POs	s AN	D PS	Os:									
	POs											PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2												2		
CO2	2									2			3		
CO3	3	1					1			2			3		
CO4	3	1					1			2			3		
CO5	3	1					1			1			3		
Average	2.8	0.6					0.6			1.4			2.8		
Round off	3	1					1			1			3		
3- Strong Co	rrelat	ion; 2	2 - Me	dium	Corr	elatio	n; 1 –	Low	Corr	elatio	n	ı	ı	1	

18MI	PE014	DESIGN OF JIGS, FIXTURES AND PRESS TOOLS	L	T	P	C		
			3	0	0	3		
OBJE	CTIVI	ES:						
•	To hel	p the students explore the various locating and clamping method	ls.					
•	To des	ign and development of jigs and fixtures for given component.						
•	To und	lerstand press working terminologies and elements of cutting die	es.					
•	To des	ign bending and drawing dies.						
•		derstand the functions and design principles of various forming t g, forming, drawing, etc.	echni	ques	like			
UNI	ГΙ	LOCATING AND CLAMPING PRINCIPLES				9		
Objectives of tool design- Function and advantages of Jigs and fixtures – Basic elements principles of location – Locating methods and devices – Redundant Location – Principles clamping –Mechanical actuation – pneumatic and hydraulic actuation - Standard parts – D bushes and Jig buttons – Tolerances and materials used.								
UNIT	ΓII	JIGS AND FIXTURES				9		
Design a	and deve	elopment of jigs and fixtures for given component- Types of Jigs	s – Po	st, T	urno	ver,		
boring,	broachii	box, pot, angular post jigs – Indexing jigs – General principle ng and grinding fixtures – Assembly, Inspection and Welding us- Quick change fixtures.			_			
UNIT		PRESS WORKING TERMINOLOGIES AND ELF OF CUTTING DIES	EME	NTS	8	9		
		Terminologies - operations — Types of presses — press accesso y — Strip layout — Material Utilization — Shearing action — Cleara						
Die set,	guide	tter of pressure- Design of various elements of dies – Die Blo plates – Stops – Strippers – Pilots – Selection of Standard pour standard views of simple blanking, piercing, compound and	parts	– De	esign	and		
UNIT IV BENDING AND DRAWING DIES								
Bending Ejectors ironing-	g dies – – Varia - Designation die	reen bending and drawing – Blank development for above open Press capacity – Spring back – knockouts – direct and indirect ables affecting Metal flow in drawing operations – draw die in and development of bending, forming, drawing, reverses – Blank development for axi-symmetric, rectangular and ellon dies.	t — pi serts - se re	essu: – dra edraw	re pa w be ing	ds - ads and		
UNI	ΓV	OTHER FORMING TECHNIQUES				9		
blanking	g dies –	ng, Embossing, coining, curling, hole flanging, shaving and size recent trends in tool design-computer Aids for sheet metal to the tooling for numerically controlled machines, setup reduction	formi	ng A	nalys	sis -		

basic introduction - tooling for numerically controlled machines- setup reduction for work holding

- Single minute exchange of dies - Poka Yoke.

	TOTAL : 45 PERIODS
OUT	COMES: On completion of this course, students will be able to
1.	Explore various locating and clamping principles.
2.	Understand functions and design of Jigs & Fixtures.
3.	Analyze functions and design Press work and cutting die.
4.	Evaluate functions and design of press working and elements of cutting dies.
5.	Apply functions and various design to other forming techniques.
TEXT	T BOOKS:
1.	Joshi, P.H. "Jigs and Fixtures", Second Edition, Tata McGraw Hill, NewDelhi, 2004.
2.	Joshi P.H "Press tools - Design and Construction", wheels publishing, 1996.
3.	Cyril Donaldson, George H. LeCain, V. C. Goold, JoyjeetGhose, "Tool Design", Fourth Edition, Tata McGraw Hill Publishing Co., Ltd., NewDelhi, 2012.
REFI	ERENCES:
1.	Venkataraman. K., "Design of Jigs Fixtures & Press Tools", Tata McGraw Hill,2005.
2.	Donaldson, Lecain and Goold "Tool Design" , 3 rd Edition, Tata McGraw Hill, 2000.
3.	Kempster, "Jigs and Fixture Design", Third Edition, Hoddes and Stoughton, 1974.
4.	"Design Data Hand Book", PSG College of Technology, Coimbatore.
5.	Hoffman "Jigs and Fixture Design", Thomson Delmar Learning, Singapore, 2004.

MAPPING OF COs, POs AND PSOs:

		POs													
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3												3		
CO2	3												3		
CO3	3												3		
CO4	3												3		
CO5	3												3		
Average	3												3		
Round off	3												3		

3- Strong Correlation; 2 - Medium Correlation; 1-Low Correlation

18MPE015 MECHANICAL VIBRATIONS L T P								
		•	3	0	0	3		
OBJEC	CTIVI	ES:	l	l.				
•	To ma	ke the students to understand different types of vibration.						
•	To ma	ke them to understand the sources of vibration and noise in autor	nobil	es.				
		ke design modifications to reduce the vibration and noise and immponents.	prov	e the	life	of		
•	To ana	alyze the Single Degree, Two Degree and Multi degree of Freedo	m Sy	stem	ıs.			
•	To stu	dy the numerical methods for vibration analysis.						
UNIT I	[BASICS OF VIBRATION				9		
	ation o	analysis of single degree and two degree of freedom systems, a finatural frequencies. BASICS OF NOISE		, iiul	, 101 0	9		
		nplitude, frequency, wavelength and sound pressure level, addition				and		
averaging	g decil nent e		analy	sis (of n	and oise,		
averaging measuren	g decil nent e	nplitude, frequency, wavelength and sound pressure level, additional bel levels, noise dose level, legislation, measurement and	analy	sis (of n	and oise,		
averaging measuren analysis. UNIT Noise Chassessme	g decilend the ment e	inplitude, frequency, wavelength and sound pressure level, additional bel levels, noise dose level, legislation, measurement and environment, equipment, frequency analysis, tracking analysis	analy sis, s mbust	rsis osouno	of n l qu noise	and oise, ality		
averaging measuren analysis. UNIT Noise Chassessme contribute	III naracter and of noise	nplitude, frequency, wavelength and sound pressure level, additional believels, noise dose level, legislation, measurement and environment, equipment, frequency analysis, tracking analysis and the state of engines, engine overall noise levels, assessment of connechanical noise, engine radiated noise, intake and exhaust noise	analy sis, s mbust	rsis osouno	of n l qu noise	and oise, ality		
averaging measuren analysis. UNIT Noise Chassessme contribute UNIT Vibration dynamic	III naracter ent of n ded nois IV n isolat forces	nplitude, frequency, wavelength and sound pressure level, additional believels, noise dose level, legislation, measurement and environment, equipment, frequency analysis, tracking analysis. AUTOMOTIVE NOISE SOURCES ristics of engines, engine overall noise levels, assessment of connechanical noise, engine radiated noise, intake and exhaust noise se, transmission noise, aerodynamic noise, tire noise, brake noise	analy sis, s mbust e, eng	ion i	of noise neces	a and oise, ality 9 e and ssary 9 ation		
averaging measuren analysis. UNIT Noise Chassessme contribute UNIT Vibration dynamic	III naracter and of noise IV n isolat forces elastic	AUTOMOTIVE NOISE SOURCES ristics of engines, engine overall noise levels, assessment of connechanical noise, engine radiated noise, intake and exhaust noise ise, transmission noise, aerodynamic noise, tire noise, brake noise CONTROL TECHNIQUES ion, tuned absorbers, un-tuned viscous dampers, damping treat generated by IC engines, engine isolation, crank shaft damping,	analy sis, s mbust e, eng	ion i	of noise neces	a and oise, ality 9 e and ssary 9 ation		
averaging measurent analysis. UNIT Noise Chassessme contribute UNIT Vibration dynamic the mass UNIT Methods palliative	III naracter ent of noted noise IV n isolate forces elastice V for content of the content o	AUTOMOTIVE NOISE SOURCES ristics of engines, engine overall noise levels, assessment of connechanical noise, engine radiated noise, intake and exhaust noise et, transmission noise, aerodynamic noise, tire noise, brake noise CONTROL TECHNIQUES ion, tuned absorbers, un-tuned viscous dampers, damping treat generated by IC engines, engine isolation, crank shaft damping, model shock absorbers.	mbust e, eng	ion rine ration at the street of the street	of n d qu noise neces	a and oise, ality 9 and ssary 9 ation is of 9 ysis,		
averaging measurent analysis. UNIT Noise Chassessme contribute UNIT Vibration dynamic the mass UNIT Methods palliative	III naracter ent of noted noise IV n isolate forces elastice V for content of the content o	AUTOMOTIVE NOISE SOURCES ristics of engines, engine overall noise levels, assessment of connechanical noise, engine radiated noise, intake and exhaust noise, transmission noise, aerodynamic noise, tire noise, brake noise CONTROL TECHNIQUES ion, tuned absorbers, un-tuned viscous dampers, damping treat generated by IC engines, engine isolation, crank shaft damping, model shock absorbers. SOURCE OF NOISE AND CONTROL ontrol of engine noise, combustion noise, mechanical noise, ponents and enclosures, automotive noise control principles, sonents and enclosures, automotive noise control principles, sone	mbuste, eng	ctive	of noise noise neces analys	a and oise, ality 9 and ssary 9 ation is of 9 ysis, ures,		
averaging measurent analysis. UNIT Noise Chassessme contribute UNIT Vibration dynamic the mass UNIT Methods palliative	III naracter ent of n ed nois IV n isolat forces elastic V for coe e treatn ergy ab	AUTOMOTIVE NOISE SOURCES ristics of engines, engine overall noise levels, assessment of concechanical noise, engine radiated noise, intake and exhaust noise etc, transmission noise, aerodynamic noise, tire noise, brake noise generated by IC engines, engine isolation, crank shaft damping, model shock absorbers. SOURCE OF NOISE AND CONTROL ontrol of engine noise, combustion noise, mechanical noise, prenents and enclosures, automotive noise control principles, son osorption, and sound transmission through barriers. TOTAL: 4	mbuste, eng	ctive	of noise noise neces analys	a and oise, ality 9 and ssary 9 ation is of 9 ysis, ures,		
averaging measurent analysis. UNIT Noise Chassessme contribute UNIT Vibration dynamic the mass UNIT Methods palliative sound end	III naracter ent of n ed nois IV n isolat forces elastic V for coe et treatn ergy ab	AUTOMOTIVE NOISE SOURCES ristics of engines, engine overall noise levels, assessment of concechanical noise, engine radiated noise, intake and exhaust noise etc, transmission noise, aerodynamic noise, tire noise, brake noise generated by IC engines, engine isolation, crank shaft damping, model shock absorbers. SOURCE OF NOISE AND CONTROL ontrol of engine noise, combustion noise, mechanical noise, prenents and enclosures, automotive noise control principles, son osorption, and sound transmission through barriers. TOTAL: 4	mbuste, eng	ctive	of noise noise neces analys	a and oise, ality 9 and ssary 9 ation is of 9 ysis, ures,		
averaging measurem analysis. UNIT Noise Chassessme contribute UNIT Vibration dynamic the mass UNIT Methods palliative sound end OUTCO 1. U	III naracter ent of n ed nois IV n isolat forces elastic V for coe et treatn ergy ab Unders	AUTOMOTIVE NOISE SOURCES ristics of engines, engine overall noise levels, assessment of concechanical noise, engine radiated noise, intake and exhaust noise et, transmission noise, aerodynamic noise, tire noise, brake noise (CONTROL TECHNIQUES) ion, tuned absorbers, un-tuned viscous dampers, damping treat generated by IC engines, engine isolation, crank shaft damping, model shock absorbers. SOURCE OF NOISE AND CONTROL ontrol of engine noise, combustion noise, mechanical noise, prents and enclosures, automotive noise control principles, so psorption, and sound transmission through barriers. TOTAL: 4 S: On completion of this course, students will be able to	mbuste, eng	ctive	of noise noise neces analys	a and oise, ality 9 and ssary 9 ation is of 9 ysis, ures,		
averaging measuremanalysis. UNIT Noise Chassessme contribute UNIT Vibration dynamic the mass UNIT Methods palliative sound end OUTCO 1. U 2. O	III naracter ent of n ed nois IV n isolat forces elastic V for coe et treatn ergy ab Unders Gaining	AUTOMOTIVE NOISE SOURCES ristics of engines, engine overall noise levels, assessment of connechanical noise, engine radiated noise, intake and exhaust noise se, transmission noise, aerodynamic noise, tire noise, brake noise (CONTROL TECHNIQUES) ion, tuned absorbers, un-tuned viscous dampers, damping treat generated by IC engines, engine isolation, crank shaft damping, model shock absorbers. SOURCE OF NOISE AND CONTROL control of engine noise, combustion noise, mechanical noise, penents and enclosures, automotive noise control principles, so posorption, and sound transmission through barriers. TOTAL: 4 S: On completion of this course, students will be able to tand causes, source and types of vibrations in machineries.	mbuste, eng	ctive	of noise noise neces analys	a and oise, ality 9 and ssary 9 ation is of 9 ysis, ures,		

5.	Learn about va	rious sources of noises and its control.
TEX	T BOOKS:	
1.	SingiresuS.Rac	o, "Mechanical Vibrations", 5 th Edition, Pearson Education, 2010
2.		omson, Marie Dillon Dahleh, ChandramouliPadmanabhan, "Theory of Application", 5 th Edition Pearson Education, 2011
3.		l Colin Hansen, " Engineering Noise Control – Theory and Practice ",4 th FN Spon, Taylore&Francise e-Library, 2009
REF	ERENCES:	
1.	Benson H. Ton	gue, "Principles of Vibrations", 2nd Edition, Oxford University, 2007
2.	Grover. G.T., "	'Mechanical Vibrations",Nem Chand and Bros., 1996
3.	Julian Happiar Heinemann,200	n-Smith - "An Introduction to Modern Vehicle Design"- Butterworth- 04
4.		dupta, K., "Introductory course on Theory and Practice of Mechanical d Edition, New Age International Publications, 2010
5.	Shabana. A.A.,	"Theory of vibrations – An introduction", 2nd Edition, Springer, 2010

MAPPIN	G OI	F CO	s, P()s Al	ND P	SOs:									
		POs													
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3												3		
CO2	3												3		
CO3	3					1							3		
CO4	2					2							3		3
CO5	2					3							3		3
Average	2.6					0.8							3		1.2
Round off	3					1							3		1
3- Strong C	orrel	ation	; 2 - N	Iediu	m Co	rrelati	ion; 1	- Lo	w Co	rrelati	ion	ı			

TO1411	PE016	PRINCIPLES OF MANAGEM	MENT	L	T	P	\mathbf{C}
				3	0	0	3
OBJE	CTIV	CS:					
•	To he	p the students to understand the basics of manage	gement and orga	nizati	ons.		
•	To ge	knowledge on various planning techniques.					
•	To ex	lore various organising methods.					
•	To Fa	niliarise different directing techniques.					
•	To Le	arn and differentiate various types of controlling	g techniques.				
UNI	TI	INTRODUCTION TO MANAGEMENT ORGANIZATIONS	NT AND				9
manage conting compan	erial role ency ap ny-publi	Inangement – Science or Art – Manager vs Is and skills – Evolution of Management – Science proaches – Types of Business organization and private sector enterprises - Organization is in Management.	ntific, human rel - Sole proprieto	ations orship	s, sy , par	stem rtner	and ship
UNI	ΤII	PLANNING					9
Nature		pose of planning – planning process – types	of planning - c	higgs	ives	– se	ttino
objectiv	_	olicies — Planning premises — Strategic Ma ecision making steps and process.					
objectiv	ques – Ē	olicies - Planning premises - Strategic Ma					
objective Technical UNIT Nature structure centralia	and pure – type zation a ment, se	olicies — Planning premises — Strategic Malecision making steps and process. ORGANISING pose — Formal and informal organization — es — Line and staff authority — departmentalised decentralization — Job Design - Human Reselection, Training and Development, Performance	organization characteristics of the delegation of the delegation ource Management	nart – tion c	org of au	ools aniza thori	9 ation ty -
UNIT Nature structur centrali Recruit	and pure – typzation a ment, sonageme	olicies — Planning premises — Strategic Malecision making steps and process. ORGANISING pose — Formal and informal organization — es — Line and staff authority — departmentalised decentralization — Job Design - Human Reselection, Training and Development, Performance	organization characteristics of the delegation of the delegation ource Management	nart – tion c	org of au	ools aniza thori	9 atior
Nature structur centralia Recruita and man UNIT	and pure – typzation a ment, so nageme TIV tions of ues – jonication	organization — Strategic Malecision making steps and process. ORGANISING pose — Formal and informal organization — es — Line and staff authority — departmentaling decentralization — Job Design - Human Reselection, Training and Development, Performant.	organization che delega ource Management — Management — motivation theory and the organization are also as a second are also as a second and the organization are also as a second are a second are a second are also as a second are a second are also as a second are	nart – tion cent – t , Ca	org of au HR areer	anizathori Plani plan tivati	and gation ation ity – ning ning oning ional nip –
UNIT Nature structur centrali Recruit and man UNIT Founda technique commu	and pure – typzation a ment, senageme TIV tions of ues – jonication nication	ORGANISING pose – Formal and informal organization – es – Line and staff authority – departmentaling decentralization – Job Design - Human Reselection, Training and Development, Performant. DIRECTING individual and group behaviour – motivation – to satisfaction – job enrichment – leadership – process of communication – barrier	organization che delega ource Management — Management — motivation theory and the organization are also as a second are also as a second and the organization are also as a second are a second are a second are also as a second are a second are also as a second are	nart – tion cent – t , Ca	org of au HR areer	anizathori Plani plan tivati	9 antior atty - ning ning ning
Objective Technical Technical Nature structure centraliand management and management technique communical Communication	and pure – type zation a ment, so nageme TIV tions of ues – journication of the pure of	ORGANISING pose – Formal and informal organization – es – Line and staff authority – departmentaling decentralization – Job Design - Human Reselection, Training and Development, Performant. DIRECTING individual and group behaviour – motivation – to satisfaction – job enrichment – leadership – process of communication – barrier – communication and IT.	organization che delega ource Management — Management — motivation theorem in communication communic	nart – tion (ent – t , Ca ories – ries or eation	org of au HR areer - mo f lead	anizathori Plani plan tivati dersh effec	9 and on the state of the state
Objective Technical Technical Nature structure centraliand management and management technique communical Communication	and pure – type zation a ment, so nageme TIV tions of ues – journication of the pure of	organisms of Strategic Materials of Planning premises — Strategic Materials of Pose — Formal and informal organization — Pose — Formal and informal organization — Pose — Line and staff authority — departmentalised decentralization — Job Design - Human Reselection, Training and Development, Performant. DIRECTING Individual and group behaviour — motivation — Poses of communication — barrier — communication and IT. CONTROLLING The section of the productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivity problem is a strategic of the productivity problem in Management control — Productivit	organization che delega ource Management — Management — motivation theorem in communication communic	nart – tion cent – tion cent – t , Ca ories – ries ories or	org of au HR ureer - mo f lead -	tivatidersh effection	9 antional fity – nings ning 9 ional fity – ctive
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objective Technical Technical UNIT Nature structur centralis Recruits and many UNIT Founda technique communicommunicommunicommunicommunicommunicomput perform	and pure – typzation a ment, senageme FIV tions of ues – joinication nication TV and press a	organisms of the control of the cont	organization characteristics of the desired ource Management — motivation theoretypes and theoretypes and theoretypes and management — TOTAL: 4	nart – tion cent – tion cent – t , Ca ories – ries ories or	org of au HR ureer - mo f lead -	tivatidersh effection	9 antioral fity - ning ning 9 ional see of a anti-

	techniques.	
3.	Learn and impl	lement various organising methods.
4.	Gain knowledg	ge on different directing techniques.
5.	Analyse and lea	arn various types of controlling techniques.
TEX	T BOOKS:	
1.	JAF Stoner, Free Education, 200	eeman R.E and Daniel R Gilbert "Management", 6th Edition, Pearson 4.
2	Stephen P. Rob Edition, 2009.	bbins & Mary Coulter, "Management", Prentice Hall (India)Pvt. Ltd., 10th
3	Hill Charles W 2007.	T. L., "Principles of Management", Tata McGraw-Hill Education India,
REF	ERENCES:	
1.	Harold Koontz 1998.	& Heinz Weihrich, "Essentials of Management", Tata McGraw Hill,
2.	Tripathy PC &	Reddy PN, "Principles of Management", Tata Mcgraw Hill, 1999.
3.	Robert Kreitne	r&MamataMohapatra, "Management",Biztantra, 2008.
4.	_	obins & David A. Decenzo & Mary Coulter, "Fundamentals of , 7th Edition, Pearson Education, 2011.
5.	R. C. Bhatia, ".	Principles of Management", Sterling Publishers (25 February 2013).

		POs													
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1							2			3			2		
CO2							2			3			2		
CO3							2			3			2		
CO4							2			3			2		
CO5							2			3			2		
Average							2			3			2		
Round off							2			3			2		

18MP	E017	AUTOMOBILE ENGINEERING	L	Т	P	C
TOTVIL	2017	THE TOTAL DEPTH TO	3	0	0	3
OBJEC	CTIVI	ES:		Ů		
•		derstand the construction and working principle of various parts	of an	autoi	nobi	le.
•	To une	derstand assembling and dismantling of engine parts and transm	ission	syste	em.	
•		paden the understanding of automotive architecture and perform				
•	To int	roduce students about the transmission system.				
•		miliarize about the wheels, tyres, and braking system.				
UNIT	ГІ	VEHICLE STRUCTURE AND ENGINES				9
aerodyna	amics (obiles, vehicle construction and different layouts, chassis, fram various resistances and moments involved), IC engines –comp ble valve timing (VVT).		-		
UNIT	II '	ENGINE AUXILIARY SYSTEMS				9
injection system), ignition	systen Electr system	n (Unit injector system, Rotary distributor type and common ronic ignition system (Transistorized coil ignition system, col), Turbo chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS).	rail d apacit	irect ive c	injec lischa	arge
injection system), ignition converter UNIT Clutch-ty drive, tra	system Electr system r system III ypes an	onic ignition system (Transistorized coil ignition system, of the chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join	rail d apacit three	irect ive c way	injec lischa catal ms, C	tion arge ytic 9 Over
injection system), ignition s converter UNIT Clutch-ty drive, tra Different	system Electr system r system r system ypes an ansfer l tial and	onic ignition system (Transistorized coil ignition system, of the chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join I rear axle, Hotchkiss Drive and Torque Tube Drive.	rail deapacity three	irect ive c way	injec lischa catal ms, C	ytic 9 Over ints,
injection system), ignition sconverter UNIT Clutch-tydrive, tradifferent UNIT Steering Suspension	system Electr system r system r system ypes an ansfer l tial and IV geome goome	onic ignition system (Transistorized coil ignition system, of the chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join	rail deapacity three mechanis, un	anisiivers	injectische catal ms, Cal join	ytic 9 Over ints, 9 es of
injection system), ignition sconverter UNIT Clutch-tydrive, tradifferent UNIT Steering Suspension	system Electr system r system r system ypes an ansfer l tial and IV geome geome ton Sys c brake	conic ignition system (Transistorized coil ignition system, of the chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join a rear axle, Hotchkiss Drive and Torque Tube Drive. STEERING, BRAKES AND SUSPENSION SYSTEMS Stry and types of steering gear box-Power Steering, Types of Fitems, Pneumatic and Hydraulic Braking Systems, Antilock Bra	rail deapacity three mechanis, un	anisiivers	injectische catal ms, Cal join	ytic 9 Over ints, 9 es of
injection system), ignition system), ignition sconverter UNIT Clutch-tydrive, tradifferent UNIT Steering Suspensive electronic UNIT Use of NAutomob Character Cell Not	system Electr system r system	conic ignition system (Transistorized coil ignition system, of the control of the control of the control of the control of the construction, gear boxes - manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join a rear axle, Hotchkiss Drive and Torque Tube Drive. STEERING, BRAKES AND SUSPENSION SYSTEMS STEERING, BRAKES AND SUSPENSION SYSTEMS Stry and types of steering gear box-Power Steering, Types of Fetens, Pneumatic and Hydraulic Braking Systems, Antilock Brace force distribution (EBD) and Traction Control.	rail deapacity three mechanis, under the mechanism of the mechanism	anisi ivers	ms, Cal joint language Emiseles, I	ytic 9 Over ints, 9 os of BS), 9 n in sion Fuel
injection system), ignition system), ignition sconverter UNIT Clutch-tydrive, tradifferent UNIT Steering Suspensive electronic UNIT Use of NAutomob Character Cell Not	system Electr system r system	conic ignition system (Transistorized coil ignition system, of the control of the	rail deapacity three mechanis, under the mechanism of the mechanism	anismivers Axle, yster Hydend Vehice Tran	ms, Cal jor	ytic 9 Over ints, 9 n in sion Fuel sion
injection system), ignition system), ignition sconverter UNIT Clutch-tydrive, tradifferent UNIT Steering Suspensive electronic UNIT Use of NAutomob Character Cell Not	system Electr system r system	conic ignition system (Transistorized coil ignition system, co.), Turbo chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join rear axle, Hotchkiss Drive and Torque Tube Drive. STEERING, BRAKES AND SUSPENSION SYSTEMS etry and types of steering gear box-Power Steering, Types of Fetens, Pneumatic and Hydraulic Braking Systems, Antilock Brake force distribution (EBD) and Traction Control. ALTERNATIVE ENERGY SOURCES Gas, Liquefied Petroleum Gas, Bio-diesel, Bio-ethanol, Gason Engine modifications required —Performance, Combustion of SI and CI engines with these alternate fuels - Electric and Heatical Training in dismantling and assembling of Engine part be given to the students. TOTAL:	rail deapacity three mechanis, under the mechanism of the mechanism	anismivers Axle, yster Hydend Vehice Tran	ms, Cal jor	ytic 9 Over ints, 9 n in sion Fuel sion
injection system), ignition system), ignition sconverter UNIT Clutch-ty drive, tradifferent UNIT Steering Suspensive electronic UNIT Use of NAutomob Character Cell Not Systems and OUTCO	system Electr system r system	conic ignition system (Transistorized coil ignition system, co.), Turbo chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join rear axle, Hotchkiss Drive and Torque Tube Drive. STEERING, BRAKES AND SUSPENSION SYSTEMS etry and types of steering gear box-Power Steering, Types of Fetens, Pneumatic and Hydraulic Braking Systems, Antilock Brake force distribution (EBD) and Traction Control. ALTERNATIVE ENERGY SOURCES Gas, Liquefied Petroleum Gas, Bio-diesel, Bio-ethanol, Gason Engine modifications required —Performance, Combustion of SI and CI engines with these alternate fuels - Electric and Hencical Training in dismantling and assembling of Engine part be given to the students. TOTAL:	rail deapacity three mechanis, under the mechanism of the mechanism	anismivers Axle, yster Hydend Vehice Tran	ms, Cal jor	ytic 9 Over ints, 9 n in sion Fuel sion
injection system), ignition system), ignition sconverter UNIT Clutch-tydrive, tradifferent UNIT Steering Suspensive electronic UNIT Use of Nautomob Character Cell Not Systems and Cource 1.	system Electr system r system	conic ignition system (Transistorized coil ignition system, co.), Turbo chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join rear axle, Hotchkiss Drive and Torque Tube Drive. STEERING, BRAKES AND SUSPENSION SYSTEMS etry and types of steering gear box-Power Steering, Types of Fetens, Pneumatic and Hydraulic Braking Systems, Antilock Brake force distribution (EBD) and Traction Control. ALTERNATIVE ENERGY SOURCES Gas, Liquefied Petroleum Gas, Bio-diesel, Bio-ethanol, Gason Engine modifications required —Performance, Combustion of SI and CI engines with these alternate fuels - Electric and Hydraulical Training in dismantling and assembling of Engine part be given to the students. TOTAL: S: On completion of this course, students will be able to	rail deapacity three mechanis, under the mechanism of the mechanism	anismivers Axle, yster Hydend Vehice Tran	ms, Cal jor	ytic 9 Over ints, 9 n in sion Fuel sion

4. Learn the functions of steering, suspension and braking systems. 5. Analyse performance, combustion and emission characteristics of alternative fuels. **TEXT BOOKS:** Kirpal Singh, "Automobile Engineering", Vol. 1 & 2, Seventh Edition, Standard Publishers, NewDelhi, 1997. 2. Jain K.K. and Asthana .R.B, "Automobile Engineering" Tata McGraw Hill Publishers, NewDelhi, 2002. Ramalingam, K. K, "Automobile Engineering", Scitech Publications, 2014. 3. **REFERENCES:** Newton, Steeds and Garet, "Motor Vehicles", Butterworth Publishers, 1989. 1. 2. Joseph Heitner, "Automotive Mechanics", Second Edition, East-West Press, 1999. Martin W, Stockel and Martin T Stockle, "Automotive Mechanics Fundamentals", The 3. Goodheart -Will Cox Company Inc, USA, 1978. Heinz Heisler, "Advanced Engine Technology", SAE International Publications USA, 4. 1998. Ganesan V. "Internal Combustion Engines", Third Edition, Tata McGraw-Hill, 2007. 5.

MAPPIN	G OI	F CO	s, PO)s Al	ND P	SOs:									
						P	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2												3		
CO2	3					2							3		
CO3	3												3		
CO4	3												3		
CO5	3					3							3		
Average	2.8					1							3		
Round off	3					1							3		
3- Strong C	orrel	ation;	2 - N	Iediu	m Coi	rrelati	ion; 1	- Lo	w Coi	rrelati	on				

18M	PE018	ENERGY CONSERVARION AND MANAGEMENT	L	P	C	
			3	0	0	3
OBJE	CTIVE	S:				
•	To enal Manage	ole the students to understand the basic concepts of Energy Engement.	ineer	ing a	nd	
•	To carr	yout energy accounting and balancing.				
•	To cond	luct energy audit and suggest methodologies for energy savings	S.			
•	To utili	se the available resources in optimal ways.				
•	To und	erstand and analyse the energy data of industries.				
UNI	TII	NTRODUCTION				9
Enviror	mental a	 Past & Present scenario of World; National Energy conspects associated with energy utilization — Energy Audit Barriers. Role of Energy Managers. Instruments for energy audited 	ing:	Need		
UNI	L II I	CLECTRICAL SYSTEMS				9
Capacit Compu	ors, Pov tation, Er	EB billing – HT and LT supply, Transformers, Cable Seer Factor Improvement, Harmonics, Electric Motors - ergy Efficient Motors, Illumination – Lux, Lumens, Types of d scope of Energy conservation(encon.) in Illumination.	Mote	or E	Efficie	ency
UNIT		THERMAL SYSTEMS				9
measure	es. Stean	oilers, Furnaces and Thermic Fluid Heaters – Efficiency com n: Distribution & Usage: Steam Traps, Condensate Recor ators & Refractories.				
UNIT	r IV I	ENERGY CONSERVATION IN MAJOR UTILITI	ES			9
		owers, Compressed Air Systems, Refrigeration and Air Condition – D.G. sets.	oning	Syst	ems	_
UNI	T V I	ENERGY ECONOMICS				9
		cs – Discount Rate, Payback Period, Internal Rate of Return, Nong – ESCO concept.	et Pre	sent	Valu	e,
		TOTAL:	45 P	ER	IOD	S
	COMES		45 P	ER	IOD	S
			45 P	ER	IOD	S
OUTO	Apply th	On completion of this course, students will be able to	45 P	PER	IOD	S
OUT(Apply th	On completion of this course, students will be able to e energy utilization at national and international levels.	45 P	ER	IOD	S
OUT(Apply the Analyze Learn va	On completion of this course, students will be able to e energy utilization at national and international levels. various energy conservation techniques in electrical systems.	45 P	ER	IOD	S

TEX	T BOOKS:									
1.	Callaghan P.W Press, Oxford,	O, "Design and Management for Energy Conservation", Pergamon 2003.								
2.	Murphy W.R a	and McKay G, "Energy Management", Butterworths, London, 2007.								
3.	Paul W. O'Call	aghan, "Energy Management", McGraw-Hill Book Company, 1993.								
REF	ERENCES:									
1.		P.S. Schmidt, D.R. Brown, "Industrial Energy Management and Temisphere Publ, Washington, 1988.								
2.		ehart, Wayne C. Turner, William J. Kennedy, "Guide to Energy , TheFaimont Press, 6th edition, 2008 Hemisphere, 2003.								
3.	Dryden. I.G.C.	, "The Efficient Use of Energy", Butterworths, London, 1982.								
4.	Steve Doty, Wa edition, 2009.	syne C. Turner, "Energy Management Handbook", FairmontPress, 7th								
5.	Trivedi P.R and	d Jolka K.R, "Energy Management", Common Wealth Publication,2002.								

MAPPIN	G OI	F CO	s, Po	Os Al	ND P	SOs:									
	POs														
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	2												2		1
CO2	3					2							3		3
CO3	3					2							3		3
CO4	3					2							3		3
CO5	3					3							3		3
Average	2.8					1.8							2.8		2.6
Round off	3					2							3		3
3- Strong C	orrel	ation	; 2 - N	Iediu	m Co	rrelati	ion; 1	- Lo	w Co	rrelati	ion				1

18MP	E019		INDUSTRIAL ROBOTICS	5	L	T	P	C
						0	0	3
OBJEC	CTIV	ES:	1		I			
•	To ma	ake	the students to understand the basic concepts of	f robotics.				
•	To lea	arn t	the concepts and techniques of robot manipulate	or and its kine	ematic	s.		
•	To lea	arn t	the various end effectors and sensors.					
•	To un	ders	stand the Robots cell design and programming.					
•	To ex	plor	re the industrial applications of robot.					
UNIT	I	FU	JNDAMENTALS OF ROBOT					9
Classifica	ation-S	Spec	on - Robot Anatomy - Coordinate Systems cifications-Pitch, Yaw, Roll, Joint notations, Sp ctions-Need for Robots-Different Applications.	peed of Motio				
UNIT	II	R	OBOT DRIVE SYSTEMS AND END	EFFECTO	RS			9
Drives, I Magnetic	Motors End E Grip	s, A Effect pers	-Hydraulic Drives-Mechanical Drives-Electrica.C. Servo Motors-Salient Features, Application of the Grippers of	ons and Compumatic and Harree Fingered	pariso Hydraı	n of ılic	all tl Gripp	hes bers
Drives, 1 Magnetic Grippers	Motors End E C Grip and E III	s, A Effect pers xter SE	a.C. Servo Motors-Salient Features, Application ctors – Grippers-Mechanical Grippers, Pneus, Vacuum Grippers; Two Fingered and Thomal Grippers; Selection and Design Consideration CNSORS AND MACHINE VISION	ons and Comparatic and Faree Fingered ons.	pariso Hydrau Grip	n of alic pers;	all tl Gripp Inte	neso persorna 9
Drives, I Magnetic Grippers UNIT Requirem sensors – Range Se Finders, Complian Signal C Reduction	Motors End E Corip and E III ments c Piezo ensors, Laser nce Se convers n, Se	s, A Effective stern SE of a opele of a popele of a po	a.C. Servo Motors-Salient Features, Application ctors — Grippers-Mechanical Grippers, Pneus, Vacuum Grippers; Two Fingered and Thomal Grippers; Selection and Design Consideration	lowing types ders, pneumatic Approach, Tin Analog Sens asing and Dig e Processing ecognition,	pariso Hydrau Grip of sen ic Pos ne of ors, V itizing	n of alic pers; sorssition Fligh Vrist g Ima	All the Gripp Interpretation of the Position Senson, Range Daysis-I	9 ttiorsors ange
Drives, I Magnetic Grippers UNIT Requirem sensors – Range Se Finders, Complian Signal C Reduction	Motors End E Corip and E III ments o Piezo	s, A Effective states SE of a o-electric resistance Raisensons sion eegminspe	ctors – Grippers-Mechanical Grippers, Pneus, Vacuum Grippers; Two Fingered and Thomal Grippers; Selection and Design Consideration and Grippers; Selection and Design Consideration and Design Consi	lowing types of the Approach, Tine Analog Sense and Dig the Processing ecognition, Cation.	of sen ic Pos ne of ors, V itizing and	n of alic pers; sors- sition Fligh Vrist g Ima Anal	All the Gripp Interpretation of the Position Senson, Range Daysis-I	9 ttion sors ange sors ata
Drives, I Magnetic Grippers UNIT Requirem sensors — Range Se Finders, Compliar Signal C Reduction Applicati UNIT Forward Kinemati freedom Manipula programm	Motors End E Carip and E III ments of Piezo ensors, Laser nce Se convers n, Se cons-In IV Kiner ics of (in 3I ator M ming L	s, A Effectorers SE of a a D-electorers Rangematic matina D) J J J J J J J J J J J J J J J J J J J	ctors — Grippers-Mechanical Grippers, Pneus, Vacuum Grippers; Two Fingered and Thomal Grippers; Selection and Design Consideration and Grippers; Selection and Design Consideration and Design Consi	lowing types of the constant o	of sen ic Posme of ors, Vitizing and Other	sors- sition Fligh Vrist g Ima Anal Anal And and ar Do ory Conmin	All the Gripp Interest of Position Senson Se	9 tion sors ata Data ams 9 erse s or
Drives, I Magnetic Grippers UNIT Requirem sensors — Range Se Finders, Compliar Signal C Reduction Applicati UNIT Forward Kinemati freedom Manipula programm	Motors End E Grip and E III	s, A Effectorers SE of a O-electorers Rai enso sion egm mati ma O) J Iech ang sim	a.C. Servo Motors-Salient Features, Application of tors — Grippers-Mechanical Grippers, Pneus, Vacuum Grippers; Two Fingered and Thomal Grippers; Selection and Design Consideration of the following the sensor, Principles and Applications of the following Sensor, LVDT, Resolvers, Optical Encodingulations Principles, Structured, Lighting Ange Meters, Touch Sensors, Binary Sensors, rs, Slip Sensors, Camera, Frame Grabber, Sensors, Image Storage, Lighting Techniques, Image Intation, Feature Extraction, Object Rection, Identification, Visual Serving and Navigation, Inverse Kinematics and Difference; Formipulators with Two, Three Degrees of Freed Tacobians, Velocity and Forces-Manipulator Intanism Design-Derivations and problems. Leaguages-VAL Programming-Motion Commands,	lowing types of the constant of the cons. lowing types of the constant of the	of sen ic Pos ne of ors, Vitizing and Other	sors- sition Fligh Vrist g Ima Anal Anal And and ar Do ory Conmin	All the Gripp Interest of Position Senson Se	9 tion sors ata Data so oator obo
Drives, I Magnetic Grippers UNIT Requirem sensors – Range Se Finders, Compliar Signal C Reduction Applicati UNIT Forward Kinemati freedom Manipula programm command UNIT RGV, AG	Motors End E E Grip and E E III	s, A Effective sterile	a.C. Servo Motors-Salient Features, Application of tors — Grippers-Mechanical Grippers, Pneus, Vacuum Grippers; Two Fingered and Thomal Grippers; Selection and Design Consideration of the following the toric Sensor, Principles and Applications of the following Meters, Touch Sensors, Optical Encodingulations Principles, Structured, Lighting Ange Meters, Touch Sensors, Binary Sensors, rs, Slip Sensors, Camera, Frame Grabber, Sensor, Image Storage, Lighting Techniques, Image Intation, Feature Extraction, Object Rection, Identification, Visual Serving and Navigation, Inverse Kinematics and Difference; Formipulators with Two, Three Degrees of Freed Tacobians, Velocity and Forces-Manipulator Imaging Design-Derivations and problems. Leaguages-VAL Programming-Motion Commands, apple Programs.	lowing types of the constant o	of sen ic Pose ic Pose and Other MMII natics), Four ajector rogrammands	n of alic pers; sors-sition Fligh Vrist g Ima Anal Anal and ur Do ory Conmin s, End	Posis Sensont, Rassers Sensont, Rassers Sensont Sensont Senson Sensont Senson S	y tionsors angular particular par

OUTCOMES: On completion of this course, students will be able to

1.	On completion of this course, students will be able to analysing fundamentals of robotics.						
2.	Understand the design concepts of robot drives and end effectors.						
3.	Apply the concept of sensors and machine vision system.						
4.	Learn the concept of Robot kinematics and write robot programming.						
5.	Evaluate the safety and economics of robots.						
TEX	T BOOKS:						
1.	Klafter R.D., Chmielewski T.A and Negin M., "Robotic Engineering - An Integrated Approach", Prentice Hall, 2003.						
2.	Groover M.P., "Industrial Robotics -Technology Programming and Applications", McGraw Hill, 2001.						
3.	J. Norberto Pires., "Industrial Robots Programming" Springer, 2007.						
REF	ERENCES:						
1.	Craig J.J., "Introduction to Robotics Mechanics & Control", Pearson Education, 2008.						
2.	Deb S.R., "Robotics Technology and Flexible Automation" Tata McGraw Hill, 1994.						
3.	Koren Y., "Robotics for Engineers", McGraw Hill Book Co., 1992.						
4.	Rajput R.K., "Robotics and Industrial Automation", S. Chand and Company, 2008.						
5.	Janakiraman P.A., "Robotics and Image Processing", Tata McGraw Hill, 1995.						

	POs													PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	3	2	2	1	2								2	2		
CO2	3	2	2	2	2								2	2		
CO3	2	1	1	2	2								2	2		
CO4	3	2	2	2	1								2	2		
CO5	2	1	1	2	1								2	2		
Average	3	2	2	2	2								2	2		
Round off	3	2	2	2	2								3			

	PE020	COMPUTATIONAL FLUID DYNAMICS	L	T	P	\mathbf{C}
			3	0	0	3
OBJE	CTIVES	S:				
•		e the students understand the Governing Equations and boundar fluid dynamic problems.	ry coi	nditi	ons o	of
•	To intro	duce numerical modelling and its role in the field of fluid flow	and l	neat 1	rans	fer.
•		le the students to understand the various discretization methods res and turbulence modelling.	s, solı	ıtion		
•	To apply	y finite volume method for convection and diffusion problems.				
•	To analy	se the finite volume approach to discretize the governing equation	tions			
UNI		OVERNING EQUATIONS AND BOUNDARY CONDITIONS				9
Momen Time-a	ntum and H veraged o	tational fluid dynamics – Governing equations of fluid dynamics of the Energy equations – Chemical species transport – Physical bound equations for Turbulent Flow – Turbulent–Kinetic Energy earlier of PDEs on CFD - Elliptic, Parabolic and Hyperbolic equations of PDEs on CFD - Elliptic, Parabolic and Hyperbolic equations in the Energy equations of PDEs on CFD - Elliptic, Parabolic and Hyperbolic equations in the Energy equations of PDEs on CFD - Elliptic, Parabolic and Hyperbolic equations in the Energy equations of fluid dynamics – Governing equations of fluid dynamics – Physical Boundary equations of fluid dynamics – Physical Boundary equations of fluid dynamics – Physical Boundary equations – Physical Boundary equa	ndary ergy	cor Equ	ditic	ns -
UNI		INITE DIFFERENCE AND FINITE VOLUME IETHODS FOR DIFFUSION				9
		TETHODS FOR DIFFESTOR				
order a	occuracy – on problen	te difference equations – Simple Methods – General Methods f Finite volume formulation for steady state One, Two and T as –Parabolic equations – Explicit and Implicit schemes – I abolic equations – Use of Finite Difference and Finite Volume	hree Exam	–din ple	nensi	iona
order a diffusio onellipt	on problentic and part	te difference equations – Simple Methods – General Methods f Finite volume formulation for steady state One, Two and T ns –Parabolic equations – Explicit and Implicit schemes – I	hree Exam meth	–din ple ods.	nensi	iona
order a diffusio onellipt UNIT Steady properti	on problem tic and para TIII F D	te difference equations – Simple Methods – General Methods f Finite volume formulation for steady state One, Two and T as –Parabolic equations – Explicit and Implicit schemes – I abolic equations – Use of Finite Difference and Finite Volume	Three Exammeth NAN	-dimple ods. ND	prob	ionalem 9 eme
order a diffusio onellipt UNIT Steady properti	on problem tic and particle and	te difference equations – Simple Methods – General Methods frinite volume formulation for steady state One, Two and This –Parabolic equations – Explicit and Implicit schemes – Inabolic equations – Use of Finite Difference and Finite Volume INITE VOLUME METHOD FOR CONVECTION OIFFUSION Insional convection and diffusion – Central, upwind differetization schemes – Conservativeness, Boundedness, Transport	Three Exammeth NAN	-dimple ods. ND	prob	ionalem 9 eme
order a diffusion onellipte UNIT Steady properti Power-I UNIT Finite v Stagger	one-dimeries of disclaw, QUIC FIV F volume mered grid —	te difference equations – Simple Methods – General Methods frinite volume formulation for steady state One, Two and This –Parabolic equations – Explicit and Implicit schemes – Inabolic equations – Use of Finite Difference and Finite Volume INITE VOLUME METHOD FOR CONVECTION OIFFUSION Insional convection and diffusion – Central, upwind difference and schemes – Conservativeness, Boundedness, Transport Schemes.	Three Exammeth N AN	-dimple ods. ND cing eness	sche, Hy	9 on on on on on on on on on o
order a diffusion onellipt UNIT Steady propertification of the steady propertification of t	one-dimeries of disclaw, QUIC FIV F volume mered grid — on, SIMPLI	te difference equations – Simple Methods – General Methods frinite volume formulation for steady state One, Two and This – Parabolic equations – Explicit and Implicit schemes – Itabolic equations – Use of Finite Difference and Finite Volume INITE VOLUME METHOD FOR CONVECTION PROPERTION Insignal convection and diffusion – Central, upwind difference and schemes – Conservativeness, Boundedness, Transport Schemes. LOW FIELD ANALYSIS Ethods -Representation of the pressure gradient term and confidence in the pressure and Velocity corrections – Pressure and Velocity – Pressure and Velocity – Pressure and Velocity – Pressure – Pressure and Velocity – Pressure – Pressu	Three Exammeth NAN	—dinaple ods. ND cing eness ty edure C	sche, Hy	9 emeebric 9 on
order a diffusion onellipte UNIT Steady propertif Power-I UNIT Finite very stagger equation UNIT Turbule number	one-dimeries of disclaw, QUIC FIV F volume mered grid — on, SIMPLI TV T ence mode r models —	te difference equations – Simple Methods – General Methods frinite volume formulation for steady state One, Two and This –Parabolic equations – Explicit and Implicit schemes – Inabolic equations – Use of Finite Difference and Finite Volume INITE VOLUME METHOD FOR CONVECTION OFFUSION INITE VOLUME METHOD FOR CONVECTION OFFUSION Insional convection and diffusion – Central, upwind differentization schemes – Conservativeness, Boundedness, Transport K Schemes. LOW FIELD ANALYSIS Ethods -Representation of the pressure gradient term and common equations – Pressure and Velocity corrections – Pressure an	Three Exammeth NAN AN	-dimple ods. ND cing eness ty edure C	sche, Hy	9 emeebrica 9 on ectio 9 lls
order a diffusion onellipte UNIT Steady propertif Power-I UNIT Finite very stagger equation UNIT Turbule number	one-dimeries of disclaw, QUIC FIV F volume mered grid — on, SIMPLI TV T ence mode r models —	te difference equations – Simple Methods – General Methods frinite volume formulation for steady state One, Two and This –Parabolic equations – Explicit and Implicit schemes – Itabolic equations – Use of Finite Difference and Finite Volume INITE VOLUME METHOD FOR CONVECTION OFFUSION Insional convection and diffusion – Central, upwind difference and schemes – Conservativeness, Boundedness, Transport Schemes. LOW FIELD ANALYSIS Ethods -Representation of the pressure gradient term and common Momentum equations – Pressure and Velocity corrections – Petalgorithm and its variants – PISO Algorithms. URBULENCE MODELS AND MESH GENERAT Is, mixing length model, Two equation (k-€) models – High and	Three Exammeth NAN AN Serence ortive	ty edure C	sche, Hy	9 emebric 9 on octio 9 ds nt —

On completion of this course, students will be able toDerive governing equations of fluid

1.

	dynamics by applying different boundary conditions.
2.	Understand finite difference and volume methods for diffusion.
3.	Apply finite volume method to solve convection diffusion problems.
4.	Learn the concept of flow field analysis.
5.	Creating different turbulence models and grid generation.
TEX	T BOOKS:
1.	Versteeg, H.K., and Malalasekera, W., " An Introduction to Computational Fluid Dynamics: Thefinite volume method' , Pearson Education Ltd. 2 nd Edition, 2007.
2.	Ghoshdastidar, P.S., "Computer Simulation of flow and heat transfer", Tata McGraw Hill Publishing Company Ltd., 1998.
3.	Anil W. Date, "Introduction to computational fluid dynamics", Cambridge University Press, Cambridge, 2009.
REF	ERENCES:
1.	Patankar, S.V. "Numerical Heat Transfer and Fluid Flow", Hemisphere Publishing Corporation, 2004.
2.	Chung, T.J. "Computational Fluid Dynamics", Cambridge University, Press, 2002.
3.	Ghoshdastidar P.S., "Heat Transfer", Oxford University Press, 2005
4.	Muralidhar, K., and Sundararajan, T., "Computational Fluid Flow and Heat

MAPPING OF COs, POs AND PSOs:

Corporation, 2009.

						P	Os							PSO	s
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2	1	2								2	2	
CO2	3	2	1	2	2								2	2	
CO3	3	1	1	2	2								2	2	
CO4	3	2	1	2	1								2	2	
CO5	2	2	1	2	1								2	2	
Average	3	2	1	2	2								2	2	
Round off	3	2	1	2	2								2	2	

Suhas.V. Patankar, "Numerical Heat Transfer and Fluid Flow", Hemisphere Publishing

Transfer", NarosaPublishing House, New Delhi, 1995.

18M	PE021	DESIGN FOR MANUFACTURE, ASSEMBLY AND ENVIRONMENTS	L	Т	P	С				
			3	0	0	3				
OBJE	CTIVE	CS:								
•		ke the students to study the various factors influencing the manufacturing.	ıfactu	rabili	ity of	f				
•		cover the application of this study to various forging, casting, waning Processes.	elding	g and						
•	To help	To help the students to design features to facilitate machining.								
•	To mal	ke the students to design features to facilitate casting.								
•	To help	p the students to design the components by considering environ	menta	l fac	tors.					
UNI	TI	DESIGN PRINCIPLES FOR MANUFACTURABI	LIT	Y		9				
selectio	n, evalu	principles for manufacturability – strength and mechanical fa ation method, process capability – feature tolerances–geon –datum features – tolerance stacks.								
UNI	T II	FACTORS INFLUENCING FORM DESIGN				9				
		ole, material, manufacture, design- possible solutions - materials		ce -in	fluei	nce				
or mate	11413 011 1	form design - form design of welded members, forgings andcast	ings.							
UNIT		COMPONENT DESIGN - MACHINING	ings.			9				
UNIT Design counter amalgan for acco	features sunk scr mation - essibility		owelir - sim	nplifi bility	catio - de	ures, on by				
UNIT Design counter amalgan for acco	features sunk scr mation - essibility tic assemb	component design - machined area- simplification by separation design for machinability - design for conomy - design for clay - Design for assembly - Product design for manual assembly	owelir - sim	nplifi bility	catio - de	ures, on by				
UNITED Design counter amalgar for accounter automated UNITED Redesign machine	features sunk scrimation - essibility tic assemble of called holes,	to facilitate machining - drills - milling cutters - keyways - do rews - reduction of machined area- simplification by separation design for machinability - design foreconomy - design for clar - Design for assembly - Product design for manual assembly by - Robotic assembly.	owelir - sim ampal - Proc	nplifi bility luct o	catio - dedesign	ures, on by esign for 9 ents,				
UNITED Design counter amalgar for accounter automate UNITED Redesign machine	features sunk ser mation - essibility tic assemble of called holes, ing the do	to facilitate machining - drills - milling cutters - keyways - do rews - reduction of machined area- simplification by separation design for machinability - design foreconomy - design for clay - Design for assembly - Product design for manual assembly by - Robotic assembly. COMPONENT DESIGN - CASTING Estings based on parting line considerations - minimizing redesign of cast members to obviate cores. Identification of une	owelir a - sim ampal - Proc	nplifi bility luct o	catio - dedesign	ures, on by esign for 9 ents,				
Design counter amalgar for accounter automate UNIT Redesign machine modifying UNIT Introduce method	features sunk screamation - essibility tic assemble for the design of calculation and the design of th	to facilitate machining - drills - milling cutters - keyways - do rews - reduction of machined area- simplification by separation design for machinability - design foreconomy - design for clay - Design for assembly - Product design for manual assembly by - Robotic assembly. COMPONENT DESIGN - CASTING Estings based on parting line considerations - minimizing redesign of cast members to obviate cores. Identification of undesign - group technology.	owelir a - sim ampal - Proc core econor	requestion bility	iremal design	ures, on by esign of or of ents, ign of DFE ental				
Design counter amalgar for accounter automate UNIT Redesign machine modifying UNIT Introduce method impact	features sunk screamation - essibility tic assemble for the design of calculation and the design of th	to facilitate machining - drills - milling cutters - keyways - do rews - reduction of machined area- simplification by separation design for machinability - design foreconomy - design for clay - Design for assembly - Product design for manual assembly by - Robotic assembly. COMPONENT DESIGN - CASTING astings based on parting line considerations - minimizing redesign of cast members to obviate cores. Identification of undesign - group technology. DESIGN FOR ENVIRONMENT environmental objectives - global issues - regional and local in guidelines - lifecycle assessment method - techniques to red	owelir a - sim ampal - Proc core econor	requestion bility	irem l designation on mo	ures, on by esign for ents, ign -				
UNITI Design counter amalgan for account uNITI Redesign machine modifyi UNITI Introduce method impact manufae	features sunk screamation - essibility tic assemble of the case of	to facilitate machining - drills - milling cutters - keyways - do rews - reduction of machined area- simplification by separation design for machinability - design foreconomy - design for clay - Design for assembly - Product design for manual assembly by - Robotic assembly. COMPONENT DESIGN - CASTING astings based on parting line considerations - minimizing redesign of cast members to obviate cores. Identification of undesign - group technology. DESIGN FOR ENVIRONMENT environmental objectives - global issues - regional and local in guidelines - lifecycle assessment method - techniques to region energy efficiency - design to regulations and standards. Interpretation of the regulations and standards.	owelir a - sim ampal - Proc core econor	requestion bility	irem l designation on mo	ures, on by esign n for gents, ign -				
UNITI Design counter amalgan for account uNITI Redesign machine modifyi UNITI Introduce method impact manufae	features sunk screamation - essibility tic assemble of the case of	to facilitate machining - drills - milling cutters - keyways - do rews - reduction of machined area- simplification by separation design for machinability - design foreconomy - design for clay - Design for assembly - Product design for manual assembly - Design for assembly - Product design for manual assembly - Robotic assembly. COMPONENT DESIGN - CASTING Institute the state of	owelir a - sim ampal - Proc core econor	requestion PER	iremal designation of G	ures, on by esign for				

3.	Analyzing design for different aspects.
4.	Understand the components design involved in casting.
5.	Creating the components which are best suited for environment.
TEXT	T BOOKS:
1.	Robert Matousek, "Engineering Design- A systematic approach", Blackie& Sons ltd., 1963.
2.	Harry Peck, "Design for Manufacture", Pitman Publishers, 1983.
3.	O. Molloy, E.A. Warman, S. Tilley, "Design for manufacture assembly", Springer Science & Business Media. 1998.
REFE	ERENCES:
1.	Bralla, "Design for Manufacture handbook, McGraw hill, 1999.
2.	Boothroyd, G, "Design for Assembly Automation and Product Design". New York, Marcel Dekker, 1980.
3.	Swift, K.G., "Knowledge Based Design for Manufacture", Kogan Page Ltd., 1987.
4.	Alan Redford and Chal, "Design for Assembly-Principles and Procedures", McGraw Hill International Europe, London, 1994.
5.	James G.Bralla, "Hand Book of Product design for Manufacturing", McGraw Hill Co., 1986.

MAPPINO	MAPPING OF COs, POs AND PSOs:															
	POs													PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	3	2	2	1	2								2	2		
CO2	3	2	2	2	2								2	2		
CO3	2	2	3	2	2								2	2		
CO4	2	2	2	2	1								2	2		
CO5	3	2	2	2	2								2	2		
Average	3	2	2	2	2								2	2		
Round off	3	2	2	2	2								2	2		
3- Strong Co	orre	elatio	n; 2 -]	Mediu	ım Co	rrelat	tion; 1	- Lo	w Cor	relati	on					

18MP	E022		NANOTECHNOLOGY	L	T	P	C
				3	0	0	3
OBJE	CTIV	ES					
•	То	mal	ke the students to understand fundamental principles of nanon	nateri	als.		
•	То	und	erstand various properties of nanomaterials.				
•	То	fam	niliarise the characterisation techniques of nanomaterials.				
•	То	gaiı	n knowledge on various fabrication techniques.				
•	То	exp	lore various applications of nanomaterials.				
UNI	ΤΙ	FU	UNDAMENTAL PRINCIPLES				9
molecul intermo	les and lecular nalities	clu fo	cation of functional nano materials - size and scale - units, susters, supra molecules — nano scale phenomena - tunnelingorces, molecular and crystalline structure, hierarchical urfaces and interfaces, bulk to surface transition, self-associated and interfaces.	g, cho	emic ructu	al bo	onds, and
UNI	ГΙ	Pl	ROPERTIES OF NANOMATERIALS				9
calculat magneti	ion app	roa ertie					port,
UNIT			ANOMATERIAL CHARACTERISATION				9
			ent, operation of Scanning electron microscopy, electron probe con microscopy, Auger electron spectroscopy, , x-ray spectros			ppe,	
UNIT	ΓΙ	S	YNTHESIS OF NANOMATERIALS				9
nano lit metals:	thograp colloid	hy al į	ques: self-assembly, self-replication, sol - gels, Langmuir - I - bio inspired synthesis, micro fluidic processes, chemical gold, silver and metal clusters - semiconductors: cadmium nanotubes, nanocomposites, nanoporous materials, biological	vapo	our d nide,	epos silio	ition
UNI	ΤV	\mathbf{A}	PPLICATIONS OF NANOMATERIALS				9
			nano sensors - environmental - biological - energy storage and conment, heating and medical.	d fue	l cell	S	
			TOTAL:	45 I	PER	IOI	OS
OUTO	COME	S:	On completion of this course, students will be able to				
1.	Under	stan	d the fundamental principles of nanomaterials.				
2.	Learn	vari	ious properties of nanomaterials.				
3.	Get kn	ow	ledge on characterisation techniques of nanomaterials.				
4.	Explo	e v	arious fabrication techniques				
5.	Get kn	ow	ledge various applications of nanomaterials.				

TEX	T BOOKS:	
1.	Guozhongcao, Reference Book	"Nano Structured and Nano Materials", Imperial College Press, 2006.
2.	Chris Binns, "I 2011.	Introduction to Nanoscience and Nanotechnology", Wiley, 1st edition,
3.	Jeremy Rams edition,2011.	den ""Nanotechnology: An Introduction", William Andrew, 1st
REFE	ERENCES:	
1.	Gabor L. Horn CRC Press; 1 e	yak, John J. Moore, H.F. Tibbals, "Fundamentals of Nanotechnology", edition -2008
2.	Bharat Bhusha	n, "Handbook of Nanotechnology", Springer, 2004.
3.	Nalwa H.S., "I V, Academic P	Handbook of Nano Structured Materials and Nano Technology", Vol. I – ress,
4.		and Cammarata R.C., "Nanomaterials – Synthesis, Properties and Institute of Physics Publishing, London, 1998.
5.	Dreselhaus M., Academic Pres	S., Dreselhaus G., and Eklund P., "Science of Fullerines and Nano Tubes, s, 1996.

MAPPINO	G OF	COs	s, PO	s AN	D PS	SOs:										
	POs													PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	3	2	2	1	2								2	2		
CO2	3	2	1	2	2								3	2		
CO3	3	2	1	2	2								2	2		
CO4	3	1	1	2	1								2	3		
CO5	3	1	1	2	1								2	2		
Average	3	2	1	2	2								2	2		
Round off	3	2	1	2	2								2	2		
3- Strong Co	orrela	tion;	2 - M	ediun	ı Cor	relati	on; 1	– Lov	v Cor	relatio	on					

18MPl	E023	TOTAL QUALITY MANAGEMEN	NT	L	T	P	C
				3	0	0	3
OBJEC	CTIVE	S:					
•	To facil	itate the understanding of quality management princ	ciples and p	roces	s.		
•	To unde	erstand needs of various TQM principles.					
•	To acqu	tire knowledge on TQM tools and techniques.					
•	To impl	lement and assure Quality in Management.					
•	To acqu	ire knowledge about various quality standards					
UNIT	I	NTRODUCTION					9
quality.		-					
	ip - Stra	TQM PRINCIPLES ategic quality planning, Quality Councils - Employer Team and Teamwork, Quality circles Recognition					
Leadershi Empower appraisal-	ip - Stra rment, 7 - Contin		n and Rev	ward,	Per	form	tion,
Leadershi Empower appraisal-	ip - Stra rment, 7 - Conting,Suppli	ategic quality planning, Quality Councils - Employer Feam and Teamwork, Quality circles Recognition auous process improvement - PDCA cycle, 5S, Ka	n and Rev	ward,	Per	form	tion,
Leadershi Empower appraisal- Partnering UNIT	ip - Strarment, 7 - Conting, Supplie III Ten tradiology, ap	nategic quality planning, Quality Councils - Employer Team and Teamwork, Quality circles Recognition auous process improvement - PDCA cycle, 5S, Ka ier selection, Supplier Rating.	n and Revaluen - Suppose of Sixeding IT -	ward, oplier sigm	Peripart	form nersl	ance hip -
Leadershi Empower appraisal- Partnering UNIT	ip - Strarment, 7 - Conting, Supplie III 1 1 logy, applied bench	nategic quality planning, Quality Councils - Employer Feam and Teamwork, Quality circles Recognition and process improvement - PDCA cycle, 5S, Kaster selection, Supplier Rating. TQM TOOLS AND TECHNIQUES I attional tools of quality - New management tool poplications to manufacturing, service sector includes	n and Revaluen - Suppose of Sixeding IT -	ward, oplier sigm	Peripart	form nersl	tion, ance hip -
Leadershi Empower appraisal-Partnering UNIT The seve Methodol Reason to UNIT Control (QFD)	ip - Strarment, Tonting, Supplie III Ten tradiction to bench IV Tenerts - Taguchi	nategic quality planning, Quality Councils - Employer Feam and Teamwork, Quality circles Recognition arous process improvement - PDCA cycle, 5S, Kaster selection, Supplier Rating. TQM TOOLS AND TECHNIQUES I itional tools of quality - New management too pplications to manufacturing, service sector including mark, Bench marking process - FMEA - Stages, Typenson and Technique Policy (1988) and 1989 are process - FMEA - Stages, Typenson and Technique Policy (1988) and 1989 are process - FMEA - Stages, Typenson and Technique Policy (1988) and 1989 are process - FMEA - Stages, Typenson and Technique Policy (1988) and 1989 are process - FMEA - Stages, Typenson and Technique Policy (1988) and 1989 are process - FMEA - Stages, Typenson and Technique Policy (1988) and 1989 are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson and Technique Policy (1988) are process - FMEA - Stages, Typenson are process - FMEA - St	ols - Six ding IT - pes.	sigm Beno	Peripart	Conc	epts,
Leadershi Empower appraisal-Partnering UNIT The seve Methodol Reason to UNIT Control (QFD)	ip - Strarment, Tonting, Supplie III Ten tradicularly applied bench IV Tenerts - Taguchiment nee	ream and Teamwork, Quality Councils - Employer Team and Teamwork, Quality circles Recognition and Pocks improvement - PDCA cycle, 5S, Kather selection, Supplier Rating. TQM TOOLS AND TECHNIQUES I stional tools of quality - New management too pplications to manufacturing, service sector including mark, Bench marking process - FMEA - Stages, Type TQM TOOLS AND TECHNIQUES II Process Capability - Concepts of Six Sigma - Quality loss function - Total Productive Main	ols - Six ding IT - pes.	sigm Beno	Peripart	Conc	epts,
Leadershi Empower appraisal-Partnering UNIT The seve Methodol Reason to UNIT Control C (QFD) - improven UNIT Need for -QS 9000	ip - Strarment, 7 - Conting, Supplied III Ten tradialogy, applied bench IV Tenent need V CISO 9000 - ISO 1	ream and Teamwork, Quality Councils - Employer Team and Teamwork, Quality circles Recognition and process improvement - PDCA cycle, 5S, Kather selection, Supplier Rating. TQM TOOLS AND TECHNIQUES I stional tools of quality - New management too pplications to manufacturing, service sector includemark, Bench marking process - FMEA - Stages, Typer TQM TOOLS AND TECHNIQUES II Process Capability - Concepts of Six Sigma - Quality loss function - Total Productive Mainereds - Performance measures - TQM and TPM similaring and the similarity of the similarity of the section of the similarity of the section in the section of the section	ols - Six ding IT - bes. uality Functions.	sign Beno	Peripart na: (ch m Dev - (Conc	epts, ng -
Leadershi Empower appraisal-Partnering UNIT The seve Methodol Reason to UNIT Control C (QFD) - improven UNIT Need for -QS 9000	ip - Strarment, 7 - Conting, Supplied III Ten tradialogy, applied bench IV Tenent need V CISO 9000 - ISO 1	ream and Teamwork, Quality Councils - Employer Team and Teamwork, Quality circles Recognition arous process improvement - PDCA cycle, 5S, Karier selection, Supplier Rating. TQM TOOLS AND TECHNIQUES I Attional tools of quality - New management too oplications to manufacturing, service sector inclumants, Bench marking process - FMEA - Stages, Typer TQM TOOLS AND TECHNIQUES II Process Capability - Concepts of Six Sigma - Quality loss function - Total Productive Maintageds - Performance measures - TQM and TPM similarical PUALITY SYSTEMS 100 - ISO 9001-2008 Quality System - Elements, Docidation - Concepts, Requirements and Benefits - TQM and service sectors.	ols - Six ding IT - bes. uality Functions.	sign Beno	Peripart na: (ch m Dev ality n in	Conc narki elopi Conc	epts, ng - ment epts,
Leadershi Empower appraisal-Partnering UNIT The seve Methodol Reason to UNIT Control C (QFD) - improven UNIT Need for -QS 9000	ip - Strarment, To Conting, Supplie III To The tradiction of the continuous section of the conti	regic quality planning, Quality Councils - Employer Team and Teamwork, Quality circles Recognition and Pocks improvement - PDCA cycle, 5S, Karier selection, Supplier Rating. TQM TOOLS AND TECHNIQUES I ational tools of quality - New management too oplications to manufacturing, service sector inclumants, Bench marking process - FMEA - Stages, Typer TQM TOOLS AND TECHNIQUES II Process Capability - Concepts of Six Sigma - Quality loss function - Total Productive Mainteds - Performance measures - TQM and TPM similarical Pocks - TQM and TPM similarical Pocks - Pocks - Requirements and Benefits - TQM and service sectors. Total Process Capability - Concepts of Six Sigma - Quality System - Elements, Docks - Performance measures - TQM and TPM similarical Pocks - TQM and Service sectors.	ols - Six ding IT - Des. uality Functionance (Tities.	sign Beno	Peripart na: (ch m Dev ality n in	Conc narki elopi Conc	gepts, ge
Leadershi Empower appraisal-Partnering UNIT I The seven Methodol Reason to UNIT I Control (QFD) - improven UNIT Need for -QS 9000 manufact	ip - Strarment, Tontier g,Supplie III Ten tradiction to bench to be to bench to be to b	regic quality planning, Quality Councils - Employer Team and Teamwork, Quality circles Recognition and Pocks improvement - PDCA cycle, 5S, Karier selection, Supplier Rating. TQM TOOLS AND TECHNIQUES I ational tools of quality - New management too oplications to manufacturing, service sector inclumants, Bench marking process - FMEA - Stages, Typer TQM TOOLS AND TECHNIQUES II Process Capability - Concepts of Six Sigma - Quality loss function - Total Productive Mainteds - Performance measures - TQM and TPM similarical Pocks - TQM and TPM similarical Pocks - Pocks - Requirements and Benefits - TQM and service sectors. Total Process Capability - Concepts of Six Sigma - Quality System - Elements, Docks - Performance measures - TQM and TPM similarical Pocks - TQM and Service sectors.	ols - Six ding IT - Des. uality Functionance (Tities.	sign Beno	Peripart na: (ch m Dev ality n in	Conc narki elopi Conc	9 epts ng ment epts.
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5.	Understand the	international standards and TQM implementation.							
TEX	T BOOKS:								
1.	Dale H. Besterfiled, Et At., "Total Quality Management", Third Edition, Pearson Education Asia, Indian Reprint, 2006.								
2.	Poornima M. C Publications, 2	Charantimath, " Total Quality Management ", 2 nd Edition, Pearson 003							
3.	L. Suganthi, An New Delhi, 202	nand A. Samuel, "Total Quality Management", PHI Learning Pvt. Ltd.							
REF	ERENCES:								
1.		s and William M. Lindsay, "The Management and Control of Quality", at Indian Edition, Cengage Learning, 2012.							
2.	Suganthi.L and	Anand Samuel, "Total Quality Management", Prentice Hall. Ltd.,2006.							
3.		B and Gopal .R.K., "Total Quality Management - Text and Cases", India) Pvt. Ltd., 2006.							
4.	R. S. Naagaraz	an, "Total Quality Management", New Age International, 2005.							
5.	_	ard, Ghopal K. Khanji, Kai Kristensen "Fundamentals of Total Quality Taylor and Francis, 2002.							

MAPPIN	MAPPING OF COs, POs AND PSOs:															
	POs													PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	2	2			2					2	1		2	1		
CO2	2	2				2	2	2		3	1		2	1		
CO3	1	2			2		2			2	2		2	2		
CO4	1				1		2			2	1		1			
CO5	2					3	2			2	2		2			
Average	1.8	1.2			1	1	1.8			2	1.4		1.8	.8		
Round off	2	1			1	1	2			2	1		2	1		
3- Strong C	orrel	ation;	2 - N	Iediui	n Coi	relat	ion; 1	- Lo	w Coi	relati	on					

18MI	PE024	OPTIMIZATION TECHNIQ	UES	L	T	P	C
				3	0	0	3
OBJE	CTIVES	5:					
•	To make	the students to know the various unconstraine	d optimization t	echni	ques	.	
•	To famil	iarise the constrained optimization techniques.					
•	To impa	rt knowledge on advanced optimization technic	lues.				
•	To desig	n various static applications.					
•	To explo	ore different dynamic applications.					
UNI	TI U	NCONSTRAINED OPTIMIZATION	TECHNIQU	JES			9
minimiz method	zation – C	ons - Single variable and multivariable optimization of Solden section, Random, pattern and gradien on Solden section.	t search metho	ds –			ation
UNI		ONSTRAINED OPTIMIZATION TE					9
		equality and inequality constraints - Direct me Lagrange multipliers - Geometric programmin		t met	hods	usin	g
UNIT	TIII A	DVANCE OPTIMIZATION TECHN	IQUES				9
optimiz	ation, Ger	mization – dynamic programming; stochastinetic algorithms and Simulated Annealing tecoptimization.		-		•	
UNIT	TIV S'	TATIC APPLICATIONS					9
axial, to	ransverse	tions – Design of simple truss members - Desigloaded members for minimum cost, weight – Design of springs.					
UNI	TV D	YNAMIC APPICATIONS					9
•		tions – Optimum design of single, two degree of ation in Mechanisms – Optimum design of sim	•			tion	
			TOTAL:	45 P	ER	IOD	S
OUTO	COMES:	On completion of this course, students will be	e able to				
1.	Compare	different unconstrained optimization technique	es.				
2.	Learn the	constrained optimization techniques.					
3.	Gain kno	wledge about advanced optimization technique	s.				
	ъ.						
4.	Design ai	nd analyse various static applications.					

TEX	T BOOKS:	
1.		, S., "Engineering Optimization – Theory & Practice", New Age P) Limited, New Delhi, 2000.
2.	Chander Moha	n, Kusum Deep, "Optimization Techniques", New Age Science, 2009.
3.		K. Yadav, S. R. Yadav, "Optimization Techniques", I.K. International use Pvt. Limited, 2012.
REF	ERENCES :	
1.	-	nization for Engineering Design Algorithms and Examples'', Prentice-vt. Ltd., New Delhi, 1995.
2.	L. R. Foulds, "	Optimization Techniques: An Introduction", Springer, 1981.
3.	Cornelius T. Le February 1998	eondes, "Optimization Techniques", Academic Press; 1st edition (9
4.	_	., "Genetic algorithms in search, optimization and machine", Barnen, ey, New York, 1989.
5.	Johnson Ray, C	C., "Optimum design of mechanical elements", Wiley, John & Sons, 1990.

MAPPING	G OI	F CO	s, PC)s Al	ND P	SOs:	,								
						P	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2	2	1	2								2	2	
CO2	3	2	2	2	2								2	2	
CO3	2	2	3	2	2								2	2	
CO4	2	2	2	2	1								2	2	
CO5	3	2	2	2	2								2	2	
Average	3	2	2	2	2								2	2	
Round off	3	2	2	2	2								2	2	
3- Strong C	orrel	ation;	2 - N	Iediu	m Coi	rrelat	ion; 1	- Lo	w Coi	relati	ion		1		1

	E001		E	NGIN	IEE	RIN	IG E	ECO	NON	ЛС	S		L	T	P	C
0 = == 0		-~											3	0	0	3
OBJEC'																
• T	To mak	the s	tudents	to und	dersta	and th	he fur	ındam	ental	ecor	omic	conce	epts.			
• T	To acq	uire bas	sic knov	vledge	e on v	alue	engii	gineeri	ng.							
• T	To lear	n the d	ifferent	cash f	flow t	techni	niques	es.								
• T	To acq	uire bas	sic knov	vledge	e on d	differe	ent ty	types	of rep	lace	ment a	nd m	ainte	nance	analy	ysis.
• T	Γo lear	n the d	ifferent	depre	ciatio	on me	ethod	ds.								
UNIT	I	INTR	RODU'	ΓΙΟΝ	N TO	EC	CON	NOM	IICS							9
Break-eve Design se UNIT	election	1 for a 1		, Proce	ess pl	lannir	ng.	omic A	Analy	sis -	- Mate	erial s	select	ion fo	or pro	oduct 9
		nreser						oney,	Singl	e pa						ictor,
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3.	Unc	lersta	nd co	ncept	of cas	sh flov	V.									
4.	Unc	lersta	nd the	e type	of rep	olacen	nent a	nd ma	intena	ance a	nalysi	s.				
5.	Dec	ide w	when t	o repl	ace ar	asset	and u	ınders	tand t	he coi	ncept	of dep	reciati	ion.		
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1.	Sasi 200		Mishr	a, "Eı	ngine	ering	Econ	omics	and (Costir	ıg" Ea	stern	econo	my E	dition	,
2.	Pan 200		Selva	m, R,	"Eng	ineeri	ing E	conon	nics",	Prenti	ice Ha	ll of I	ndia L	td, N	ew De	lhi,
3.				Mana Publis	_		•			e", In	ternat	ional	Stude	nt Edi	tion,	
REFI	ERE	NCI	ES:													
1.	Rich 200		Pettin	ger, "	Masto	ering	Orgai	nizatio	onal B	Sehavi	our",	Масп	nillan	Press	,Lond	on,
2.		ındra hi, 19		, "Org	zaniza	itiona	l Beh	aviou	rs", V	ikas P	ublish	ing H	ouse l	Pvt. L	td.,Ne	w
3.				- Bell , Pren					_	-	t in E	ngine	ering	– Pri	nciple	S
4.	Bar	athw	al. R.	R, '' E	ngine	ering	Econ	omics	'', Ma	Graw	Hill,	1997.				
5.		id . dersl	A k.	han: 12	Engi	ineerii	ng B	Econo	ту,	''Eng	ineeri	ing	Econo	omy'',	Do	rling
MAPP	ING (OF C	COs, I	POs A	ND P	SOs:										
							P	Os							PSOs	 ;
		1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	L	2	1			2					3					2
CO2	2		2			2					3					2
CO3	3	1	1			2					3					2
CO4			2			2					3					2

3

3.0

3

3- Strong Correlation; 2 - Medium Correlation; 1-Low Correlation

2.0

2

CO5

0.6

1.6

2

Average

Round off

2.0

2

18MOE	E002	INDUSTRIAL ENGINEERING	L	T	P	C
			3	0	0	3
OBJEC'	TIVE	S:		•		
• T	o expla	in about various production system and various layouts.				
• T	o expla	in and provides knowledge on Process Planning and Control	•			
• T	o discu	ss on various types of work study and work measurement.				
• T	o discu	ss on various Inventory control techniques and material hand	lling	tech	niques	3.
• T	o expla	in the concept of system analysis and maintenance.				
TINITE	T T	DODITOTION OXOTEM				Δ.

UNIT I PRODUCTION SYSTEM

9

Industrial engineering - Concept, History and development, Applications, Roles of Industrial engineer. Production management, Industrial engineering versus production management, Operations Management. Production system — Analysis, Input output model, Productivity, Factors affecting productivity. Plant layout, Process layout, Product layout, Combination layout, fixed position layout, Flow pattern, and Workstation design

UNIT II | PROCESS PLANNING AND CONTROL

9

Process planning – definition, procedure, Process selection, Machine capacity, process sheet, process analysis, process chart – symbols, outline process chart, flow process chart. Group technology – functional and group layout, classification and coding system, formation of component family. Production planning, economic batch quantity, loading, scheduling. Production control – dispatching, routing. Progress control – bar, curve, gantt chart, route & schedule chart, line of balance

UNIT III WORK STUDY

9

Work study – definition, need, advantages, objectives of method study and work measurement, method study procedure, flow diagram, string diagram, multiple activity chart, operation analysis, analysis of motion, principles of motion economy, design of work place layout & ergonomics, therbligs, SIMO chart, stop watch procedure, micro & macro motion study. Predetermined motion time system, work sampling – principle, procedure.

UNIT IV | INVENTORY MANAGEMENT

9

Inventory – control, classification, management, objectives, functions. Economic order quantity, inventory models, ABC analysis, Material Requirement Planning(MRPI), Manufacturing Resource Planning(MRP II), Operating cycle, Just in Time manufacturing system, KANBAN technique, lean manufacturing, Supply chain management. Material handling – functions, principles, Engineering and economic factors, Material handling equipment – selection, maintenance, types.

UNIT V SYSTEM ANALYSIS AND MAINTENANCE

9

System concept - system analysis, systems engineering, techniques, applications. Value analysis – aim, technique, procedure, advantages, value engineering, value control, types of values. Reengineering, Business process re-engineering. Plant maintenance – objectives, importance, maintenance engineer – duties, functions and responsibilities. Types – breakdown, scheduled, preventive, predictive.

TOTAL: 45 PERIODS

OUT	COMES:	On completion of this course, students will be able to
1.	Design of Pl	ant layout and material handling system.
2.		luction planning and control activities such as work study, product planning, cheduling, Inventory Control.
3.	Explain the	ergonomics of manufacturing.
4.	Define the p	roductivity management system and inventory management.
5.	Understand t	the system analysis and maintenance.
TEX	T BOOKS:	
1.	O. P. Khann New Delhi,	a, "Industrial Engineering and Management", Dhanpat Rai and Sons, 2008
2.	Samuel Eilo Digitized, 20	n, "Elements of Production Planning and Control", McMillan and Co., 007.
3		sang, "Industrial Engineering and Production Management", First nand and Company, 2000
REF	ERENCES	
1.	J. A. Tompk	ins and J. A. White, "Facilities planning", John Wiley, 2010.
2.	Benjamin W	. Neibel, "Motion and time study", Richard .D .Irwin Inc., 2006.
3.	Hamdy M. T	Taha, "Operations Research, an Introduction", McMillan Co.,2008.
4.	Lee J. Kraje	wski, Larry P.Ritaman, "Operations Management", Addison Wesley,2007.
5.	Ravi Shanka Ltd, NewDe	r, " Industrial Engineering and Management ", Golgotia Publications Pvt lhi, 2009.

						P	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2			1					1			3	1	
CO2	3	1			2					1			3	2	
CO3	3	2	1		1								3	1	
CO4	3	2	2		1					2			3	1	
CO5	3	3	1		1					1			3	1	
Average	3.0	2.0	0.8		1.2					1.0			3.0	1.2	
Round off	3	2	1		1					1			3	1	

18MC	DE003	ENTREPRENEURSHIP DEVELOPMENT	L	T	P	C
			3	0	0	3
OBJE	CTIVE	S:		•		
•	To deve	elop and strengthen entrepreneurial quality and motivation in s	stud	ents.		
•	To impa	art basic entrepreneurial skills and understanding to run a busi	ness	s effi	ciently	у.
•	To unde	erstand the various business world.				
•	To acqu	nire the knowledge of finance and accounting.				
•	To unde	erstand the growth Strategies in small industry.				
UNI	TII	ENTREPRENEURSHIP				9
		Types of Entrepreneurs – Difference between Entrepreneur and in Economic Growth, Factors Affecting Entrepreneurial Growth		-	eneur	
UNI	ГП	MOTIVATION				9
Busines	s game	influencing an Entrepreneur – Achievement motivation ts, Thematic apperception Test – Stress Management ograms – Need, Objectives.				
UNIT		BUSINESS				9
		es – Definition, Classification – Characteristics, Ownership teps involved in setting up a Business – identifying, selectively Survey and Research, Tachno aconomic Feasibility Assas	ng a	ı Go	od Bu	siness
opportu of Preli	nity, Ma	teps involved in setting up a Business – identifying, selections and Research, Techno-economic Feasibility Assess Project Reports – Project Appraisal – Sources of Information	ng a	Go ent –	od Bu - Prepa	siness ration
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TEX	T BOOKS:	
1.	Khanka. S.S., 6 Delhi,2013.	Entrepreneurial Development" S.Chand & Co. Ltd., Ram Nagar, New
2.	Donald F Kura CengageLearn	tko, "Entreprenuership – Theory, Process and Practice" , 9 th Edition, ing, 2014.
3.	S. Anil Kumar Ltd.2003.	, "Entrepreneurship Development", New Age International Pvt.
REF	ERENCES:	
1.	Hisrich R D, P	eters M P, "Entrepreneurship" 8th Edition, Tata McGraw-Hill, 2013.
2.	Mathew J Man 2 nd Edition Dre	imala, "Enterprenuership theory at cross roads: paradigms and praxis", am tech, 2005.
3.	Rajeev Roy, " E	Entrepreneurship",2nd Edition, Oxford University Press, 2011.
4.	"Faulty and I Entrepreneurs	External Experts – A Hand Book for New Entrepreneurs Publishers: hip Development",2 nd Edition, Institute of India, Ahmadabad, 1986.
5.		n , "Enterpreneurship Development", Tata McGraw-Hill Publishing New Delhi, 2009

						P	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1					2					1	2	3			1
CO2					1				2	1	2	3			1
CO3					1				3	1	2	3			1
CO4					1					2	2	3			1
CO5					2					1	2	3			1
Average					1.4				1.0	1.2	2	3.0			1.0
Round off					1				1	1	2	3			1

18M(DE004	ELEMENTS OF PROJECT MANAGEMENT	L	T	P	C
			3	0	0	3
OBJE	CTIVE	S:				
•	To ena	ble the students to have overall view of project management to	echn	ique	S.	
•	To intr	oduce students to project definition, management techniques, jling.	plan	ning	and	
•	To und	erstand the commercial aspects of projects.				
•	To app utilizat	ly project management principles in business situations to option.	imiz	e res	ource	
•	To app	ly project management principles to time optimization.				
UNI	TI	PROJECT MANAGEMENT DEFINITIONS				9
	_	ment – Definition –Goal - Lifecycles. Project Selection Methor et Formulation. Project Manager – Roles- Responsibilities an				
UNI	T II	PLANNING AND BUDGETING				9
Project	- Metho	ocess – Work Break down Structure – Role of Multidisciplina ds. Cost Estimating and Improvement. Budget uncertainty and	•			nent.
Project UNIT	– Metho	ds. Cost Estimating and Improvement. Budget uncertainty and SCHEDULING & RESOURCE ALLOCATION	l risl	c mai	nagen	nent.
Project UNIT PERT & Gantt C	– Metho Γ III & CPM : Charts – F	ds. Cost Estimating and Improvement. Budget uncertainty and	l risl	mai nt – S	nagen	9 ation
Project UNIT PERT & Gantt C	- Metho F III & CPM Charts - F t's Critic	ds. Cost Estimating and Improvement. Budget uncertainty and SCHEDULING & RESOURCE ALLOCATION Networks - Crashing – Project Uncertainty and Risk Manage Expediting a project – Resource loading and levelling. Allocation	l risl	mai nt – S	nagen	9 ation
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Project UNIT PERT & Gantt C Goldrat UNIT The Pla control UNIT	- Metho Γ III & CPM Charts - F tt's Critic Γ IV In-Monito system. T V Organisa	ds. Cost Estimating and Improvement. Budget uncertainty and SCHEDULING & RESOURCE ALLOCATION Networks - Crashing – Project Uncertainty and Risk Manage Expediting a project – Resource loading and levelling. Allocating all Chain. CONTROL AND COMPLETION or-Control cycle – Data Collecting and reporting – Project Corproject Evaluation, Auditing and Termination. PROJECT ORGANISATION & CONFLICT	l risk	nt – Secarc	Simul e reso	9 ation urces 9 ng the
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Project UNIT PERT & Gantt C Goldrat UNIT The Pla control UNIT Formal Origin &	- Metho F III & CPM Charts - Entr's Critic F IV In-Monitor system. T V Organisa & Consect COMES Demonitor	SCHEDULING & RESOURCE ALLOCATION Networks - Crashing – Project Uncertainty and Risk Manage Expediting a project – Resource loading and levelling. Allocating all Chain. CONTROL AND COMPLETION Or-Control cycle – Data Collecting and reporting – Project Controject Evaluation, Auditing and Termination. PROJECT ORGANISATION & CONFLICT MANAGEMENT Intion Structure – Organisation Design – Types of project organ quences. Managing conflict – Team methods for resolving control to the completion of this course, students will be able to	emering someting some	ions.	Simul e reso	9 ation purces 9 ng the
Project UNIT PERT & Gantt C Goldrat UNIT The Pla control UNIT Formal Origin & OUT C 1.	- Metho F III CPM Charts - F It's Critic F IV In-Monito system. T V Organisa & Consect COMES Demonito Explain	SCHEDULING & RESOURCE ALLOCATION Networks - Crashing – Project Uncertainty and Risk Manage Expediting a project – Resource loading and levelling. Allocatinal Chain. CONTROL AND COMPLETION Or-Control cycle – Data Collecting and reporting – Project Corproject Evaluation, Auditing and Termination. PROJECT ORGANISATION & CONFLICT MANAGEMENT Intion Structure – Organisation Design – Types of project organ quences. Managing conflict – Team methods for resolving confluences. Managing conflict – Team methods for resolving co	emering someting some	ions.	Simul e reso	9 ation purces 9 ng the

5.	Explore commercial and legal aspects of projects.
TEX	Γ BOOKS:
1.	Clifford Gray and Erik Larson, "Project Management", Tata McGraw Hill Edition, 2005.
2.	John M. Nicholas, "Project Management for Business and Technology - Principles and Practice", Second Edition, Pearson Education, 2006.
3.	Grag and Lawron, (2006), "Project Management", Tata McGraw Hill.
REF	ERENCES:
1.	Reck and Crane, (2000), "Project Management", Wiley Eastern.
2.	Gido and Clements, "Successful Project Management", Second Edition, Thomson Learning, 2003.
3.	Harvey Maylor, " Project Management ", Third Edition, Pearson Education, 2006.
4.	Morris and Pritco, (2004), "Managing Projects", Wiley Eastern.
5.	Dennis Locke, (2000), "Project Management", Gower.

MAPPING (OF CO	Os, PO	Os AN	ID PS	Os:										
						P	Os						PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1					1	2				3			2		1
CO2					2	2				3			2		1
CO3					2	2				3			2		1
CO4					2	2				3			2		1
CO5					1	2				3			2		1
Average					1.6	2.0				3.0			2		1
Round off					2	2				3			2		1
3- Strong Co	orrelat	tion; 2	2 - M	edium	Corr	elatio	n; 1 -	- Low	Corr	elatio	n				

18MOE(006	NON DESTRUCTIVE TESTING AND MATERIALS	L	Т	P	C			
			3	0	3				
OBJECT	IVE	S:							
•	To study and understand the various Non-Destructive Evaluation and Testing methods.								
•	To le	arn the theory and industrial applications of NDT.							
_	To un	nderstand the concepts of thermography, eddy current testing ods.	and	surfa	ace NI	DΤ			
•	To ol	otain the knowledge on Ultrasonic testing and Acoustic Emiss	sion.						
•	To explore the principles of radiography.								
UNIT I	UNIT I OVERVIEW OF NDT								
• UNIT I	To ex	aplore the principles of radiography.			4la a .1 -				

Non-Destructive Testing Versus Mechanical testing, Overview of NDT Methods for the detection of manufacturing defects as well as material characterisation. Relative merits and limitations, Various physical characteristics of materials and their applications in NDT – Unaided and aided visual inspection.

UNIT II | SURFACE NDE METHODS

9

9

Liquid Penetrant Testing - Principles, types and properties of liquid penetrants, developers, advantages and limitations of various methods, Testing Procedure, Interpretation of results. Magnetic Particle Testing- Theory of magnetism, inspection materials Magnetisation methods, Interpretation and evaluation of test indications, Principles and methods of demagnetization, Residual magnetism.

UNIT III THERMOGRAPHY AND EDDY CURRENT TESTING

arrangement, Applications, advantages, Limitations, Interpretation/Evaluation.

Thermography- Principles, Contact and non-contact inspection methods, Techniques for applying liquid crystals, Advantages and limitation - infrared radiation and infrared detectors, Instrumentations and methods, applications. Eddy Current Testing-Generation of eddy currents, Properties of eddy currents, Eddy current sensing elements, Probes, Instrumentation, Types of

UNIT IV ULTRASONIC TESTING AND ACOUSTIC EMISSION 9

Ultrasonic Testing-Principle, Transducers, transmission and pulse-echo method, straight beam and angle beam, instrumentation, data representation, A-Scan, B-scan, C-scan. Phased Array Ultrasound, Time of Flight Diffraction. Acoustic Emission Technique —Principle, AE parameters, Applications.

UNIT V RADIOGRAPHY 9

Principle, interaction of X-ray with matter, imaging, film and film less techniques, types and use of filters and screens, geometric factors, Inverse square law, characteristics of films - graininess, density, speed, contrast, characteristic curves, Penetrometers, Exposure charts, Radio graphic equivalence. Fluoroscopy- Xero-Radiography, Computed Radiography, Computed Tomography.

			TOTAL: 45 PERIODS				
OUT	COMES:	On completion of this course, students will be	pe able to				
1.	Understan	ding need of Non-Destructive Testing method	ls.				
2.	Understan	ding the surface NDT methods.					
3.	Learn the	principles and operation of Thermography and	d Eddy current testing.				
4.	Analysing the Ultrasonic testing and Acoustic Emission.						
5.	Applying	the principle and operation of Radiography te	sting.				
TEX	т воок	S:					
1.		j, T. Jayakumar, M. Thavasimuthu, " Practica blishing House, 2009.	l Non-Destructive Testing",				
2.		ash, "Non-Destructive Testing Techniques" nal Publishers, 2010	, 1st revised edition, New Age				
3.		al Prasad, C. G. Krishnadas Nair," Non-Destr ", Tata McGraw-Hill Publishing Company Lt					
REF	ERENCE	S:					
1.		els Handbook, "Non-Destructive Evaluation o Metals, Metals Park, Ohio, USA, 200, Volum	~ ·				
2.		x, "Introduction to Non-destructive testing: a www.Jersey, 2005.	a training guide", Wiley, 2 nd				
3.	Charles, J.	Hellier, "Handbook of Nondestructive evaluatio	n" , McGraw Hill, New York 2001.				
4.	Barry Hul	l, Vernon John " Non-Destructive Testing", S	pringer, 1988.				
5.		Singh Wadhwa, Er. Harvinder Singh "A Tex ", Laxmi Publications, 1 st edition 2015.	tbook of Engineering Material				

						P	Os						PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2											3	1	
CO2	3	2	1										3	2	
CO3	3	2	1										3	2	
CO4	3	2	1										3	2	
CO5	3	2	1										3	2	
Average	3.0	2.0	0.8										3.0	1.8	
Round off	3	2	1										3	2	

18M(OE006	INTRIDUCTION TO AUTOMOBILE ENGINEERING	L	T	P	C		
			3	0	0	3		
OBJE	CTIVI	ES:						
•	To und	derstand the construction and working principle of various part	ts of an	auto	mob	ile.		
•	To und	derstand assembling and dismantling of engine parts and transr	mission	syst	em.			
•	To bro	oaden the understanding of automotive architecture and perform	nance.					
•	To int	roduce students about the transmission system.						
•	To fan	niliarize about the wheels, tires, and automotive air conditioning	ıg.					
UNI	TI	VEHICLE STRUCTURE AND ENGINES				9		
aerodyn	namics (obiles, vehicle construction and different layouts, chassis, frantvarious resistances and moments involved), IC engines – naterials - variable valve timing (VVT).		•				
injection system)	nically c n systen , Electr	ENGINE AUXILIARY SYSTEMS controlled gasoline injection system for SI engines, Electronic in (Unit injector system, Rotary distributor type and common onic ignition system (Transistorized coil ignition system,	n rail d capacit	irect ive	inje discl	ction narge		
Electror injection system) ignition converte	nically c n systen , Electr system er syster	controlled gasoline injection system for SI engines, Electronic in (Unit injector system, Rotary distributor type and commor onic ignition system (Transistorized coil ignition system,), Turbo chargers (WGT, VGT), Engine emission control by in, Emission norms (Euro and BS).	n rail d capacit	irect ive	inje discl	liesel ction narge alytic		
Electror injection system) ignition converte UNIT	nically con system y, Electr ysystem er system types an ransfer l	controlled gasoline injection system for SI engines, Electronic in (Unit injector system, Rotary distributor type and common onic ignition system (Transistorized coil ignition system,), Turbo chargers (WGT, VGT), Engine emission control by	n rail d capacit y three ft mech	irect ive way	injedisch cata	liesel ction narge alytic 9		
Electror injection system) ignition converte UNIT	nically con system respectively, Electrical system respectively respec	controlled gasoline injection system for SI engines, Electronic (Unit injector system, Rotary distributor type and common onic ignition system (Transistorized coil ignition system,), Turbo chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join	n rail d capacity three ft mecl ints, ur	irect ive way manis	injedisch cata	liesel ction narge alytic 9		
Electror injection system) ignition converted UNIT Clutch-tdrive, transfer UNIT Steering Suspens	nically con system references system references system ransfer lential and riv g geome sion Sys	controlled gasoline injection system for SI engines, Electronic (Unit injector system, Rotary distributor type and commor onic ignition system (Transistorized coil ignition system,), Turbo chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS ad construction, gear boxes- manual and automatic, gear ship box, fluid flywheel, torque converter, propeller shaft, slip join rear axle, Hotchkiss Drive and Torque Tube Drive.	rail decapacity three ft mechanists, ur	nanis aivers	ms, sal jo	liesel ction narge alytic 9 Overpints, 9 es of		
Electror injection system) ignition converted UNIT Clutch-tdrive, transfer UNIT Steering Suspens	nically con system system er system types and ransfer land of IV g geome sion System system from the system of IV g geome sion System from	controlled gasoline injection system for SI engines, Electronic (Unit injector system, Rotary distributor type and common onic ignition system (Transistorized coil ignition system,), Turbo chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS ad construction, gear boxes- manual and automatic, gear ship box, fluid flywheel, torque converter, propeller shaft, slip join rear axle, Hotchkiss Drive and Torque Tube Drive. STEERING, BRAKES AND SUSPENSION SYSTEMS try and types of steering gear box-Power Steering, Types of Items, Pneumatic and Hydraulic Braking Systems, Antilock Braking Syst	ft mechints, ur TEMS Front A aking S	nanis nivers	ms, sal jo	liesel ction narge alytic 9 Overpints, 9 es of		
Electror injection system) ignition converted UNIT Clutch-tdrive, transported UNIT Steering Suspense electron UNIT Automorims, Comodific	nically constructions of the construction	controlled gasoline injection system for SI engines, Electronical (Unit injector system, Rotary distributor type and common onic ignition system (Transistorized coil ignition system,), Turbo chargers (WGT, VGT), Engine emission control by m, Emission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join rear axle, Hotchkiss Drive and Torque Tube Drive. STEERING, BRAKES AND SUSPENSION SYSTEMS try and types of steering gear box-Power Steering, Types of tems, Pneumatic and Hydraulic Braking Systems, Antilock Brake force distribution (EBD) and Traction Control. AUTOMOTIVE AIR CONDITIONING, WHEEL	ft mechints, un TEMS Front A aking S S, TII pes of gy sou	nanis axle, System RES	ms, sal jo	liesel ction harge alytic 9 Over pints, 9 es of aBS), 9		
Electror injection system) ignition converte UNIT Clutch-t drive, tr Differer UNIT Steering Suspens electron UNIT Automorims, Comodific	nically constructions of the construction	controlled gasoline injection system for SI engines, Electronical (Unit injector system, Rotary distributor type and common onic ignition system (Transistorized coil ignition system, and ignition system, by Turbo chargers (WGT, VGT), Engine emission control by the Emission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join rear axle, Hotchkiss Drive and Torque Tube Drive. STEERING, BRAKES AND SUSPENSION SYSTEMS try and types of steering gear box-Power Steering, Types of the Emission (EBD) and Traction Control. AUTOMOTIVE AIR CONDITIONING, WHEEL AND ALTERNATIVE ENERGY SOURCES conditioning - Wheels and tires: Wheel quality, assembly, type tion of tires and tire specifications - Alternative Energy equired —Performance, Combustion and Emission Character.	ft mechints, un TEMS Front A aking S S, TII pes of gy souristics	nanis axle, system RES	ms, sal jo	liesel ction harge alytic 9 Over pints, 9 es of ABS), 9 wheel agine d CI		
Electror injection system) ignition converte UNIT Clutch-t drive, tr Differer UNIT Steering Suspens electron UNIT Automorims, C modific engines	nically constructions of the construction	controlled gasoline injection system for SI engines, Electronic in (Unit injector system, Rotary distributor type and commor onic ignition system (Transistorized coil ignition system, and ignition system), Turbo chargers (WGT, VGT), Engine emission control by the mission norms (Euro and BS). TRANSMISSION SYSTEMS and construction, gear boxes- manual and automatic, gear shift box, fluid flywheel, torque converter, propeller shaft, slip join rear axle, Hotchkiss Drive and Torque Tube Drive. STEERING, BRAKES AND SUSPENSION SYSTEMS try and types of steering gear box-Power Steering, Types of the stems, Pneumatic and Hydraulic Braking Systems, Antilock Brakes force distribution (EBD) and Traction Control. AUTOMOTIVE AIR CONDITIONING, WHEEL AND ALTERNATIVE ENERGY SOURCES conditioning - Wheels and tires: Wheel quality, assembly, type tion of tires and tire specifications - Alternative Energe equired —Performance, Combustion and Emission Character esse alternate fuels - Electric and Hybrid Vehicles, Fuel Cell. TOTAL	ft mechints, un TEMS Front A aking S S, TII pes of gy souristics	nanis axle, system RES	ms, sal jo	liesel ction harge alytic 9 Over pints, 9 es of ABS), 9 wheel agine d CI		

2.	Evaluating the various engine auxiliary systems.
3.	Understand components of transmission systems.
4.	Learn the functions of steering, suspension, braking systems, wheels and tires.
5.	Analysing performance, combustion and emission characteristics of alternative fuels
TEX	T BOOKS:
1.	Kirpal Singh, "Automobile Engineering", Vol. 1 & 2, Seventh Edition, Standard Publishers, NewDelhi, 1997.
2.	Jain K.K. and Asthana .R.B, "Automobile Engineering" Tata McGraw Hill Publishers, NewDelhi, 2002.
3.	Ramalingam, K. K, "Automobile Engineering", Scitech Publications, 2014.
REF	ERENCES:
1.	Newton, Steeds and Garet, "Motor Vehicles", Butterworth Publishers, 1989.
2.	Joseph Heitner, "Automotive Mechanics", Second Edition, East-West Press, 1999.
3.	Martin W, Stockel and Martin T Stockle, "Automotive Mechanics Fundamentals", The Goodheart –Will Cox Company Inc, USA, 1978.
4.	Heinz Heisler, "Advanced Engine Technology", SAE International Publications USA, 1998
5.	Ganesan V. "Internal Combustion Engines", Third Edition, Tata McGraw-Hill, 2007.

MAPPING	OF C	Os, P	Os Al	ND PS	SOs:										
						PO	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2											3	2	
CO2	3	2											2	3	
CO3	3	2			1	2							3	2	
CO4	3	2											3	2	
CO5	3	2		3	2	3							3	2	3
Average	3.0	2.0		0.6	0.6	1.0							2.8	2.2	0.6
Round off	3	2		1	1	1							3	2	1
3- Strong C	orrela	tion;	2 - M	ediun	ı Corı	relatio	on; 1 -	- Low	v Cor	relatio	n				

18MOE	2007	INDUSTRIAL AUTOMATION	L	T	P	\mathbf{C}	
			3	0	0	3	
OBJECT	IVES						
•	To make	the students to understand basics of industrial automation.					
•	To explo	re various types of sensors and transducers.					
•	To get k	nowledge on electrical drives and machine vision system.					
•	To progr	amme programmable logic controllers.					
•	To desig	n simple mechatronics systems.					
UNIT I	INT	RODUCTION TO AUTOMATION				9	
Automation	– Elen	on - General Aspects – Advantages and Limitations of Automatic nents of Automation – Aims of Automation – Mechanisation a n – Low Cost Automation – Assembly Automation Equipment.					
UNIT II	T II SENSORS AND TRANSDUCERS 9						
temperature	measu	nant transducers- optical measurement systems-encoders, pho c transducers- solid state sensors and transducers-magnet rements, Chemical measurements-piezoelectric – accelerome	ic r	neas	urem	ents,	
UNIT III Electromag Signal proc Integral, De	ELE netic Pressing, A	c transducers- solid state sensors and transducers-magnetic rements, Chemical measurements-piezoelectric – accelerometers- flow, distance, velocity measurements. CTRICAL DRIVES AND MACHINE VISION Inciples, Solenoids and Relays, Electrical drives -stepper mote A/D and D/A converters – Introduction to Data acquisition systematical and PID controller – Microcontroller. Introduction to machine	ors, em -	serve Pro	urem ultras o mo portio syste	ents, conic 9 tors. conal, em -	
UNIT III Electromag Signal proc Integral, De	ELE netic Pressing, Activative ame Gra	c transducers- solid state sensors and transducers-magnetic rements, Chemical measurements-piezoelectric – accelerometers- flow, distance, velocity measurements. CTRICAL DRIVES AND MACHINE VISION Inciples, Solenoids and Relays, Electrical drives -stepper mote A/D and D/A converters – Introduction to Data acquisition system and PID controller – Microcontroller. Introduction to machine beer, Sensing and Digitizing Image Data- Lighting Techniques,	ors, em -	serve Pro	urem ultras o mo portio syste	ents, conic 9 tors. conal, em -	
temperature sensors and UNIT III Electromag Signal proc Integral, De Camera, Fr	ELE netic Pressing, Appli	c transducers- solid state sensors and transducers-magnetic rements, Chemical measurements-piezoelectric – accelerometers- flow, distance, velocity measurements. CTRICAL DRIVES AND MACHINE VISION Inciples, Solenoids and Relays, Electrical drives -stepper mote A/D and D/A converters – Introduction to Data acquisition system and PID controller – Microcontroller. Introduction to machine beer, Sensing and Digitizing Image Data- Lighting Techniques,	ors, em -	serve Pro	urem ultras o mo portio syste	ents, conic 9 tors. conal, cem -	
temperature sensors and UNIT III Electromag Signal proce Integral, De Camera, Frand Analyst UNIT IV Programma Modules - 1	ELE netic Pressing, Activative ame Grais, Appli PRO ble logic Mnemon	c transducers- solid state sensors and transducers-magnetic rements, Chemical measurements-piezoelectric – accelerometers- flow, distance, velocity measurements. CTRICAL DRIVES AND MACHINE VISION Inciples, Solenoids and Relays, Electrical drives -stepper mote A/D and D/A converters – Introduction to Data acquisition systematical and PID controller – Microcontroller. Introduction to machine ber, Sensing and Digitizing Image Data- Lighting Techniques, cations.	ors, em - ne vi Ima	serve Pro- sion age P	o mo portio syste roces - Ou	ents, conic 9 tors. onal, em - ssing 9 itput and	
temperature sensors and UNIT III Electromag Signal proce Integral, De Camera, Frand Analyst UNIT IV Programma Modules - 1	ELE netic Pressing, Appli PRO ble logio Mnemon rols -Pro	c transducers- solid state sensors and transducers-magnetic rements, Chemical measurements-piezoelectric – accelerometers- flow, distance, velocity measurements. CTRICAL DRIVES AND MACHINE VISION Inciples, Solenoids and Relays, Electrical drives -stepper mote A/D and D/A converters – Introduction to Data acquisition systematical and PID controller – Microcontroller. Introduction to machine ber, Sensing and Digitizing Image Data- Lighting Techniques, cations. GRAMMABLE LOGIC CONTROLLERS C controller – Basic structure - Programming units - Memory ics – Latching- Timers – Internal relays - Counters – Shift Regional Controller – Shift Reg	ors, em - ne vi Ima	serve Pro- sion ige P	o mo portio syste roces - Ou	ents, conic 9 tors. conal, cem - ssing 9 utput and	
UNIT IV Programma Modules - J Jump Contr UNIT V Mechatroni Place robot	ransductransdu	c transducers- solid state sensors and transducers-magnetic rements, Chemical measurements-piezoelectric – accelerometers- flow, distance, velocity measurements. CTRICAL DRIVES AND MACHINE VISION Inciples, Solenoids and Relays, Electrical drives -stepper mote A/D and D/A converters – Introduction to Data acquisition systematical and PID controller – Microcontroller. Introduction to machine beer, Sensing and Digitizing Image Data- Lighting Techniques, cations. GRAMMABLE LOGIC CONTROLLERS C controller – Basic structure - Programming units - Memory ics – Latching- Timers – Internal relays - Counters – Shift Registers amming the PLC using Ladder diagram -Simple example of PL	ors, em - ne vi Ima I L A TIO Catio catio cer n	serve Production	o mo portio syste roces - Ou Iaster ation	tors. onal, em - ssing putput and and trol-	
temperature sensors and UNIT III Electromag Signal proceed Integral, De Camera, Frand Analys UNIT IV Programma Modules - Jump Control UNIT V Mechatroni Place robot Traffic Control Co	ransductransdu	c transducers- solid state sensors and transducers-magneterements, Chemical measurements-piezoelectric – accelerometers- flow, distance, velocity measurements. CTRICAL DRIVES AND MACHINE VISION Inciples, Solenoids and Relays, Electrical drives -stepper mote A/D and D/A converters – Introduction to Data acquisition systemater and PID controller – Microcontroller. Introduction to machine beer, Sensing and Digitizing Image Data- Lighting Techniques, cations. GRAMMABLE LOGIC CONTROLLERS C controller – Basic structure - Programming units - Memory ics – Latching- Timers – Internal relays - Counters – Shift Regingramming the PLC using Ladder diagram -Simple example of PLCHATRONICS SYSTEM DESIGN AND APPLICATE gineering Design, Traditional and mechatronics design, Applicated barriers, Bar code reader, Wind screen wiper wing stepp	ors, em - In isters C ap TIO cation ers, I	serve Produced Produced Produc	o morportion system of twalends of twalend	tors. onal, em - ssing g atput and and trol- king	
temperature sensors and UNIT III Electromag Signal proceed Integral, De Camera, Frand Analys UNIT IV Programma Modules - Jump Control UNIT V Mechatroni Place robot Traffic Control Co	ELE netic Pressing, Applied PRO ble logic Mnemon rols -Program ME(can be served by the served by t	c transducers- solid state sensors and transducers-magnet rements, Chemical measurements-piezoelectric – accelerometers- flow, distance, velocity measurements. CTRICAL DRIVES AND MACHINE VISION Inciples, Solenoids and Relays, Electrical drives -stepper mote A/D and D/A converters – Introduction to Data acquisition system and PID controller – Microcontroller. Introduction to machine beer, Sensing and Digitizing Image Data- Lighting Techniques, cations. GRAMMABLE LOGIC CONTROLLERS C controller – Basic structure - Programming units - Memory ics – Latching- Timers – Internal relays - Counters – Shift Regingeramming the PLC using Ladder diagram -Simple example of PLC CHATRONICS SYSTEM DESIGN AND APPLICATE gineering Design, Traditional and mechatronics design, Applications bears are code reader, Wind screen wiper wing stepperface - IOT applications – Industry 4.0. Case studies: Coin counters	ors, em - In isters C ap TIO cation ers, I	serve Produced Produced Produc	o morportion system of twalends of twalend	tors. onal, em - ssing g atput and and trol- king	
temperature sensors and UNIT III Electromag Signal proceed Integral, De Camera, Frand Analys UNIT IV Programma Modules - Jump Control UNIT V Mechatroni Place robot Traffic Commachine.	remeasure transduction transduc	c transducers- solid state sensors and transducers-magnet rements, Chemical measurements-piezoelectric – accelerometers- flow, distance, velocity measurements. CTRICAL DRIVES AND MACHINE VISION Inciples, Solenoids and Relays, Electrical drives -stepper mote A/D and D/A converters – Introduction to Data acquisition system and PID controller – Microcontroller. Introduction to machine between the property of the	ors, em - In isters C ap TIO cation ers, I	serve Produced Produced Produc	o morportion system of twalends of twalend	tors. onal, em - ssing g atput and and trol- king	

3. Compare the different actuation systems, controllers and machine vision systems 4. Understand the PLC and develop programs using ladder logic. Design the mechatronics systems for various applications. 5. **TEXT BOOKS:** Bolton.W, "Mechatronics", Addison Wesley, 4th Edition, New Delhi, 2010. 1. 2. Bradley.D.A, Dawson.D Burd N.C.and Loader A.J, "Mechatronics", Chapman and Hall Publications, New York, 1993. Rajput R.K., "Robotics and Industrial Automation", S.Chand and Company, 2008. 3. **REFERENCES:** Janakiraman P.A., "Robotics and Image Processing", Tata Mc Graw Hill, 1995. 1. 2. David W. Pessen, "Industrial Automation Circuit Design and Components", John Wiley, New York, 1990. Rohner.P, "Automation with Programmable Logic Controllers", Macmillan /McGraw Hill, 3. New York, 1996. Brian Morris, "Automatic Manufacturing Systems Actuators, Controls and Sensors", 4. McGraw Hill, New York, 1994. Jacob Fraden, "Handbook of Modern Sensors Physics, Designs, and Applications", Third 5. Edition, Springer-Verlag New York, 2004.

MAPPING OF	COs,	POs	AND	PSOs	:										
						P	Os							PSOs	
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
CO1	3	2											3	1	
CO2	3	2		2									3	1	
CO3	3	3		1									3	1	
CO4	3	3	1	2									3	2	
CO5	3	2	3	1									3	2	
Average	3.0	2.4	0.8	1.2									3.0	1.4	
Round off	3	2	1	1									3	1	
3- Strong Corr	elatio	n; 2 -	Medi	um C	orrela	tion;	1 – L	ow Co	orrela	tion					

191/101	E008	INTRODUCTION TO COMPOSITE MATERIALS	\mathbf{L}	T	P	\mathbf{C}
			3	0	0	3
OBJEC	CTIVE	CS:				
•	To en	able the students to understand the properties and design of composite	e ma	terial	s.	
•	To far	niliarize the different type of polymer matrix composites.				
•	To un	derstand the various manufacturing techniques for metal matrix comp	osite	es.		
•	To stu	dy the various manufacturing methods for ceramic matrix composites	s.			
•	To un	derstand the geometrical aspects in Composite Materials.				
UNIT		NTRODUCTION TO REINFORCEMENT AND MATRI NTERFACE	RIX			12
Propertie	es – Ap s – Proj	 Fibres – Glass fibre, Aramid fibre, Carbon fibre, boron fibre plications – Comparison of fibres – Particulate and whisker reinforerties. Wettability – Effect of surface roughness – Interfacial bondistrength. 	orcei	ments	s. M	atrix
UNIT	II P	OLYMER MATRIX COMPOSITES				8
	D					
moulding	n, resin g, film	ing – Thermal matrix composites – Hand layup and spray technique, transfer moulding, autoclave moulding – Thermoplastic matrix comstacking – Diaphragm forming – Thermoplastic tape laying. Glanical properties – Fracture. Applications.	posi	tes –	Inje	ctio
moulding	n, resing, film	transfer moulding, autoclave moulding – Thermoplastic matrix comstacking – Diaphragm forming – Thermoplastic tape laying. Gl	posi	tes –	Inje	ctio
moulding interface. UNIT I Types. Ir	n, resing, film . Mecha	transfer moulding, autoclave moulding – Thermoplastic matrix compatacking – Diaphragm forming – Thermoplastic tape laying. Glanical properties – Fracture. Applications.	posi ¹	tes – fibre	Injed/poly	ction yme
moulding interface. UNIT I Types. Ir Titanium	n, resing, film . Mecha III M mportar	transfer moulding, autoclave moulding – Thermoplastic matrix com- stacking – Diaphragm forming – Thermoplastic tape laying. Glanical properties – Fracture. Applications. IETAL MATRIX COMPOSITES It metallic matrices. Processing – Solid state, liquid state, deposition,	posi ¹	tes – fibre	Injed/poly	ction yme
moulding interface. UNIT I Types. Ir Titanium UNIT I Ceramic insitu ch	n, resing, film. Mechanism	transfer moulding, autoclave moulding – Thermoplastic matrix compatacking – Diaphragm forming – Thermoplastic tape laying. Glanical properties – Fracture. Applications. IETAL MATRIX COMPOSITES It metallic matrices. Processing – Solid state, liquid state, deposition, acc. Mechanical properties. Applications.	positilass insit	tes – fibre u. Sio	Inject/poly	8 re /
moulding interface. UNIT I Types. Ir Titanium UNIT I Ceramic insitu ch	matrix a matrix a matrix b G	transfer moulding, autoclave moulding – Thermoplastic matrix compatacking – Diaphragm forming – Thermoplastic tape laying. Glanical properties – Fracture. Applications. IETAL MATRIX COMPOSITES It metallic matrices. Processing – Solid state, liquid state, deposition, ace. Mechanical properties. Applications. IERAMIC MATRIX COMPOSITES materials – Processing – Hot pressing, liquid infiltration technique, reaction techniques – CVD, CVI, sol-gel process. Interface in C	insit Lar	tes – fibre u. Sio	Inject/poly	8 re /
moulding interface. UNIT I Types. In Titanium UNIT I Ceramic insitu ch propertie UNIT Unidirect – Fibre le curves –	n, resing, film Mechanical Mechanical Services W G tional later graph a Fatigu	transfer moulding, autoclave moulding – Thermoplastic matrix compatacking – Diaphragm forming – Thermoplastic tape laying. Glanical properties – Fracture. Applications. IETAL MATRIX COMPOSITES It metallic matrices. Processing – Solid state, liquid state, deposition, ace. Mechanical properties. Applications. IERAMIC MATRIX COMPOSITES materials – Processing – Hot pressing, liquid infiltration technique, reaction techniques – CVD, CVI, sol-gel process. Interface in C rmal shock resistance – Applications. IEOMETRICAL ASPECTS, FATIGUE AND CREEP IN	insit Lar MCs	u. Sides. Mo	Inject/poly/poly/poly/poly/poly/poly/poly/poly	8 cessnic
moulding interface. UNIT I Types. In Titanium UNIT I Ceramic insitu ch propertie UNIT UNIT Unidirect – Fibre le curves –	n, resing, film Mechanical Mechanical Services W G tional later graph a Fatigu	transfer moulding, autoclave moulding – Thermoplastic matrix compatacking – Diaphragm forming – Thermoplastic tape laying. Glanical properties – Fracture. Applications. IETAL MATRIX COMPOSITES It metallic matrices. Processing – Solid state, liquid state, deposition, ace. Mechanical properties. Applications. IERAMIC MATRIX COMPOSITES Interface in Compatible of the processing – Hot pressing, liquid infiltration technique, reaction techniques – CVD, CVI, sol-gel process. Interface in Compatible of the process	insit Lar Mane r ow.	u. Sidenxides. Mo	m fil	8 cessonic

OUTCO	MES:	On completion of this course, students will be able to
1.	Analyse t	the fibre reinforced Laminate for optimum design.
2.	Explore t	the concepts of Polymer Matrix Composites.
3.	Discuss d	different Metal Matrix Composites properties and manufacturing process.

4.	Understand	the different Ceramic Matrix Composites properties.										
5.	Apply Fatigue and creep theory to study and analyse the Mechanical behaviour of Composites.											
TEXT	BOOKS:											
1.	Krishnan K	Chawla, "Composite Materials Science and Engineering", Springer, 2001.										
2.		Mathews F L and Rawlings R D, "Composite Materials: Engineering and Science", CRC Press and Woodhead Publishing Limited, 2002.										
3.	Derek Hull,	Derek Hull, "An introduction to Composite Materials", Cambridge Univ. Press, 1988.										
REFER	RENCES:											
1.	"Handbook	of Composites" – American Society of Metals, 1990										
2.		., ''Principles of Composite Material Mechanics'', Second Edition, McGrawress in progress, 1994.										
3.	Autar K. Ka	w, "Mechanics of Composite Materials", Second Edition, CRC Press, 2006										
4.	Halpin, J.C. 1984.	, "Primer on Composite Materials, Analysis", Technomic Publishing Co.,										
5.		K. and Newman, S., "Composite Materials Technology: Processes and Hansen Publisher, Munish, 1990.										

MAPPING OF C	COs, P	Os Al	ND PS	SOs:												
	POs													PSOs		
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	3	2	2										3	2		
CO2	3	2	2										3	1		
CO3	3	2	2										3	2		
CO4	3	2	2										3	1		
CO5	3	3	1										3	2		
Average	3.0	2.2	1.8										3.0	1.6		
Round off	3	2	2										3	2		
3- Strong Correlation; 2 - Medium Correlation; 1 – Low Correlation																

18MC)E009	INDUSTRIAL REFRIGERATION AND AIR CONDITIONING	L	Т	P	C						
			3	0	0	3						
OBJE	CTIVE	S:										
•	To mak Operati	te the students to understand vapour compression and vapour a on.	bsorp	tion s	syste	m						
•	To anal	To analyse the refrigeration cycles and methods for improving Performance.										
•	To acqu	To acquire the knowledge on components of refrigeration systems.										
•	To desi	gn air conditioning systems using cooling load calculations.										
•	To exp	lore the application of refrigeration and air conditioning system	ıs.									
UNIT	I IN	TRODUCTION				9						
Refriger	ation an	Refrigeration and Air conditioning and its Practical appled C.O.P.— Ideal cycles- Refrigerants Desirable properties ODP & GWP.										
UNIT	II V	APOUR COMPRESSION REFRIGERATION SY	STE	M		9						
and sup-	er heatin perature	sion cycle: p-h and T-s diagrams - deviations from theoretical g- effects of condenser and evaporator pressure on COP- mul refrigeration - Cascade systems – problems. Equipments: Typansion devices, Evaporators.	ti pres	sure	syste	em -						
UNIT	III O'	THER REFRIGERATION SYSTEMS				9						
refrigera	ition- Ej	oles of Vapour absorption systems and adsorption cooling spector refrigeration systems. Thermoelectric refrigeration-x and Pulse tube refrigeration systems.	•									
UNIT	IV PS	SYCHOMETRIC PROPERTIES AND PROCESS	ES			9						
saturation Thermo	on, Rela dynamic	poist Air-Gibbs Dalton law, Specific humidity, Dew point tementive humidity, Enthalpy, Humid specific heat, Wet wet bulb temperature, Psychometric chart, Psychometric g of airstreams.	bulb	ten	pera	ıture						
UNIT	•	IR CONDITIONING SYSTEMS AND LOAD STIMATION			9							
Solar R selection	adiation- n-fresh a ion of s	g loads- Outside and inside design conditions- Heat transfer Electrical appliances- Infiltration and ventilation- internal hair load-Human comfort & IAQ principles- effective ten ummer &winter air conditioning load- Classifications- Lay	neat longerate	oad- <i>A</i> ure of pl	Appa & c ants-	ratu hart - Ai						

TOTAL: 45 PERIODS

OUT	COMES: On completion of this course, students will be able to									
1.	Analyse different refrigeration systems, air conditioning systems and refrigerants.									
2.	Understand the applications of refrigeration and air conditioning systems.									
3.	Learn the components and working of refrigeration and air conditioning systems									
4.	Evaluate different psychometric properties and processes.									
5.	Perform heating and cooling load calculations.									
TEX	Γ BOOKS:									
1.	Arora, C. P., "Refrigeration and Air Conditioning", 3 rd ed., McGraw Hill, Delhi, 2010.									
2.	Manohar Prasad., "Refrigeration and Air Conditioning", 2 nd ed., New Age Int., 2011.									
3.	Dick Wirz"Commercial Refrigeration for Air Conditioning Technicians" 3 rd ed., Cengage learning 2016.									
REFI	ERENCES:									
1.	Roy J. Dossat, "Principles of Refrigeration", 4 th edition, Pearson Education Asia, 2009.									
2.	Wilbert F Stoecker "Industrial Refrigeration" Handbook 1st Edition, McGraw Hill,1998.									
3.	Ahmadul Ameen., "Refrigeration and Air Conditioning", 1st edition, prentice-hall of India Private limited New Delhi 2006.									
4.	Jones W. P., "Air conditioning engineering", 5 th edition,Elsevier Butterworth-Heinemann, 2001.									
5.	Stoecker, W. F. and Jones J. W., "Refrigeration and Air Conditioning", McGraw Hill, New Delhi, 1986.									

MAPPING OF COs, POs AND PSOs:																	
	POs													PSOs			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3		
CO1	3	2											3	2	3		
CO2	3	2	3										3	2			
CO3	3	3											3	2			
CO4	3	2	2										3	3			
CO5	3	2	3		1	2							3	3			
Average	3.0	2.2	1.6		0.2	0.4							3.0	2.4	0.6		
Round off	3	2	2		0	0							3	2	1		
3- Strong C	orrel	ation;	2 - N	Iediu	m Coi	relat	ion; 1	- Lo	w Co	rrelati	ion						